



Technical Note

No. 336

**CALCULATION OF THE ADMITTANCE OF A
PARALLEL PLATE CAPACITOR CONTAINING
A TOROID-SHAPED SAMPLE**

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U. S. DEPARTMENT OF COMMERCE
NATIONAL BUREAU OF STANDARDS

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Calculation of the Admittance of a Parallel
Plate Capacitor Containing a Toroid-Shaped Sample

Eric G. Johnson, Jr.

The theoretical admittance of a toroid-shaped sample in a parallel plate capacitor system is developed. This calculation represents a first and second order perturbation correction to the usual quasistatic formula. The FORTTRAN listing of the machine program is included. The analysis is done under the condition that the sample is not in contact with the capacitor plates and can be described by a complex permeability, μ_M , and complex permittivity, ϵ_M .

Key Words:

Fortran
Lossy materials
Parallel plate capacitor
Permeability
Permittivity
Theoretical admittance

1. Introduction

The purpose of this calculation is to permit an accurate determination of the permittivity and permeability of a material sample for the frequency range in which the capacitor and inductor system are generally applicable.* This particular calculation considers

*This technical note is a companion to the NBS Technical Note #311, "Computation of the Permeability and Permittivity of a Relatively Small Ring Sample in a Toroidal Coil," which contains a similar analysis for the inductor structure of a toroid-shaped sample. Both the capacitor and inductor measurements are necessary if one is to get a complete determination of the permeability and permittivity of a sample.

the parallel plate capacitor system in which there has been placed a toroidal-shaped sample. Our purpose is to correct the usual quasi-static formulae (zero order solution) for characterizing a capacitor to at least second order in perturbation theory. The zero and first order calculation is performed under the assumption that there is no height dependence of the electromagnetic field. Only radial dependence is permitted. However, because we wish to be able to study lossy materials (complex μ_M and ϵ_M) we have chosen the geometry of the experiment to be such that the sample is not in contact with either of the metal plates of the capacitor system. Because of this configuration, it is necessary to make a guess of an effective permeability $\bar{\mu}$ and permittivity $\bar{\epsilon}$ for the zero and first order solution to the problem. The second order term primarily attempts to correct for the fact that there is indeed height dependence for the electromagnetic field. This second order is derived under a relaxation of the requirement that tangential component of the magnetic field is continuous. It is expected that when this second order term is important there is the corresponding circumstance that the sample tends to not have an internal electromagnetic field, i. e., it is as though there is a surface current acting on the sample surface. So to aid in the convergence of the second order term and hopefully to make it a more reliable estimate of the corrections necessary to the zero and first order term, this calculation errs in the direction of assuming that there is a surface current in the second order term.

2. Initialization of the Problem

Assume an experimental system with the following boundary conditions:

1. We have two finite radius parallel plates. Each plate has infinite conductivity.

2. A rectangular cross-sectioned toroid is placed between the plates.
3. Two complex frequency dependent parameters--permeability, μ_M , and permittivity, ϵ_M -- are used to characterize the material in the toroid.
4. The excitation mechanism of the capacitor system is such that no angular field dependence exists and is such the H_ϕ is the only magnetic variable. This means that the basic electromagnetic field equations namely (1) will be reduced to a single equation, (2) below. Equation (1) assumes the $\exp(i\omega t)$ time dependence. Thus,

$$\nabla \times \underline{E} = -i\omega \mu \underline{H}, \text{ and}$$

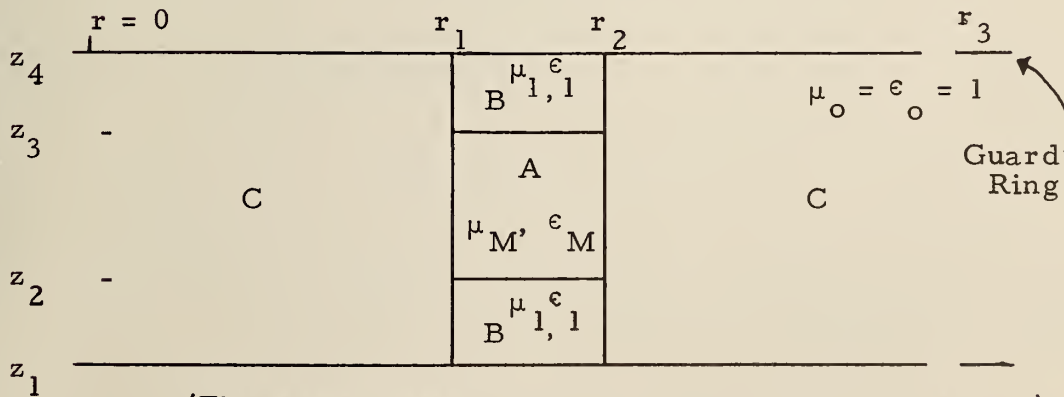
$$\nabla \times \underline{H} = i\omega \epsilon \underline{E} \tag{1}$$

$$i = \sqrt{-1}$$

(natural units are used, namely, $c = 1$. Hence all units are powers of cm. The ω is cm^{-1} ; μ, ϵ are dimensionless).

5. The coordinates of interest are shown in Figures 1 and 2.

SIDE VIEW



(The system is symmetric around the $r = 0$ position.)

Figure 1

TOP VIEW OF SYSTEM

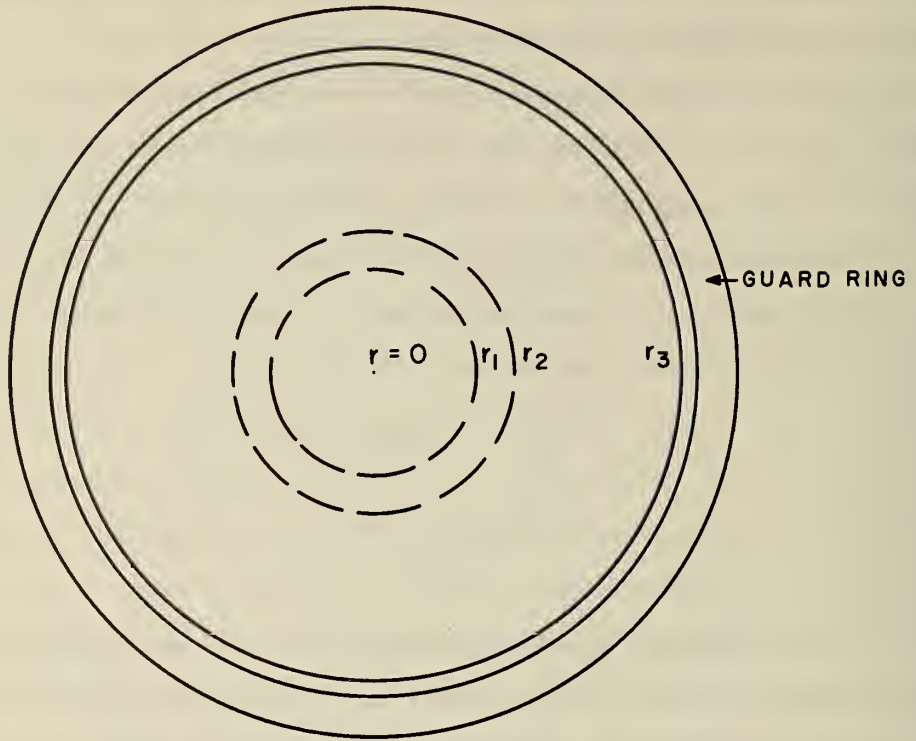


Figure 2

The r_1 and r_2 are the radial coordinates of the toroid sample A.

The r_3 is the radius at which the system has its voltage drop prescribed.

The z_2 and z_3 are the z axis coordinates of the toroid sample A.

The z_4 , z_3 and z_1 , z_2 are the z axis coordinates of two toroid-shaped material B. They have no loss in their ϵ_1 and μ_1 . The relative

size of $\frac{z_2 - z_1}{z_3 - z_2}$ and $\frac{z_4 - z_3}{z_3 - z_2}$ is about 2.5%. The structure is

used to provide a precise measure of the distances $z_4 - z_3$ and

$z_2 - z_1$. We characterize the permeability and permittivity of the

space $r_3 \geq r \geq 0$ and $z_1 \leq z \leq z_4$ by:

$$\mu = 1 \quad \text{and} \quad \epsilon = 1, \quad \text{for region C;}$$

$$\mu = \mu_1 \quad \text{and} \quad \epsilon = \epsilon_1, \quad \text{for region B;}$$

$$\text{and } \mu = \mu_M \quad \text{and} \quad \epsilon = \epsilon_M, \quad \text{for region A.}$$

The regions A, B, and C are indicated in Figure 1. A functional form

for μ is
$$\mu = P(r) \left[P(z) (\mu_M - \mu_1) + \mu_1 - 1 \right] + 1.$$

The same form for ϵ is possible. Here we have defined

$$P(r) = \theta(r - r_1) - \theta(r - r_2)$$

and

$$P(z) = \theta(z - z_3) - \theta(z - z_2),$$

where θ is the step function.

3. Analysis

Upon reducing the (1) with assumptions 1 to 5 and setting $f \equiv rH_{\phi}$ the following differential equation results:

$$r \frac{\partial}{\partial r} \frac{1}{r\epsilon} \frac{\partial}{\partial r} f + \frac{\partial}{\partial z} \frac{1}{\epsilon} \frac{\partial}{\partial z} f + \omega^2 \mu f = 0 \quad (2)$$

The boundary conditions are $\frac{\partial}{\partial z} f = 0$ at $z = z_1, z_4$; and $\frac{f}{r} \rightarrow 0$ as $r \rightarrow 0$. The admittance, Y , of this system at $r = r_3$ is defined as the ratio of the peak current to peak driving voltage. Thus,

$$Y = 2\pi i \omega f(r_3) / \left[\int_z^{z_4} \frac{1}{r} \frac{\partial}{\partial r} f dz \right]_{r=r_3} = \frac{2\pi i \omega r_3}{z_4 - z_1} \left[f(r_3) / \left(\frac{\partial}{\partial r} f \right) (r_3) \right] \quad (3)$$

The position r_3 is chosen so that the influence of the toroid sample on the field structure has no resulting z dependence. That is, r_3 is sufficiently far from the sample so that the only type of field that exists at r_3 is pure propagating waves with no z dependence $\left(r_3 > r_2 + 4(z_4 - z_1) \right)$. By fixing the voltage drop point at r_3 we solve a basic problem for making the admittance of a parallel plate capacitor unique. Thus the voltage drop at r_3 is given by the line integral

$$\frac{1}{i\omega} \int_{z_1}^{z_4} \frac{1}{\epsilon r} \frac{\partial}{\partial r} f dz \Big|_{r=r_3}$$

This means we have chosen a path at $r = r_3$ that is only along the z direction. With this specification and noting that the admittance contribution outside $r = r_3$ is the same with or without the sample, we can subtract the two admittance measurements and equate the result to the corresponding subtraction of the two theoretical admittances.

In order to eliminate mathematical consideration of fringing fields, we assume that the capacitor is infinite. We then arbitrarily choose r_3 as the point where we define the interior of the capacitor system. We must experimentally fix r_3 and still be able to neglect the effects of fringing fields. Practically, this is accomplished by having a capacitor of radius r_3 and by using a guard ring. We now solve the equation for f . A first order guess to f is to assume that the sample completely fills both regions A and B with the weighted average parameters $\bar{\epsilon}$, $\bar{\mu}$, as is defined below. We can solve this f_0 exactly. We next assume that f may be written as $f = f_0 + \epsilon(r, z) g(r, z)$, where g is assumed to be a perturbation connection to the f_0 solution. By allowing this transformation and making g and its derivative continuous we are granting the existence of surface current on the material sample.

We thus have the following equation for g

$$\pi \partial_n \frac{1}{\bar{\epsilon}} \partial_n g + \partial_z^2 g + \omega^2 \bar{\mu} \epsilon g = H \equiv \omega^2 (\bar{\mu} - \mu) f_0 + \pi \partial_n \frac{1}{\bar{\epsilon}} \left(\frac{1}{\bar{\epsilon}} - \frac{1}{\epsilon} \right) \partial_n f_0, \quad (4)$$

where f_0 obeys the equation

$$\pi \partial_n \frac{1}{\bar{\epsilon}} \partial_n f_0 + \omega^2 \bar{\mu} f_0 = 0. \quad (5)$$

Here, $\bar{\epsilon} = P(\pi) (\epsilon_2 - 1) + 1$, $\bar{\mu} = P(\pi) (\mu_2 - 1) + 1$,

where $\epsilon_2 = \epsilon_1 / \left(1 + (\epsilon_1 / \epsilon_M - 1) \left(\frac{z_3 - z_2}{z_4 - z_1} \right) \right)$

and $\mu_2 = \mu_1 + (\mu_M - \mu_1) \left(\frac{z_3 - z_2}{z_4 - z_1} \right)$.

The solution to (5) is

$$f_0 = \pi \left[A I_1(i\omega \pi \sqrt{\bar{\mu} \bar{\epsilon}}) + B K_1(i\omega \sqrt{\bar{\mu} \bar{\epsilon}} \pi) \right] \text{ for each region.}$$

Thus,

$$\begin{aligned} f_0 &= \pi I_1(i\omega \pi) & \pi \leq \pi_1 \\ f_0 &= \pi \left[\bar{A} I_1(i\omega \sqrt{\mu_2 \epsilon_2} \pi) + \bar{B} K_1(i\omega \sqrt{\mu_2 \epsilon_2} \pi) \right], & \pi_1 \leq \pi \leq \pi_2 \\ f_0 &= \pi \left[A I_1(i\omega \pi) + B K_1(i\omega \pi) \right], & \pi_2 \leq \pi \leq \pi_3 \end{aligned} \quad (6)$$

We require f_0 and $\frac{1}{\epsilon} \partial_r f_0$ to be continuous across the r_1 and r_2 boundary.

This implies with definitions $x_{1,2} = i\omega r_{1,2}$ and $\bar{x}_{1,2} = i\omega r_{1,2} \sqrt{\mu_2 \epsilon_2}$

that
$$\begin{aligned} \bar{I}_1(x_1) &= \bar{A} I_1(\bar{x}_1) + \bar{B} K_1(\bar{x}_1) \\ I_0(x_1) &= \sqrt{\frac{\mu_2}{\epsilon_2}} \left[\bar{A} I_0(\bar{x}_1) - \bar{B} K_0(\bar{x}_1) \right], \end{aligned}$$

and that

$$\begin{aligned} C_1 &\equiv \bar{A} I_1(\bar{x}_2) + \bar{B} K_1(\bar{x}_2) = A I_1(x_2) + B K_1(x_2) \\ C_2 &\equiv \sqrt{\frac{\mu_2}{\epsilon_2}} \left[\bar{A} I_0(\bar{x}_2) - \bar{B} K_0(\bar{x}_2) \right] = A I_0(x_2) - B K_0(x_2). \end{aligned}$$

We solve for A, B as follows:

$$\begin{pmatrix} A \\ B \end{pmatrix} = \begin{pmatrix} K_0(x_2) & K_1(x_2) \\ I_0(x_2) & -I_1(x_2) \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} / D_1, \quad (7)$$

where $D_1 = (I_1(x_2) K_0(x_2) + K_1(x_2) I_0(x_2))$.

The \bar{A} , \bar{B} is given by

$$\begin{pmatrix} \bar{A} \\ \bar{B} \end{pmatrix} = \begin{pmatrix} K_0(\bar{x}_1) & K_1(\bar{x}_1) \\ I_0(\bar{x}_1) & -I_1(\bar{x}_1) \end{pmatrix} \begin{pmatrix} I_1(x_1) \\ \sqrt{\frac{\epsilon_2}{\mu_2}} I_0(x_1) \end{pmatrix} / D_2, \quad (8)$$

where

$$D_2 = (I_1(\bar{x}_1) K_0(\bar{x}_1) + K_1(\bar{x}_1) I_0(\bar{x}_1)).$$

The Wronskian is

$$\begin{aligned} W &= I_0(z) K_0(z) - I_0(z) K_0(z)' = I_1(z) K_0(z) + I_0(z) K_1(z) \\ &= \frac{1}{z} \quad \text{for all } z \text{ including } z \rightarrow 0. \end{aligned} \quad (9)$$

Thus we can write $D_1 = \frac{1}{x_2}$ and $D_2 = \frac{1}{\bar{x}_1}$. (10)

Next we reduce the inhomogeneous term as follows:

$$\begin{aligned} H &= \omega^2 (\bar{\mu} - \mu) f_0 + (1 - \frac{\bar{\epsilon}}{\epsilon}) (-\bar{\mu} \omega^2 f_0) + \frac{1}{\epsilon} \alpha_n(f_0) \alpha_n (1 - \frac{\bar{\epsilon}}{\epsilon}) \\ &= \omega^2 f_0 \left[-\mu + \frac{\bar{\epsilon} \bar{\mu}}{\epsilon} \right] + \frac{1}{\epsilon} \alpha_n(f_0) \alpha_n (1 - \frac{\bar{\epsilon}}{\epsilon}). \end{aligned} \quad (11)$$

Equation (4) can be solved in terms of the expansion

$$g = \sum_{n=0}^{\infty} N_n \cos k_n (z - z_1) R_n(n),$$

where

$$k_n = \frac{n\pi}{z_4 - z_1} \quad \text{and} \quad N_n = \sqrt{\frac{2 - \delta_{n0}}{z_4 - z_1}}.$$

The equations to fix $R_n(r)$ are now given as

$$\left[n \frac{\partial}{\partial n} \frac{\partial}{\partial n} - k_n^2 + \omega^2 \right] R_n + \omega^2 \sum_{n'=0}^{\infty} A_{nn'} R_{n'} P(n) = \begin{aligned} & - f_0(n) B_n P(n) \\ & - D_n^a \delta(n - n_1) \\ & - D_n^b \delta(n - n_2) \end{aligned} \quad (12)$$

Here, $A_{nn'}$, D_n^a , B_n , D_n^b are defined:

$$A_{nn'} = N_n N_{n'} (\mu_m \epsilon_m - \mu_1 \epsilon_1) \int_{z_2}^{z_3} \cos k_n (z - z_1) \cos k_{n'} (z - z_1) dz + (\mu_1 \epsilon_1 - 1) \delta_{nn'} \quad (13)$$

$$B_n = \omega^2 \left[\left\{ (\mu_m - \mu_1) - \epsilon_2 \mu_2 \left(\frac{1}{\epsilon_m} - \frac{1}{\epsilon_1} \right) \right\} \frac{N_n}{k_n} \sin k_n (z - z_1) \right]_{z_2}^{z_3} + \frac{\delta_{n0}}{N_0} \left[\mu_1 - \frac{\epsilon_2 \mu_2}{\epsilon_1} \right] \quad (14)$$

$$D_n^a = \frac{1}{\epsilon} \frac{\partial}{\partial n} f_0 \Big|_{n=n_1} E_n \quad D_n^b = -\frac{1}{\epsilon} \frac{\partial}{\partial n} f_0 \Big|_{n=n_2} E_n, \quad \text{where}$$

$$E_n \equiv N_n \left[\epsilon_2 \left(\frac{1}{\epsilon_m} - \frac{1}{\epsilon_1} \right) \frac{\sin k_n (z - z_1)}{k_n} \right]_{z_2}^{z_3} + \left(\frac{\epsilon_2}{\epsilon_1} - 1 \right) \frac{\delta_{n0}}{N_0}.$$

Here $\delta_{n0} = 0$ $n \neq 0$, and

$$\delta_{n0} = 1 \quad n = 0.$$

We further compute $A_{nn'}$ to get

$$A_{nn'} = \frac{N_n N_{n'}}{2} (\mu_m \epsilon_m - \mu_1 \epsilon_1) \left[\frac{\sin(k_n - k_{n'}) (z - z_1)}{k_n - k_{n'}} + \frac{\sin(k_n + k_{n'}) (z - z_1)}{k_n + k_{n'}} \right]_{z_2}^{z_3} \quad (15)$$

when $n \neq n'$.

When $n = n'$, we have

$$A_{nn} = \left(1 - \frac{1}{2} \delta_{n0} \right) \left[z + \frac{\sin 2k_n (z - z_1)}{2k_n} \right]_{z_2}^{z_3} (\mu_m \epsilon_m - \mu_1 \epsilon_1) + \mu_1 \epsilon_1 - 1. \quad (16)$$

Thus we now define: $\lambda_n^2 \equiv \kappa_n^2 - \omega^2$, $\lambda_n \equiv +\sqrt{\lambda_n^2}$,
 $\bar{\lambda}_n^2 \equiv \lambda_n^2 - \omega^2 A_{nn}$, $\bar{\lambda}_n \equiv +\sqrt{\bar{\lambda}_n^2}$, (17)

$\lambda_n^2(n) \equiv (\bar{\lambda}_n^2 - \lambda_n^2) P(n) + \lambda_n^2$ and the Green's function equations

$[n \frac{\partial}{\partial n} \frac{1}{n} \frac{\partial}{\partial n} - \lambda_n^2(n)] G_n(n, \bar{n}) = -\delta(n - \bar{n})$, (18)

$G_n(n, \bar{n}) [\bar{n} \frac{\partial}{\partial \bar{n}} \frac{1}{\bar{n}} \frac{\partial}{\partial \bar{n}} - \lambda_n^2(\bar{n})] = -\delta(n - \bar{n})$. (19)

The solution to these equations is given as

$G_n(n, \bar{n}) = n C_n(\bar{n}) T_n(n)$, $\bar{n} > n$,
 $\equiv n C_n(n) T_n(\bar{n})$, $\bar{n} < n$.

The normalization condition on T_n given by

$n [C_n' T_n - T_n' C_n] = -1 \equiv nW$,

or since the term in the bracket is the Wronskian, W , and its solution is

$W' = -\frac{1}{n} W$ or $W = \frac{C}{n}$, we have the requirement that $C = -1$.

To find W , we fix $T_n(r)$ and $C_n(r)$ as follows:

$C_n(n) = C_n^a I_1(\lambda_n n) + C_n^b K_1(\lambda_n n)$, $0 \leq n \leq n_1$,
 $C_n(n) = \bar{C}_n^a I_1(\lambda_n n) + \bar{C}_n^b K_1(\lambda_n n)$, $n_1 \leq n \leq n_2$,
 $C_n(n) = K_1(\lambda_n n)$, $n_2 \leq n$,
 $T_n(n) = I_1(\lambda_n n) / C_n^b$, $0 \leq n \leq n_1$,
 $T_n(n) = \bar{S}_n^a I_1(\lambda_n n) + \bar{S}_n^b K_1(\lambda_n n)$, $n_1 \leq n \leq n_2$,
 $T_n(n) = S_n^a I_1(\lambda_n n) + S_n^b K_1(\lambda_n n)$, $n_2 \leq n$. (20)

To check if $rW = -1$, we consider the case $r \rightarrow 0$. We have

$\lambda_n [(C_n^a I_0 - C_n^b k_0) \frac{1}{C_n^b} I_1 - \frac{1}{C_n^b} I_0 (C_n^a I_1 + C_n^b k_1)] \xrightarrow{n \rightarrow 0} -\frac{1}{n}$, (21)

hence $rW = -1$ as desired.

The conditions for connection of the three regions are that T_n , C_n , and their derivatives must be continuous across the r_1 , r_2 boundaries. As a consequence, we have the following equations:

$$\begin{aligned}
 C_n^a I_1(\lambda_n n_1) + C_n^b K_1(\lambda_n n_1) &= \bar{C}_n^a I_1(\bar{\lambda}_n n_1) + \bar{C}_n^b K_1(\bar{\lambda}_n n_1) \\
 \bar{C}_n^a I_1(\bar{\lambda}_n n_2) + \bar{C}_n^b K_1(\bar{\lambda}_n n_2) &= K_1(\lambda_n n_2) \\
 C_n^a I_0(\lambda_n n_1) - C_n^b K_0(\lambda_n n_1) &= \frac{\bar{\lambda}_n}{\lambda_n} \left[\bar{C}_n^a I_0(\bar{\lambda}_n n_1) - \bar{C}_n^b K_0(\bar{\lambda}_n n_1) \right] \quad (22) \\
 \bar{C}_n^a I_0(\bar{\lambda}_n n_2) - \bar{C}_n^b K_0(\bar{\lambda}_n n_2) &= -\frac{\lambda_n}{\bar{\lambda}_n} K_0(\lambda_n n_2) \\
 S_n^a I_1(\lambda_n n_2) + S_n^b K_1(\lambda_n n_2) &= \bar{S}_n^a I_1(\bar{\lambda}_n n_2) + \bar{S}_n^b K_1(\bar{\lambda}_n n_2) \\
 S_n^a I_0(\lambda_n n_2) - S_n^b K_0(\lambda_n n_2) &= \frac{\bar{\lambda}_n}{\lambda_n} \left[\bar{S}_n^a I_0(\bar{\lambda}_n n_2) - \bar{S}_n^b K_0(\bar{\lambda}_n n_2) \right] \\
 \bar{S}_n^a I_1(\bar{\lambda}_n n_1) - \bar{S}_n^b K_1(\bar{\lambda}_n n_1) &= I_1(\lambda_n n_1) / C_n^b \\
 \bar{S}_n^a I_0(\bar{\lambda}_n n_1) - \bar{S}_n^b K_0(\bar{\lambda}_n n_1) &= \frac{\lambda_n}{\bar{\lambda}_n} I_0(\lambda_n n_1) / C_n^b.
 \end{aligned}$$

Upon solving these equations, we find that:

$$\begin{pmatrix} \bar{C}_n^a \\ \bar{C}_n^b \end{pmatrix} = \begin{pmatrix} K_0(\bar{\lambda}_n n_2) & K_1(\bar{\lambda}_n n_2) \\ I_0(\bar{\lambda}_n n_2) & -I_1(\bar{\lambda}_n n_2) \end{pmatrix} \begin{pmatrix} K_1(\lambda_n n_2) \\ -\frac{\lambda_n}{\bar{\lambda}_n} K_0(\lambda_n n_2) \end{pmatrix} / D_1 \quad ,$$

$$\begin{aligned}
 D_1 &= I_1(\bar{\lambda}_n n_2) K_0(\bar{\lambda}_n n_2) + K_1(\bar{\lambda}_n n_2) I_0(\lambda_n n_2) = \frac{1}{\lambda} [I_0' K_0 - K_0' I_0] \\
 &= \frac{1}{n_2 \bar{\lambda}_n} \quad)
 \end{aligned}$$

[See (10) for this reduction.]

$$\begin{pmatrix} \bar{S}_n^a \\ \bar{S}_n^b \end{pmatrix} = \begin{pmatrix} K_0(\bar{\lambda}_n n_1) & K_1(\bar{\lambda}_n n_1) \\ I_0(\bar{\lambda}_n n_1) & -I_1(\bar{\lambda}_n n_1) \end{pmatrix} \begin{pmatrix} I_1(\lambda_n n_1) \\ \frac{\lambda_n}{\bar{\lambda}_n} I_0(\lambda_n n_1) \end{pmatrix} \left(\frac{n_1 \bar{\lambda}_n}{C_n^b} \right) \quad ,$$

$$\begin{pmatrix} C_n^a \\ C_n^b \end{pmatrix} = \begin{pmatrix} \kappa_o(\lambda_n n_1) & \kappa_i(\lambda_n n_1) \\ I_o(\lambda_n n_1) & -I_i(\lambda_n n_1) \end{pmatrix} \begin{pmatrix} \bar{C}_n^a I_i(\bar{\lambda}_n n_1) + \bar{C}_n^b \kappa_i(\bar{\lambda}_n n_1) \\ \frac{\bar{\lambda}_n}{\lambda_n} [\bar{C}_n^a I_o(\bar{\lambda}_n n_1) - \bar{C}_n^b \kappa_o(\bar{\lambda}_n n_1)] \end{pmatrix} / D_2$$

$$D_2 = \kappa_o I_i + I_o \kappa_i = \frac{1}{\lambda_n} [\kappa_o I_o' - I_o \kappa_o'] = \frac{1}{\lambda_n n_1} \quad \text{and finally,}$$

$$\begin{pmatrix} S_n^a \\ S_n^b \end{pmatrix} = \begin{pmatrix} \kappa_o(\lambda_n n_2) & \kappa_i(\lambda_n n_2) \\ I_o(\lambda_n n_2) & -I_i(\lambda_n n_2) \end{pmatrix} \begin{pmatrix} \bar{S}_n^a I_i(\bar{\lambda}_n n_2) + \bar{S}_n^b \kappa_i(\bar{\lambda}_n n_2) \\ \frac{\bar{\lambda}_n}{\lambda_n} [\bar{S}_n^a I_o(\bar{\lambda}_n n_2) - \bar{S}_n^b \kappa_o(\bar{\lambda}_n n_2)] \end{pmatrix} (\lambda_n n_2).$$

We next construct the integral equation for R_n . That is

$$\begin{aligned} R_n &= \int G_n(n, \bar{n}) f_o(\bar{n}) d\bar{n} B_n - G_n(n, n_1) D_n^a - G_n(n, n_2) D_n^b \\ &= \omega^2 \sum_{n' \neq n} \int_{n_1}^{n_2} G_n(n, \bar{n}) d\bar{n} R_{n'}(\bar{n}) A_{nn'} \\ &\quad + [G_n \overset{\rightarrow}{\partial}_{\bar{n}} R_n - G_n \bar{n} \overset{\leftarrow}{\partial}_{\bar{n}} \frac{1}{\bar{n}} R_n]_{\bar{n} = n_3}. \end{aligned} \quad (23)$$

Now we assume R_n has only outgoing waves; therefore, we have the following integral equation:

$$\begin{aligned} R_n(n) &= \int_{n_1}^{n_2} G_n(n, \bar{n}) f_o(\bar{n}) d\bar{n} B_n + D_n^a G_n(n, n_1) + D_n^b G_n(n, n_2) \\ &\quad + \omega^2 \sum_{n' \neq n} A_{nn'} \int_{n_1}^{n_2} G_n(n, \bar{n}) R_{n'}(\bar{n}) d\bar{n}. \end{aligned} \quad (24)$$

The solution of this integral equation by standard iteration is for $n \neq 0$:

$$R_n(n) = \int_{n_1}^{n_2} G_n(n, \bar{n}) f_o(\bar{n}) d\bar{n} B_n + D_n^a G_n(n, n_1) + D_n^b G_n(n, n_2); \quad (25)$$

and for $n = 0$:

$$\begin{aligned} R_0(n) &= \int_{n_1}^{n_2} G_0(n, \bar{n}) f_o(\bar{n}) d\bar{n} B_0 + D_0^a G_0(n, n_1) + D_0^b G_0(n, n_2) \\ &\quad + \omega^2 \sum_{n' > 0} A_{0n'} \int_{n_1}^{n_2} G_0(n, \bar{n}) R_{n'}(\bar{n}) d\bar{n}. \end{aligned}$$

The final form for f , at $r = r_3$, is

$$f = f_o + R_0 = B^a [B^b \kappa_i(i\omega n_3) + I_i(i\omega n_3)] n_3. \quad (26)$$

The admittance is given with $r = r_3$ as follows:

$$Y = \frac{2\pi n_3}{z_4 - z_1} \left[\frac{B^b k_1(i\omega n_3) + I_1(i\omega n_3)}{-B^b k_0(i\omega n_3) + I_0(i\omega n_3)} \right]. \quad (27)$$

The basic computational problem is to determine B^b and B^a . We make the expansion of the f_0 and R_0 function explicit so that we can determine B^b :

$$f_0 = \pi [A I_1 + B K_1], \quad n > n_2, \quad (28)$$

$$R_n(n) = \pi C_n(n) \left\{ \int_{n_1}^n T_n(\bar{n}) \bar{n} (\bar{A} I_1(\bar{x}) + \bar{B} K_1(\bar{x})) B_n d\bar{n} \right. \\ \left. + D_n^a T_n(n_1) \right. \quad (29)$$

$$\left. + \pi T_n(n) \left\{ \int_n^{n_2} C_n(\bar{n}) \bar{n} (\bar{A} I_1(\bar{x}) + \bar{B} K_1(\bar{x})) B_n d\bar{n} \right. \right. \\ \left. \left. + D_n^b C_n(n_2), \right. \right.$$

$$R_0(n_3) = \pi_3 C_0(n_3) \left\{ B_0 \int_{n_1}^{n_2} T_0(\bar{n}) \bar{n} f_0(\bar{n}) d\bar{n} \right\} \\ \left\{ + D_0^a T_0(n_1) + D_0^b T_0(n_2) \right\} \quad (30)$$

$$+ \omega^2 \sum_{n' > 0} A_{0n'} \pi_3 C_0(n_3) \int_{n_1}^{n_2} T_0(\bar{n}) R_{n'}(\bar{n}) d\bar{n}$$

Here $\bar{x} = \bar{n} r$, $n \neq 0$, and $\bar{\lambda} = i\omega \sqrt{\mu_2 \epsilon_2}$.

Thus we define

$$R_0 = \pi_3 k_1(i\omega n_3) [H^{(1)} + \omega^2 H^{(2)}] \quad \text{and note that } B^b \text{ is now}$$

$$B^b = (B + H^{(1)} + \omega^2 H^{(2)}) / A.$$

The $H^{(1)}$, $H^{(2)}$ are defined as follows:

$$H^{(1)} = B_0 \int_{n_1}^{n_2} T_0(\bar{n}) d\bar{n} f_0(\bar{n}) \bar{n} \\ + D_0^a T_0(n_1) + D_0^b T_0(n_2), \quad (31)$$

$$H^{(2)} = \sum_{n>0} A_{0n} \int_{n_1}^{n_2} T_0(\bar{n}) R_n(\bar{n}) d\bar{n}. \quad (32)$$

We define:

$$\begin{aligned} P_1^n(n) &\equiv \int_{n_1}^n I_1(\bar{x}_n) I_1(\bar{x}) n d n, & (\bar{x}_n \equiv \bar{\lambda}_n n), \\ P_2^n(n) &\equiv \int_{n_1}^n I_1(\bar{x}_n) K_1(\bar{x}) n d n, \\ P_3^n(n) &\equiv \int_{n_1}^n K_1(\bar{x}_n) I_1(\bar{x}) n d n, \\ P_4^n(n) &\equiv \int_{n_1}^n K_1(\bar{x}_n) K_1(\bar{x}) n d n. \end{aligned} \quad (33)$$

The integrals are:

$$\begin{aligned} P_1^n(n) &= \left[n (I_1(\bar{x}_n) I_0(\bar{x}) \bar{\lambda} - \bar{\lambda}_n I_0(\bar{x}_n) I_1(\bar{x})) \right]_{n_1}^n / z_n, \\ P_2^n(n) &= \left[-n (I_1(\bar{x}_n) K_0(\bar{x}) \bar{\lambda} + \bar{\lambda}_n I_0(\bar{x}_n) K_1(\bar{x})) \right]_{n_1}^n / z_n, \\ P_3^n(n) &= \left[n (K_1(\bar{x}_n) I_0(\bar{x}) \bar{\lambda} + \bar{\lambda}_n K_0(\bar{x}_n) I_1(\bar{x})) \right]_{n_1}^n / z_n, \\ P_4^n(n) &= \left[-n (K_1(\bar{x}_n) K_0(\bar{x}) \bar{\lambda} - \bar{\lambda}_n K_0(\bar{x}_n) K_1(\bar{x})) \right]_{n_1}^n / z_n. \end{aligned} \quad (34)$$

$$(z_n \equiv \bar{\lambda}_n^2 - \bar{\lambda}^2).$$

We have defined:

$$\begin{aligned} H_n^{(5)}(n) &\equiv \bar{A} P_1^n(n) + \bar{B} P_2^n(n), \\ H_n^{(6)}(n) &\equiv \bar{A} P_3^n(n) + \bar{B} P_4^n(n), \\ H_n^{(3)}(n) &\equiv D_n^a T_n(n_1) + \bar{B}_n (\bar{S}_n^a H_n^{(5)}(n) + \bar{S}_n^b H_n^{(6)}(n)), \\ H_n^{(4)}(n) &\equiv D_n^b C_n(n_2) + \bar{B}_n \left\{ \bar{C}_n^a (H_n^{(5)}(n_2) - H_n^{(5)}(n)) + \right. \\ &\quad \left. \bar{C}_n^b (H_n^{(6)}(n_2) - H_n^{(6)}(n)) \right\}, \end{aligned} \quad (35)$$

$$\begin{aligned} R_n(n) &\equiv n [C_n(n) H_n^{(3)}(n) + T_n(n) H_n^{(4)}(n)], \\ H_n^{(2)} &\equiv \int_{n_1}^{n_2} T_0(n) R_n(n) d n, \end{aligned} \quad (36)$$

hence,

$$H^{(2)} = \sum_{n>0} A_{0n} H_n^{(2)}. \quad (37)$$

Now, in addition we have:

$$H^{(1)} \equiv \bar{B}_0 H^{(7)} + \bar{D}_0^a T_0(n_1) + \bar{D}_0^b T_0(n_2) \quad (38)$$

$$H^{(7)} \equiv \bar{S}_0^a H_0^{(5)}(n_2) + \bar{S}_0^b H_0^{(6)}(n_2). \quad (39)$$

4. Discussion

The analysis has gone as far as possible without numerical integration of (36). We summarize the basic necessary results in Appendix A. In Appendix B we have a FORTRAN 63 listing of the machine program. In Appendix C is a sample calculation. (Here $\mu_M = UM + IUM^*$ and $\epsilon_M = EM + IEM^*$ in the computer program. UM , EM are the real parts and UM^* , EM^* are the imaginary parts. They must be negative to describe a lossy system. Appendix D gives a flow chart of the input data necessary to run the machine program.

The quasistatic formula used is
$$Y_{qs} = i\omega\pi \frac{(r_2^2 - r_1^2)}{z_4 - z_1} \epsilon_2$$

The computation has explicitly separated out the highest order correction, $H^{(2)}$, for the determination of the admittance of the sample. This correction can be used to get an estimate of the accuracy of the admittance calculation. This correction is calculated by Simpson intervals to an accuracy of about 3%. Thus if this $H^{(2)}$ term is less than 10%, and subject to discussion of the introduction we can conclude that the admittance is known to at least 0.5%. In addition, one has an option of varying r_3 by 10%. Under this option one can get an estimate of how sensitive the experimental system is to the inexact knowledge of r_3 . As a consequence we have a simple measure of the degree the radiation part of the electromagnetic field is present.

The program prints out the results in mho's for the admittance.

5. Acknowledgements

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APPENDIX A

SUMMARY OF FORMULAE USED IN MACHINE PROGRAM

$$\begin{pmatrix} A \\ B \end{pmatrix} = x_2 \begin{pmatrix} K_1(x_2) & K_0(x_2) \\ -I_1(x_2) & I_0(x_2) \end{pmatrix} \begin{pmatrix} \sqrt{\frac{\mu_2}{\epsilon_2}} (\bar{A} I_0(\bar{x}_2) - \bar{B} K_0(\bar{x}_2)) \\ \bar{A} I_1(\bar{x}_2) + \bar{B} K_1(\bar{x}_2) \end{pmatrix} \quad (A1)$$

$$\begin{pmatrix} \bar{A} \\ \bar{B} \end{pmatrix} = \bar{x}_1 \begin{pmatrix} K_0(\bar{x}_1) & K_1(\bar{x}_1) \\ I_0(\bar{x}_1) & -I_1(\bar{x}_1) \end{pmatrix} \begin{pmatrix} I_1(x_1) \\ \sqrt{\frac{\epsilon_2}{\mu_2}} I_0(x_1) \end{pmatrix} \quad (A2)$$

$$f_0 = \bar{A} I_1(\bar{x}) + \bar{B} K_1(\bar{x}) \quad \bar{x} \equiv i\omega\sqrt{\mu_2}\epsilon_2 z \quad n_1 \leq n \leq n_2 \quad (A3)$$

$$A_{0n} = (\mu_n \epsilon_n - \mu_1 \epsilon_1) \sqrt{2} \frac{\sin k_n(z - z_1)}{z_4 - z_1} \Big|_{z_2}^{z_3} \quad (A4)$$

$$A_{nn} = \mu_1 \epsilon_1 - 1 + (\mu_n \epsilon_n - \mu_1 \epsilon_1) \left(\frac{1 - \frac{1}{2} \delta_{n0}}{z_4 - z_1} \right) \left(z + \frac{\sin 2k_n(z - z_1)}{2k_n} \right) \Big|_{z_2}^{z_3} \quad (A5)$$

$$D_n^a = n_1 i\omega I_0(i\omega n_1) E_n \quad (A6)$$

$$D_n^b = -n_2 i\omega [A I_0(i\omega n_2) - B K_0(i\omega n_2)] E_n \quad (A7)$$

$$E_n = \left[\epsilon_2 \left(\frac{1}{\epsilon_n} - \frac{1}{\epsilon_1} \right) F_n + \left(\frac{\epsilon_2}{\epsilon_1} - 1 \right) \frac{\delta_{n0}}{N_0} \right], \quad N_0 = \frac{1}{\sqrt{z_4 - z_1}} \quad (A8)$$

$$F_n = \frac{1}{k_n} \sqrt{\frac{2 - \delta_{n0}}{z_4 - z_1}} \sin k_n(z - z_1) \Big|_{z_2}^{z_3} \quad (A8)$$

$$\lambda_n^2 = k_n^2 - \omega^2, \quad \lambda_n = +\sqrt{\lambda_n^2} \quad (A9)$$

$$\bar{\lambda}_n^2 = \lambda_n^2 - \omega^2 A_{nn} \quad (A9)$$

$$T_n(n) = \bar{S}_n^a I_1(\bar{\lambda}_n n) + \bar{S}_n^b K_1(\bar{\lambda}_n n) \quad n_1 \leq n \leq n_2 \quad (A10)$$

$$C_n(n) = \bar{C}_n^a I_1(\bar{\lambda}_n n) + \bar{C}_n^b K_1(\bar{\lambda}_n n) \quad (A10)$$

$$B_n = \omega^2 \left[\left\{ (\mu_n - \mu_1) - \epsilon_2 \mu_2 \left(\frac{1}{\epsilon_n} - \frac{1}{\epsilon_1} \right) \right\} F_n + \left(\mu_1 - \frac{\epsilon_2 \mu_2}{\epsilon_1} \right) \frac{\delta_{n0}}{N_0} \right] \quad (A11)$$

$$\begin{pmatrix} \bar{C}_n^a \\ \bar{C}_n^b \end{pmatrix} = \pi_2 \bar{\lambda}_n \begin{pmatrix} K_0(\bar{\lambda}_n \pi_2) & K_1(\bar{\lambda}_n \pi_2) \\ I_0(\bar{\lambda}_n \pi_2) & -I_1(\bar{\lambda}_n \pi_2) \end{pmatrix} \begin{pmatrix} K_1(\lambda_n \pi_2) \\ \frac{\lambda_n}{\bar{\lambda}_n} K_0(\lambda_n \pi_2) \end{pmatrix} \quad (\text{A12})$$

$$\begin{pmatrix} \bar{S}_n^a \\ \bar{S}_n^b \end{pmatrix} = \frac{\pi_1 \bar{\lambda}_n}{C_n^b} \begin{pmatrix} K_0(\bar{\lambda}_n \pi_1) & K_1(\bar{\lambda}_n \pi_1) \\ I_0(\bar{\lambda}_n \pi_1) & -I_1(\bar{\lambda}_n \pi_1) \end{pmatrix} \begin{pmatrix} I_1(\lambda_n \pi_1) \\ \frac{\lambda_n}{\bar{\lambda}_n} I_0(\lambda_n \pi_1) \end{pmatrix} \quad (\text{A13})$$

$$\begin{pmatrix} C_n^a \\ C_n^b \end{pmatrix} = \lambda_n \pi_1 \begin{pmatrix} K_0(\lambda_n \pi_1) & K_1(\lambda_n \pi_1) \\ I_0(\lambda_n \pi_1) & -I_1(\lambda_n \pi_1) \end{pmatrix} \begin{pmatrix} \bar{C}_n^a I_1(\bar{\lambda}_n \pi_1) + \bar{C}_n^b K_1(\bar{\lambda}_n \pi_1) \\ \frac{\bar{\lambda}_n}{\lambda_n} [\bar{C}_n^a I_0(\bar{\lambda}_n \pi_1) - \bar{C}_n^b K_0(\bar{\lambda}_n \pi_1)] \end{pmatrix} \quad (\text{A14})$$

$$\begin{pmatrix} S_n^a \\ S_n^b \end{pmatrix} = \lambda_n \pi_2 \begin{pmatrix} K_0(\lambda_n \pi_2) & K_1(\lambda_n \pi_2) \\ I_0(\lambda_n \pi_2) & -I_1(\lambda_n \pi_2) \end{pmatrix} \begin{pmatrix} \bar{S}_n^a I_1(\bar{\lambda}_n \pi_2) + \bar{S}_n^b K_1(\bar{\lambda}_n \pi_2) \\ \frac{\bar{\lambda}_n}{\lambda_n} [\bar{S}_n^a I_0(\bar{\lambda}_n \pi_2) - \bar{S}_n^b K_0(\bar{\lambda}_n \pi_2)] \end{pmatrix} \quad (\text{A15})$$

$$\Delta Y = \frac{2\pi\pi_3}{z_4 - z_1} \left[\frac{B^b K_1(i\omega\pi_3) + I_1(i\omega\pi_3)}{-B^b K_0(i\omega\pi_3) + I_0(i\omega\pi_3)} - \frac{I_1(i\omega\pi_3)}{I_0(i\omega\pi_3)} \right] \quad (\text{A16})$$

$$B^b = \frac{B + H^{(1)} + \omega^2 H^{(2)}}{A} \quad (\text{A17})$$

$$H^{(1)} = B_0 H^{(\eta)} + D_0^a T_0(\pi_1) + D_0^b T_0(\pi_2) \quad (\text{A18})$$

$$H^{(\eta)} = \bar{S}_0^a (H_0^{(5)}(\pi_2) - H_0^{(5)}(\pi_1)) + \bar{S}_0^b (H_0^{(6)}(\pi_2) - H_0^{(6)}(\pi_1)) \quad (\text{A19})$$

$$H^{(2)} = \sum_{n>0} A_{0n} H_n^{(2)} \quad (\text{A20})$$

$$H_n^{(2)} = \int_{\pi_1}^{\pi_2} T_0(\pi) R_n(\pi) d\pi \quad (\text{A21})$$

$$R_n(\pi) = \pi [C_n(\pi) H_n^{(3)}(\pi) + T_n(\pi) H_n^{(4)}(\pi)] \quad (\text{A22})$$

$$H_n^3(n) = D_n^a T_n(n_1) + B_n \left\{ \begin{array}{l} \bar{S}_n^a [H_n^{(5)}(n) - H_n^{(5)}(n_1)] \\ + \bar{S}_n^b [H_n^{(6)}(n) - H_n^{(6)}(n_1)] \end{array} \right\} \quad (A23)$$

$$H_n^{(4)}(n) = D_n^b C_n(n_2) + B_n \left\{ \begin{array}{l} \bar{C}_n^a [H_n^{(5)}(n_2) - H_n^{(5)}(n)] \\ + \bar{C}_n^b [H_n^{(6)}(n_2) - H_n^{(6)}(n)] \end{array} \right\} \quad (A24)$$

$$H_n^{(5)}(n) = \bar{A} P_1^n(n) + \bar{B} P_2^n(n) \quad (A25)$$

$$H_n^{(6)}(n) = \bar{A} P_3^n(n) + \bar{B} P_4^n(n) \quad (A26)$$

$$P_1^n(n) = [n (I_1(\bar{x}_n) I_0(\bar{x}) \bar{\lambda} - \bar{\lambda}_n I_0(\bar{x}_n) I_1(\bar{x}))] / \bar{z}_n \quad (A27)$$

$$P_2^n(n) = [-n (I_1(\bar{x}_n) K_0(\bar{x}) \bar{\lambda} + \bar{\lambda}_n I_0(\bar{x}_n) K_1(\bar{x}))] / \bar{z}_n \quad (A28)$$

$$P_3^n(n) = [n (K_1(\bar{x}_n) I_0(\bar{x}) \bar{\lambda} + \bar{\lambda}_n K_0(\bar{x}_n) I_1(\bar{x}))] / \bar{z}_n \quad (A29)$$

$$P_4^n(n) = [-n (K_1(\bar{x}_n) K_0(\bar{x}) \bar{\lambda} - \bar{\lambda}_n K_0(\bar{x}_n) K_1(\bar{x}))] / \bar{z}_n \quad (A30)$$

$$\bar{z}_n = \bar{\lambda}_n^2 - \bar{\lambda}^2, \quad \bar{x}_n = \bar{\lambda}_n n, \quad \bar{x} = \bar{\lambda} n$$

APPENDIX B

FORTTRAN LISTING

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PROGRAM CAPACITOR
COMMON R,Z,F,U1, SK,ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1, CAP
1CA,CB,SA,SB,X1,X2, Z21,Z31,Z41,UM,E1,EM,RATIO,Y1,Z32,IB,ONA, CAP
2SN1,SN2,DU,DE,AK,CFT,SUM,F2,ICYLE, TEMP,ST,C,B, SUB ,I1 CAP
3 ,STEP2
DIMENSION R(4),Z(4), SK(100,2),ALM(100,2),AL(100),AA(100), CAP
1AB(100),AD(100),ADB(100),BK0(500),BK1(500),BI0(500),BI1(500), CAP
2CA(100,2),CB(100,2),SA(100,2),SB(100,2),X1(2),X2(2),RATIO(2),Y2(3)CAP
3,SN1(100,2),SN2(100,2),CFT(6),SUM(7),SUB(2),ST(6) AP
4 ,C(3,2)
TYPE COMPLEX U1, ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,CA, CAP
1CB,SA,SB,X1,X2, X, UM,E1,EM, RATIO,Y1,AREA,Y2, CAP
2Y3, ONA,DU,DE, SUM, TEMP,ST ,SUB CAP
3,C,CFT ,E2,U2
DATA ( CON=2.0944E-10),(PI=1.668E-02 )
C THIS PROGRAM COMPUTES THE ADMITTANCE IN MHOS OF A TOROID SAMPLE CAP
C IN PARALLEL PLATE CAPACITOR. THE INPUT DATA IS THE THREE RAD1(CM),CAP
C THE FOUR Z AXIS VALUES, THE FREQUENCY (HZ),AND THE TWO SETS OF CAP
C VALUES FOR THE PERMITTIVITY AND PERMIBILITY. THE OUTPUT DATA CAP
C IS THE ADMITTANCES-- SECOND ORDER CORRECTION,QUASISTATIC, CAP
C AND TOTAL. CAP
SENSE LIGHT 1
ONA=(1.,0.)
2 READ 1,(R(I),I=1,3),Z,IA,IB,E1,U1 CAP
1 FORMAT(3E18.5/4E18.5/ 2I4/ 2C(E18.5,E18.5 )) CAP
C R IS RADIUS VALUES,Z IS HEIGHT VALUES IA=-1 IS ADMITTANCE TEST
C IA=0 SKIPS TEST OF SENSITIVITY IB=1 SKIPS HIGHER MODE =0 DOES IT
IT=-1 CAP
101 READ 102,E,IC,IS,ITES CAP
C E IS FREQUENCY IN HERTZ IC= NUMBER OF DIFFERENT EM AND UM
C IS IS PAGE NUMBER ITES=-1 TO EXIT AFTER NEXT BATCH OF DATA
C ITES=0 NEW SPACIAL DIMENSION =+1 NEW FREQUENCY
F= CON*E $ F2=F**2 CAP
102 FORMAT(E18.5,3I4) CAP
6 PRINT 7,IS,E,(R(I),I=1,3),Z,E1,U1 CAP
7 FORMAT( 51H1ADMITTANCE FOR CAPACITOR WITH TOROID GEOMETRY PAGE 14/CAP
118H THE FREQUENCY IS E18.4, 4HHZ. / CAP
227H THE RADIAL DIMENSIONS ARE 3E18.4 / CAP
327H THE Z AXIS DIMENSIONS ARE 4E18.4 /14H SPACER E1 IS CAP
4C(E18.4,E18.4),7H U1 IS C(E18.4,E18.4)/ CAP
591H THE LENGTH MEASUREMENTS ARE IN CM. ADMITTANCES ARE IN MHOS. TCAP
6HE REST ARE DIMENSIONLESS. //) CAP
PRINT 701 CAP
701 FORMAT(115H MU EPSILON QUACAP
1SI STATIC ADM CORRECT ADM DBL SUM ADM / CAP
2125H UM +I UM* EM +I EM* Y1 +ICAP
3 Y2 YC1 +I YC2 DY1 +I DY2 CNT )CAP
ITT=1 CAP
9 IS=IS+1 CAP
IF(IT)71,72,13 CAP
71 Z41= Z(4)-Z(1) $ B= 1./Z41 CAP
STEP2=(R(2)-R(1))/32. CAP
FIX= PI /Z41 CAP
212 Z21= Z(2)-Z(1)$ Z32=Z(3)-Z(2) CAP

```

```

Z31= Z(3)-Z(1) $ AK=(3.14159265)/Z41
72 AREA= FIX *(R(2)**2-R(1)**2)*(0.,0.5)*F CAP
12 DO 13 I1=1,IC CAP
211 FORMAT(2C(E18.5,E18.5)) CAP
225 READ 211, EM,UM CAP
Z5=Z32/Z41
E2=E1/(ONA+Z5*(E1/EM-ONA))
U2=U1+Z5*(UM-U1)
Y1=AREA*(E2-ONA)
15 CALL ADMIT(E2,U2)
216 X=R(3) *F*(0.,1.) $ CALL BESSL2(X,500) $ F3=FIX*R(3) CAP
DO 215 J=1,2 CAP
Y2(J)=F3*((RATIO(J)*BK1(500)+BI1(500))/(RATIO(J)*(-BK0(500))+
1BIO(500))-BI1(500)/BIO(500))
IF(IB)215,215,213
215 CONTINUE
IF(IA)217,218,218 CAP
217 X= 0.9*X $ F3=0.9*F3 $CALL BESSL2(X,500) $ ITT=ITT+1 CAP
Y2(3)=F3*((RATIO(2)*BK1(500)+BI1(500))/(RATIO(2)*(-BK0(500))+
1BIO(500))-BI1(500)/BIO(500))
PER= CABS( (Y2(2)-Y2(3))/Y2(2)) CAP
219 FORMAT(60H NEXT ADMITTANCE FRACTIONAL CHANGE WITH R(3)= 0.9*R(3) CAP
1IS E12.4) CAP
PRINT 219,PER CAP
GO TO 218 CAP
213 Y2(2)=Y2(1)
218 Y3=Y2(2)-Y2(1) CAP
302 PRINT 8,UM,EM,Y1,Y2(2),Y3,ICYLE CAP
8 FORMAT(C(E13.4,E12.4),4C(E12.4,E12.4),I4) CAP
ITT=ITT+1 CAP
IF(ITT-46)13,6,6 CAP
13 CONTINUE CAP
IF(ITES)240.2,103 CAP
103 IT=0 CAP
GO TO 101 CAP
240 CALL EXIT CAP
END CAP
SUBROUTINE SAVE(J) CAP
COMMON R,Z,F,U1, SK,ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BIO,BI1, CAP
1CA,CB,SA,SB,X1,X2, Z21,Z31,Z41,UM,E1,EM,RATIO,Y1,Z32,IB,ONA, CAP
2SN1,SN2,DU,DE,AK,CFT,SUM,F2,ICYLE, TEMP,ST,C,B, SUB ,IT CAP
DIMENSION R(4),Z(4), SK(100,2),ALM(100,2),AL(100),AA(100), CAP
1AB(100),AD(100),ADB(100),BK0(500),BK1(500),BIO(500),BI1(500), CAP
2CA(100,2),CB(100,2),SA(100,2),SB(100,2),X1(2),X2(2),RATIO(2),Y2(3)CAP
3,SN1(100,2),SN2(100,2),CFT(6),SUM(7),SUB(2),ST(6) AP
4 ,C(3,2)
TYPE COMPLEX U1, ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BIO,BI1,CA, CAP
1CB,SA,SB,X1,X2, X, UM,E1,EM, RATIO,Y1,AREA,Y2, CAP
2Y3, ONA,DU,DE, SUM, TEMP,ST ,SUB CAP
3,C,CFT
IF(IT)50,101,101
50 J1=0
IT=1
B1=B*1.414213562 $B2=SQRTF(B) $B3=B2*1.414213562 $B4=B/2.0

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```

X6=Z32*B $SN2(1,1)=X6      $SN2(1,2)=B2*( Z32)
2   GO TO 9                                     SAVE
101  IF( J-J1) 10,10,3
3   SK(J,1)=SK(J-1,1)+AK
SK(J,2)=SK(J,1)**2
X4=SK(J,1)*Z21
X5=SK(J,1)*Z31
SN1(J,2)=(SINF(X5)-SINF(X4))/SK(J,1) $ SN2(J,2)= SN1(J,2)*B3
SN1(J,1)=((SINF( 2.*X5)-SINF(2.*X4))/( SK(J,1)))*B4
SN2(J,1)= (SN1(J,1)+X6
SN1(J,2)= SN1(J,2)*B1
9   J1=J1+1
10  RETURN
END
SUBROUTINE INTGR(J)
COMMON R,Z,F,U1, SK,ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1, CAP
1CA,CB,SA,SB,X1,X2, Z21,Z31,Z41,UM,E1,EM,RATIO,Y1,Z32,IB,ONA, CAP
2SN1,SN2,DU,DE,AK,CFT,SUM,F2,ICYLE, TEMP,ST,C,B, SUB
3,IT,STEP2,T,HC,AF,P
DIMENSION R(4),Z(4), SK(100,2),ALM(100,2),AL(100),AA(100), CAP
1AB(100),AD(100),ADB(100),BK0(500),BK1(500),BI0(500),BI1(500), CAP
2CA(100,2),CB(100,2),SA(100,2),SB(100,2),X1(2),X2(2),RATIO(2),Y2(3)CAP
3,SN1(100,2),SN2(100,2),CFT(6),SUM(7),SUB(2),ST(6)
4,H(8,2),T(6,2),HC(5), P(4),C(3,2),AF(33)
TYPE COMPLEX U1, ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,CA, CAP
1CB,SA,SB,X1,X2,T0,P1,P2,P3,P4,X,X3,UM,E1,EM, RATIO,Y1,AREA,Y2, CAP
2Y3, ONA,DU,DE,CFT,SUM,H,T,CR,HC,TEMP,ST ,P,C,AF,SUB
TYPE COMPLEX HF1,HF2,HF3,HF4,HF5, HFB3,HFB4,HFB5,HFB6, INTGR
1 RF,TF,CF,RFB,TFB,CFB,X0,X5,RT,RTB,DM1,DM2 ,RA1,RA2,RC,AL4 INTGR
TF(K,K1)= SA(K,2)*BI1(K1)+SB(K,2)*BK1(K1) INTGR
CF(K,K1)= CA(K,2)*BI1(K1)+CB(K,2)*BK1(K1) INTGR
P1(K1,K2)= BI1(K1)*BI0(K2)*X0- X*BI0(K1)*BI1(K2) INTGR
P2(K1,K2)= -(BI1(K1)*BK0(K2)*X0+X*BI0(K1)*BK1(K2) )
P3(K1,K2)= BK1(K1)*BI0(K2)*X0+X*BK0(K1)*BI1(K2) INTGR
P4(K1,K2)= -(BK1(K1)*BK0(K2)*X0-X*BK0(K1)*BK1(K2) )
HF5(I)=(SA(100,2)*P(I)+SB(100,2)*P(I+1))
HF3(K) =(SA(K,2)*H(5,1)+SB(K,2)*H(6,1) )*ADB(K) INTGR
HF4(K) =(CA(K,2)*H(5,1)+CB(K,2)*H(6,1) )*ADB(K) INTGR
IF(J-1)1,1,3
84 SUM(4)=(AF(1)+AF(33))/(2.,0.) INTGR
DO 85 L=5,30,4 INTGR
85 SUM(4)=SUM(4)+AF(L) INTGR
SUM(5)= 2.*(SUM(4)+2.*SUM(3)) INTGR
SUM(6)= SUM(4)+SUM(3)+2.*SUM(2) INTGR
SUM(1)= (SUM(6)-SUM(5))/(SUM(6)*15.) INTGR
TOO = CABS(SUM(1)) $ J3=J-1 INTGR
IF( TOO -0.02) 87,87,86
86 PRINT 90,TOO,J3 INTGR
90 FORMAT(* THE INTEGRATION ERROR IS* E10.2 *THE MODE NUMBER IS* I4) INTGR
87 ST(4)= (STEP*0.666666667)*SUM(6) INTGR
RETURN INTGR
1 I8=1 $ GO TO 2
3 I8=2
2 JB1=J+100 INTGR

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JB2=J+300
R(4)=R(1)
JR=JB1 $ JS=200
I6=1 $ I7=2
GO TO 10
20 R(4)=R(2)
H(1,1)= H(3,1) $ H(7,1)=H(4,1)
T(1,1)= T(3,1)
I6=2
HC(2)=AL(J)*T(1,1)-H(1,1)
JR=JB2 $JS=400
GO TO 10
30 H(2,1)=H(3,1) $H(8,1)=H(4,1)
T(2,1)=T(3,1)
GO TO (90,91),I8
91 C(2,1)=C(3,1)
HC(3)= AB(J)*C(2,1)+H(8,1)
I7=1
R(4)=R(2)
RA1 = (C(3,1)*(H(3,1)+HC(2))+T(3,1)*(HC(3)-H(4,1))) *R(4)
JR= J+400 $JS=500
AF(1)= RA1*HC(5)
STEP=0.15/ CABS(ALM(J,2))
IF(STEP-STEP2)32,32,31
31 STEP=STEP2
32 DO 80 L=2,33
R(4)=R(4)- STEP
I6=3
GO TO 10
40 X=ALM(1,2)*R(4)
CALL BESSL2(X,401) $ T(6,1)=TF(1,401)
RA1 = (C(3,1)*(H(3,1)+HC(2))+T(3,1)*(HC(3)-H(4,1))) *R(4)
80 AF(L)=RA1*T(6,1)
DO 81 L=2,3
81 SUM(L)=(0.,0.)
DO 82 L=2,33,2
82 SUM(2)=SUM(2)+AF(L)
DO 83 L=3,33,4
83 SUM(3)=SUM(3)+AF(L)
GO TO 84
10 X0= ALM(100,2)*R(4)
X = ALM(J,2)*R(4)
GO TO (11,12),I7
11 CALL BESSL2(X0,500)
CALL BESSL2(X ,JR )
12 P(1)= P1(JR,JS )
P(2)= P2(JR,JS )
P(3)= P3(JR,JS )
P(4)= P4(JR,JS )
H(5,1)=HF5(1)
H(6,1)=HF5(3)
H(3,1)=HF3(J) $ T(3,1)=TF(J,JR)
GO TO (851,861),I8
861 H(4,1)=HF4(J) $ C(3,1)=CF(J,JR)

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851 GO TO (20,30,40),I6
90 HC(3)=AB(1)*T(2,1)
  ST(5)=HC(3)+HC(2)+H(2,1)
  HC(5)=T(2,1)
  RETURN
  END
  SUBROUTINE COEF(J)
  COMMON R,Z,F,U1, SK,ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,
1 CA,CB,SA,SB,X1,X2, Z21,Z31,Z41,UM,E1,EM,RATIO,Y1,Z32,IB,ONA,
2 SN1,SN2,DU,DE,AK,CFT,SUM,F2,ICYLE, TEMP,ST,C,B, SUB
  DIMENSION R(4),Z(4), SK(100,2),ALM(100,2),AL(100),AA(100),
1 AB(100),AD(100),ADB(100),BK0(500),BK1(500),BI0(500),BI1(500),
2 CA(100,2),CB(100,2),SA(100,2),SB(100,2),X1(2),X2(2),RATIO(2),Y2(3)
3 ,SN1(100,2),SN2(100,2),CFT(6),SUM(7),SUB(2),ST(6)
4 ,C(3,2)
  TYPE COMPLEX U1, ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,CA,
1 CB,SA,SB,X1,X2, X, UM,E1,EM, RATIO,Y1,AREA,Y2,
2 Y3, ONA,DU,DE, SUM, TEMP,ST, SUB
3 ,C,CFT
  J1= J
  JB1=J+100
  J2 =J+200
  JB2=J+300
  CALL BESSL2(X1(1),J1)
  CALL BESSL2(X1(2),JB1)
  CALL BESSL2(X2(1),J2)
  CALL BESSL2(X2(2),JB2)
  TEMP= ALM(J,1)/ALM(J,2)
  IF(J-100)5,7,7
7 TEMP=EM*TEMP
  CB(100,1)=(1.,0.)
  GO TO 6
5 CA(J,2)=(BK0(JB2)*BK1(J2)-BK1(JB2)*TEMP*BK0(J2))*X2(2)
  CB(J,2)=(BI0(JB2)*BK1(J2)+BI1(JB2)*TEMP*BK0(J2))*X2(2)
  CB(J,1)= ( BI0(J1)*(CA(J,2)*BI0(JB1)-CB(J,2)*BK0(JB1))
1 -BI1(J1)*(CA(J,2)*BI0(JB1)-CB(J,2)*BK0(JB1))/TEMP)*X1(1)
6 SA(J,2)=(BK0(JB1)*BI1(J1)+BK1(JB1)*TEMP*BI0(J1))*X1(2)/CB(J,1)
  SB(J,2)=(BI0(JB1)*BI1(J1)-BI1(JB1)*TEMP*BI0(J1))*X1(2)/CB(J,1)
  IF(J-1) 1,1,2
1 ST(1)=(SA(J,2)*BI1(JB2)+SB(J,2)*BK1(JB2))*X2(1)
  ST(2)=(SA(J,2)*BI0(JB2)-SB(J,2)*BK0(JB2))*X2(1)/TEMP
  SA(J,1)= BK0(J2)*ST(1)+BK1(J2)*ST(2)
  SB(J,1)= BI0(J2)*ST(1)-BI1(J2)*ST(2)
3 RETURN
2 IF(J-100)3,1,3
  END
  SUBROUTINE ADMIT(E2,U2)
  COMMON R,Z,F,U1, SK,ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,
1 CA,CB,SA,SB,X1,X2, Z21,Z31,Z41,UM,E1,EM,RATIO,Y1,Z32,IB,ONA,
2 SN1,SN2,DU,DE,AK,CFT,SUM,F2,ICYLE, TEMP,ST,C,B, SUB ,IT
  DIMENSION R(4),Z(4), SK(100,2),ALM(100,2),AL(100),AA(100),
1 AB(100),AD(100),ADB(100),BK0(500),BK1(500),BI0(500),BI1(500),
2 CA(100,2),CB(100,2),SA(100,2),SB(100,2),X1(2),X2(2),RATIO(2),Y2(3)
3 ,SN1(100,2),SN2(100,2),CFT(6),SUM(7),SUB(2),ST(6)
  AP
INTGR
COEF
CAP
CAP
CAP
CAP
CAP
AP
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CAP
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4 ,C(3,2)
TYPE COMPLEX U1, ALM, BB, BA, AL, AA, AB, AD, ADB, BK0, BK1, B10, B11, CA, CAP
1CB, SA, SB, X1, X2, X, UM, E1, EM, RATIO, Y1, AREA, Y2, CAP
2Y3, ONA, DU, DE, SUM, TEMP, ST, SUB, CAP
3, C, CFT, DE1, DE2, AAA, DE3, AAB
4, DE4, DE5, DE6, E2, U2, E3, AAC, AAD, AL4, AL5, AL8
TYPE REAL MS1, MS2, MIC1, MIC2
IF (IT) 58, 63, 63
58 Z6=SQRTF(Z41)
63 DU=UM*EM-U1*E1
DE=E1*U1-1. $DE6=U2*E2 $DE5=E2/E1-1. $DE3=CSQRT(DE6)
DE1=E2*(1./EM-1./E1) $DE2=-F2*(DE1*U2-UM+U1) $DE4=(U1-DE6/E1)*F2
DE4=DE4*Z6 $DE5=DE5*Z6
C FO CASE HAS I=100
C BAR STUFF IN EQUATIONS IS LABELED BY TWO ADMIT
SK(1,1)=0. ADMIT
IF DIVIDE CHECK 101,101
101 CALL SAVE(1)
AD(1)= DU*SN2(1,1) +DE ADMIT
ALM(1,1)= (0.,1.)*F $ALM(100,1)=ALM(1,1) ADMIT
E3=EM $EM=E2
ALM(100,2)=ALM(100,1)*DE3
11 AL4=ALM(100,2)**2
ALM(1,2)= CSQRT(F2*(1.+AD(1)))*(0.,1.)
AL8=ALM(1,2)**2-AL4
IF(CABS(AL8/AL4)-1.0E-6)600,600,604
600 PRINT 602
602 FORMAT(* CONDITIONS OF SYSTEM ARE SUCH THAT THE ACCURACY IS */
1* TOTALLY UNRELIABLE *)
CALL EXIT
604 ADB(1)=DE2*SN2(1,2) +DE4
ADB(1)=ADB(1)/AL8
DO 150, J=1,100,99
X1(1)= ALM(J,1)*R(1) ADMIT
X1(2)= ALM(J,2)*R(1) ADMIT
X2(1)= ALM(J,1)*R(2) ADMIT
X2(2)= ALM(J,2)*R(2) ADMIT
150 CALL COEF (J) ADMIT
EM=E3
AAC= X1(1) *B10(100)
AAD=-X2(1) *(SA(100,1)*B10(300)-SB(100,1)*BK0(300))
AAA=DE1*AAC $AAB=DE1*AAD
AL(1)=AAA*SN2(1,2) +AAC*DE5
AB(1)=AAB*SN2(1,2) +AAD*DE5
IF DIVIDE CHECK 40,200
200 BA= SA(1,1) -1. ADMIT
IF(CABS(BA)-1.E-7)201,201,220
220 PRINT 42
42 FORMAT(*NORMALIZATION ERROR HAS OCCURRED*)
201 BB= SB(100,1)
ICYCLE =0
IA=-1
IF EXPONENT FAULT 499,499
499 CALL INTGR(1)

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      IF EXPONENT FAULT 500,501
500  RATIO(1)=RATIO(2)=(0.,0.)      $ GO TO 40
501  BB=BB+ST(5)
      SUB(2)=BB
      RATIO(1)=BB/SA(100,1)
      IF(IB)1,1,2
1    DO 100,I=2,99      $ I=I
      CALL SAVE(I)
      ICYLE =ICYLE+1
      AD(I)=DU*SN2(I,1)+DE
      AL(I)=AAA*SN2(I,2) $AB(I)=AAB*SN2(I,2)
      ALM(I,1)=      ( SK(I,2) -F2)
      ALM(I,2)=      ( ALM(I,1)  -F2*AD(I))
      AL5=ALM(I,2)-AL4 $ALM(I,2)=CSQRT(ALM(I,2))
      IF(CABS(AL5/AL4)-1.0E-6)600,600,601
601  ADB(I)=DE2*SN2(I,2)/AL5
      ALM(I,1)= CSQRT(ALM(I,1)) $AA(I)=SN1(I,2)*DU
      X1(1)=ALM(I,1)*R(1)
      X1(2)=ALM(I,2)*R(1)
      X2(1)=ALM(I,1)*R(2)
      X2(2)=ALM(I,2)*R(2)
      CALL COEF(I)
      IF DIVIDE CHECK 40,300
300  IF EXPONENT FAULT 301,301
301  CALL INTGR(I)
      IF EXPONENT FAULT 40,400
400  ST(6)      = ST(4)*AA(I)      *F2
      MS2= CABS(SUB(2))*(0.001)
      MIC2=CABS(ST(6))
      SUB(2)=SUB(2)+ST(6)
20   IF( MS2-MIC2) 100,100,99
99   IF(IA)102,103,2
102  I4=I+1 $IA=  0 $ GO TO 100
103  IF(I-I4)2,2,97
97   I4=I+1
100  CONTINUE
2    RATIO(2)=SUB(2)/SA(100,1)
      RETURN
40   PRINT 41
41   FORMAT(*NEXT LINE HAS HAD AN OVERFLOW OR DIVIDE CHECK*)
      RETURN
      END
      SUBROUTINE BESSL2(X7,I)
      COMMON R,Z,F,U1, SK,ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,
1CA,CB,SA,SB,X1,X2,      Z21,Z31,Z41,UM,E1,EM,RATIO,Y1,Z32,IB,ONA,
2SN1,SN2,DU,DE,AK,CFT,SUM,F2,ICYLE, TEMP,ST,C,B,  SUB
      DIMENSION R(4),Z(4),      SK(100,2),ALM(100,2),AL(100),AA(100),
1AB(100),AD(100),ADB(100),BK0(500),BK1(500),BI0(500),BI1(500),
2CA(100,2),CB(100,2),SA(100,2),SB(100,2),X1(2),X2(2),RATIO(2),Y2(3)
3,SN1(100,2),SN2(100,2),CFT(6),SUM(7),SUB(2),ST(6)
4 ,C(3,2)
      TYPE COMPLEX U1, ALM,BB,BA, AL,AA,AB,AD,ADB,BK0,BK1,BI0,BI1,CA,
1CB,SA,SB,X1,X2,      X,  UM,E1,EM,      RATIO,Y1,AREA,Y2,
2Y3,  ONA,DU,DE,      SUM,      TEMP,ST      ,SUB

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3,C,CFT
TYPE DOUBLE X4,X5,H01A,H01B,H02A,H02B,H11A,H11B,H12A,H12B
TYPE COMPLEX X3,PH,X7
DATA (PH=(0.,1.))
IF DIVIDE CHECK 2,1
1 X3=X7*PH
X4=X3 $ X5=X7
CALL ALLH(X4,X5,H01A,H01B,H02A,H02B,H11A,H11B,H12A,H12B)
B11(1)=(0.,-0.5)*((H11A+H12A)+PH*(H11B+H12B))
BK1(1)=(-1.57079633,0.)*(H11A+PH*H11B)
IF(I-401)100,200,100
100 B10(1)=0.5*((H01A+H02A)+PH*(H01B+H02B))
BK0(1)=(0.,1.57079633)*(H01A+PH*H01B)
200 IF DIVIDE CHECK 22,3
2 J=1 $ GO TO 21
22 J=2
21 PRINT 4,I,J
4 FORMAT(* NEXT, LINE HAS BESSL2 DIVIDE CHECK I= *,2I4)
3 RETURN
END
SUBROUTINE ALLH(ZA,ZB,H01A,H01B,H02A,H02B,H11A,H11B,H12A,H12B)
C THE REMAINING SUBROUTINES ARE A PACKAGE FOR HANKEL FUNCTION
C GENERATION . THIS PACKAGE WAS DEVELOPED BY GARNEY HARDY
TYPE DOUBLE ZA,ZB,H01B,H01A,H02A,H02B,H11A,H11B,H12A
2,H12B,X,Y,ABSZ
X=ZA
Y=ZB
ABSZ=DSQRT(X*X+Y*Y)
IF(ABSZ-7.7D)1,1,3
1 CALL HSMALL(X,Y,H01A,H01B,H02A,H02B,H11A,H11B,H12A,H12B)
RETURN
3 CALL HLARGE(X,Y,H01A,H01B,H02A,H02B,H11A,H11B,H12A,H12B)
RETURN
END
SUBROUTINE CHIS(CHI)
DIMENSION CHI(20)
TYPE DOUBLE CHI
CHI(1)=1.57D
CHI(2)=2.D
CHI(3)=2.36D
CHI(4)=2.67D
CHI(5)=2.95D
CHI(6)=3.2D
CHI(7)=3.44D
CHI(8)=3.66D
CHI(9)=3.87D
CHI(10)=4.06D
CHI(11)=4.26D
CHI(12)=4.43D
CHI(13)=4.61D
CHI(14)=4.77D
CHI(15)=4.94D
CHI(16)=5.09D
CHI(17)=5.25D
BESSL2
BESSL2

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CHI(18)=5.39D
CHI(19)=5.54D
CHI(20)=5.68D
RETURN
END
SUBROUTINE AS(A0,A1)
DIMENSION A0(20),A1(20)
TYPE DOUBLE A0,A1
TYPE DOUBLE AN
A0(1)=-.125D
A1(1)=.375D
DO 1 N=2,20
AN=N
A0(N)=-((2.D*AN-1.D)**2)*A0(N-1))/(AN*8.D)
1 A1(N)=((4.D0-((2.D0*AN-1.D0)**2))*A1(N-1))/(AN*8.D0)
RETURN
END
SUBROUTINE JSMALL(X,Y,AJOA,AJOB,AJ1A,AJ1B)
TYPE DOUBLE X,Y,AJOA,AJOB,AJ1A,AJ1B,ZA,ZB,AM,ZMA,
1 ZMB,SIGN ,SUMA,SUMB,FACTM,TERMA,TERMB
ZA=X
ZB=Y
ZA=ZA/2.D
ZB=ZB/2.D
CALL ZMPY(ZA,ZB,ZA,ZB,ZA,ZB)
AM=0.D
FACTM=1.D
ZMA=1.D
ZMB=0.D
SUMA=1.D
SUMB=0.D
SIGN=1.D
1 CALL ZMPY(ZA,ZB,ZMA,ZMB,ZMA,ZMB)
SIGN=-SIGN
AM=AM+1.D
FACTM=FACTM*AM
TERMA=ZMA/(FACTM*FACTM)
TERMB=ZMB/(FACTM*FACTM)
SUMA=SUMA+SIGN*TERMA
SUMB=SUMB+SIGN*TERMB
2 IF (DABS(TERMA)+DABS(TERMB)-1.D-13)3,1,1
3 AJOA=SUMA
AJOB=SUMB
AM=1.D
FACTM=1.D
ZMA=1.D
ZMB=0.D
SUMA=1.D
SUMB=0.D
SIGN=1.D
5 CALL ZMPY(ZA,ZB,ZMA,ZMB,ZMA,ZMB)
SIGN=-SIGN
FACTM=FACTM*AM
AM=AM+1.D

```

```

TERMA=ZMA/(FACTM*FACTM*AM)
TERMB=ZMB/(FACTM*FACTM*AM)
SUMA=SUMA+SIGN*TERMA
SUMB=SUMB+SIGN*TERMB
4 IF(DABS(TERMA)+DABS(TERMB)-1.D-13)7,5,5
7 AJ1A=SUMA/2.D
  AJ1B=SUMB/2.D
  CALL ZMPY(X,Y,AJ1A,AJ1B,AJ1A,AJ1B)
  RETURN
  END
SUBROUTINE HSMALL(X,Y,H01A,H01B,H02A,H02B ,H11A,H11B,H12A,H12B)
TYPE DOUBLE X,Y,H01A,H01B,H02A,H02B,H11A,H11B,H12A,
1H12B,ZA,ZB,AJOA,AJOB,AJ1A,AJ1B,PSI,SIX,SUMA,
2SUMB,S,FACTS,TERMA,TERMB,ALOG,BLOG,FUNNYA,
3FUNNYB,ZMA,ZMB,SIGN
  ZA=X
  ZB=Y
  CALL JSMALL(ZA,ZB,AJOA,AJOB,AJ1A,AJ1B)
  PSI=-.577215664901532860606512D
  SIX=.6366197723675813430755350D
  ZA=ZA/2.D
  ZB=ZB/2.D
  CALL ZMPY(ZA,ZB,ZA,ZB,ZA,ZB)
  ZMA=1.D
  ZMB=0.D
  SUMA=PSI
  SUMB=0.D
  S=0.D
  FACTS=1.D
  SIGN=1.D
1 CALL ZMPY(ZA,ZB,ZMA,ZMB,ZMA,ZMB)
  SIGN=-SIGN
  S=S+1.D
  FACTS=FACTS*S*S
  PSI=PSI+1.D/S
  TERMA=PSI*ZMA/FACTS
  TERMB=PSI*ZMB/FACTS
  SUMA=SUMA+SIGN*TERMA
  SUMB=SUMB+SIGN*TERMB
  IF(DABS(TERMA)+DABS(TERMB)-1.D-13)3,1,1
3 H01A=AJOA+SUMB*SIX
  H01B=AJOB-SUMA*SIX
  H02A=AJOA-SUMB*SIX
  H02B=AJOB+SUMA*SIX
  PSI=-.577215664901532860606512D
  ZMA=1.D
  ZMB=0.D
  SUMA=PSI+PSI+1.D
  PSI=SUMA
  SUMB=0.D
  S=0.D
  FACTS=1.D
  SIGN=1.D
5 CALL ZMPY(ZA,ZB,ZMA,ZMB,ZMA,ZMB)

```

```

SIGN=-SIGN
S=S+1.D
FACTS=FACTS*S*(S+1.D)
PSI=PSI+1.D/S+1.D/(S+1.D)
TERMA=PSI*ZMA/FACTS
TERMB=PSI*ZMB/FACTS
SUMA=SUMA+SIGN*TERMA
SUMB=SUMB+SIGN*TERMB
IF(DABS(TERMA)+DABS(TERMB)-1.D-13)7,5,5
7 CALL ZMPY(ZA,ZB,SUMA,SUMB,SUMA,SUMB)
SUMA=SUMA+1.D
CALL ZMPY(X,Y,AJ1A,AJ1B,AJ1A,AJ1B)
H11A=AJ1A+SIX*SUMB
H11B=AJ1B-SIX*SUMA
H12A=AJ1A-SIX*SUMB
H12B=AJ1B+SIX*SUMA
ZA=X/2.D
ZB=Y/2.D
  ALOG=DSQRT(ZA*ZA+ZB*ZB)
  ALOG=DLOG(ALOG)
BLOG=DATAN2(Y,X)
FUNNYA=-SIX*BLOG
FUNNYB=SIX*ALOG
CALL ZDIV(AJ1A,AJ1B,X,Y,AJ1A,AJ1B)
CALL ZMPY(FUNNYA,FUNNYB,AJOA,AJOB,AJOA,AJOB)
CALL ZMPY(FUNNYA,FUNNYB,AJ1A,AJ1B,AJ1A,AJ1B)
H01A=H01A+AJOA
H01B=H01B+AJOB
H02A=H02A-AJOA
H02B=H02B-AJOB
CALL ZDIV(H11A,H11B,X,Y,H11A,H11B)
CALL ZDIV(H12A,H12B,X,Y,H12A,H12B)
H11A=H11A+AJ1A
H11B=H11B+AJ1B
H12A=H12A-AJ1A
H12B=H12B-AJ1B
RETURN
END
SUBROUTINE HLARGE(X,Y,H01A,H01B,H02A,H02B,H11A,H11B,H12A,H12B)
  TYPE DOUBLE X,Y,H01A,H01B,H02A,H02B,H11A,H11B,H12A,
1H12B,ZA,ZB,RIPI,PI,ABSZ,ARGZ,ABZM,FACTO,FACT1,SUM01A,
2SUM02A,SUM01B,SUM02B,SUM11A,SUM11B,SUM12A,SUM12B,
3CXA,CXB,CXNEGA,CXNEGB,ZSA,ZSB,EPS,EPA,PA,PB,QA,QB,
4ZHALA,ZHALB,EY
  DIMENSION CHI(20),A0(20),A1(20)
  TYPE DOUBLE A0,A1,CHI
  ZA=X
  ZB=Y
  IF(SENSE LIGHT 1)1,3
1 RIPI=.5641895835477562869480795D
  PI=3.141592653589793238462643D
  CALL CHIS(CHI)
  CALL AS(A0,A1)
3 ABSZ=DSQRT(ZA*ZA+ZB*ZB)

```

```

ARGZ=DATAN2(ZB,ZA)
IF(DABS(ARGZ)-PI/2.D)29,29,31
31 IF(ARGZ-PI/2.D)33,29,35
35 ZA=-ZA
   ARGZ=PI-ARGZ
   M=1
   GO TO 37
33 ZA=-ZA
   ZB=-ZB
   ARGZ=ARGZ+PI
   M=2
   GO TO 37
29 M=3
37 ABZM=1.D
   FACT0=2.D*DEXP(PI/(8.D*ABSZ))
   FACT1=2.D*DEXP((3.D*PI)/(8.D*ABSZ))
   SUM01A=1.D
   SUM01B=0.D
   SUM02A=1.D
   SUM02B=0.D
   SUM11A=1.D
   SUM11B=0.D
   SUM12A=1.D
   SUM12B=0.D
   CXA=1.D
   CXB=0.D
   CXNEGA=1.D
   CXNEGB=0.D
   ZSA=1.D
13 ZSB=0.D
   EPS=1.D
   DO 5 K=1,20
   EPA=EPS
   ABZM=ABZM*ABSZ
   EPS=FACT0*CHI(K)*DABS(AO(K))/ABZM
   IF(EPS-EPA)19,7,7
19 CALL ZMPY(ZSA,ZSB,ZA,ZB,ZSA,ZSB)
   CALL ZMPY(CXA,CXB,0.D,1.D,CXA,CXB)
   CALL ZMPY(CXNEGA,CXNEGB,0.D,-1.D,CXNEGA,CXNEGB)
   PA=CXA*AO(K)
15 PB=CXB*AO(K)
   CALL ZDIV(PA,PB,ZSA,ZSB,QA,QB)
   SUM01A=SUM01A+QA
   SUM01B=SUM01B+QB
   PA=CXNEGA*AO(K)
17 PB=CXNEGB*AO(K)
   CALL ZDIV(PA,PB,ZSA,ZSB,QA,QB)
   SUM02A=SUM02A+QA
   SUM02B=SUM02B+QB
18 IF(EPS-1.D-10)7,7,5
5 CONTINUE
7 CALL ZMPY(RIPI,-RIPI,SUM01A,SUM01B,H01A,H01B)
   CALL ZMPY(RIPI,RIPI,SUM02A,SUM02B,H02A,H02B)
   CXA=1.D

```

```

CXB=0.D
CXNEGA=1.D
CXNEGB=0.D
ZSA=1.D
ZSB=0.D
ABZM=1.D
EPS=1.D
DO 9 K=1,20
EPA=EPS
ABZM=ABZM*ABSZ
EPS=FACT1*CHI(K)*DABS(A1(K))/ABZM
IF(EPS-EPA)25,11,11
25 CALL ZMPY(CXA,CXB,0.D,1.D,CXA,CXB)
CALL ZMPY(CXNEGA,CXNEGB,0.D,-1.D,CXNEGA,CXNEGB)
CALL ZMPY(ZSA,ZSB,ZA,ZB,ZSA,ZSB)
PA=CXA*A1(K)
21 PB=CXB*A1(K)
CALL ZDIV(PA,PB,ZSA,ZSB,QA,QB)
SUM11A=SUM11A+QA
SUM11B=SUM11B+QB
PA=CXNEGA*A1(K)
23 PB=CXNEGB*A1(K)
CALL ZDIV(PA,PB,ZSA,ZSB,QA,QB)
SUM12A=SUM12A+QA
SUM12B=SUM12B+QB
24 IF(EPS-1.D-10)11,11,9
9 CONTINUE
11 CALL ZMPY(-RIPI,-RIPI,SUM11A,SUM11B,H11A,H11B)
CALL ZMPY(-RIPI,RIPI,SUM12A,SUM12B,H12A,H12B)
ZHALA=DSQRT(ABSZ)*DCOS(.5D*ARGZ)
ZHALB=DSQRT(ABSZ)*DSIN(.5D*ARGZ)
EY=DEXP(ZB)
PA=DCOS(ZA)/EY
PB=DSIN(ZA)/EY
CALL ZDIV(PA,PB,ZHALA,ZHALB,QA,QB)
CALL ZMPY(H01A,H01B,QA,QB,H01A,H01B)
CALL ZMPY(H11A,H11B,QA,QB,H11A,H11B)
CALL ZMPY(PA,PB,ZHALA,ZHALB,QA,QB)
CALL ZDIV(H02A,H02B,QA,QB,H02A,H02B)
CALL ZDIV(H12A,H12B,QA,QB,H12A,H12B)
GO TO (39,41,43),M
39 H02A=2.D*H01A+H02A
H02B=-2.D*H01B-H02B
H12A=-2.D*H11A-H12A
H12B=2.D*H11B+H12B
H01A=-H01A
H11B=-H11B
RETURN
41 PA=H01A
PB=H01B
QA=H11A
QB=H11B
H01A=2.D*H01A+H02A
H01B=2.D*H01B+H02B

```

```
H11A=-2.D*H11A-H12A
H11B=-2.D*H11B-H12B
H02A=-PA
H02B=-PB
H12A=QA
H12B=QB
43 RETURN
END
```

APPENDIX C

SAMPLE CALCULATION

ADMITTANCE FOR CAPACITOR WITH TOROID GEOMETRY PAGE 1

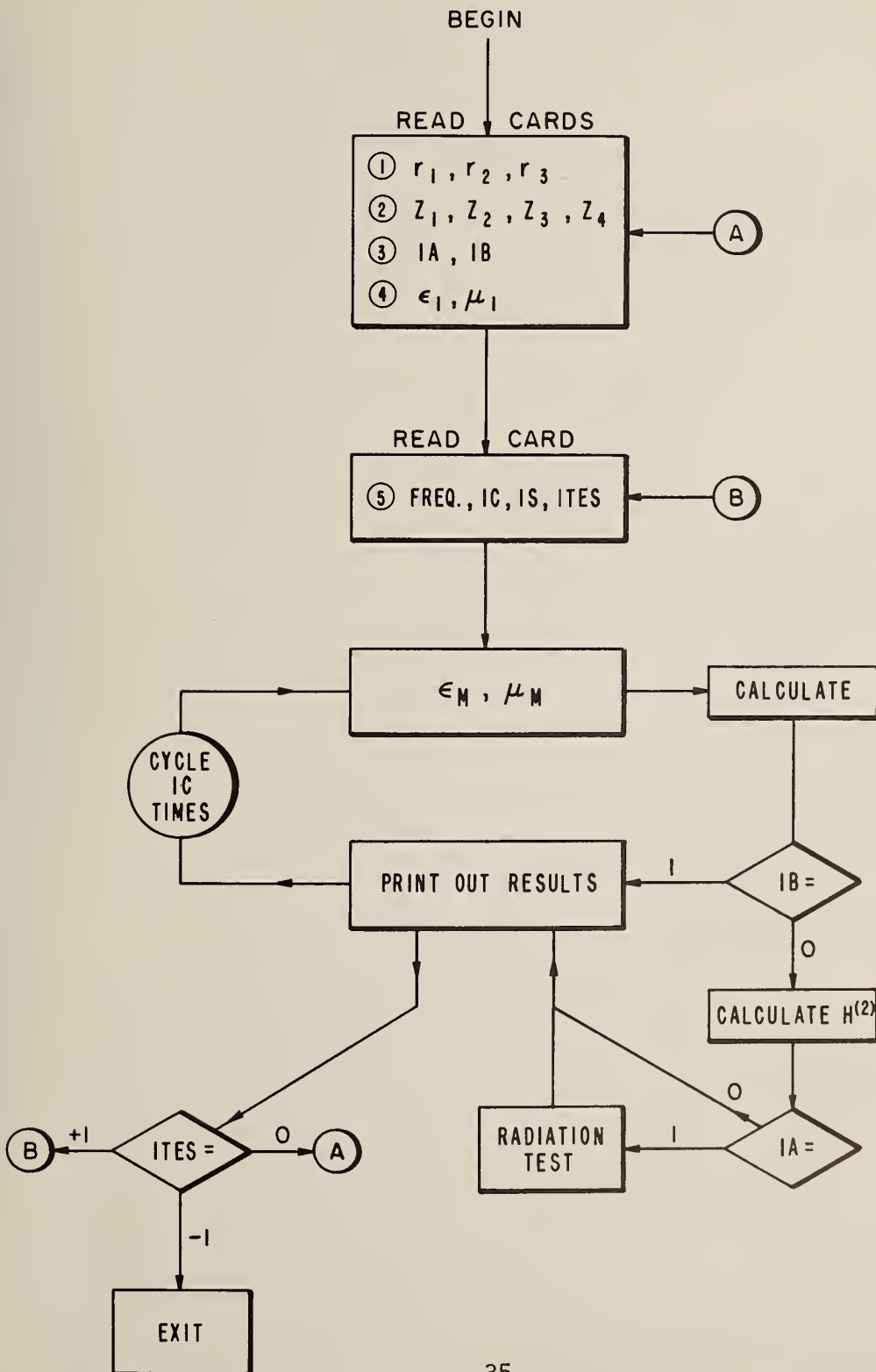
THE FREQUENCY IS 1.0000×10^6 HZ.
 THE RADIAL DIMENSIONS ARE 1.1176×10^0 2.5400×10^0
 -6.5550×10^{-2} 6.2750×10^{-2}
 THE Z AXIS DIMENSIONS ARE 1.0000×10^0 6.5550×10^{-2}
 SPACER E1 IS 2.0000×10^0 -0.0000×10^0 U1 IS 1.0000×10^0 -0.0000×10^0
 THE LENGTH MEASUREMENTS ARE IN CM. ADMITTANCES ARE IN MHOS. THE REST ARE DIMENSIONLESS.

33

UM	MU	EPSILON	QUASI STATIC ADM	CORRECT ADM	DBL SUM ADM	
$+I$	$+I$	$+I$	$+I$	YC1	DY1	
EM	EM	Y1	$+I$	$+I$	$+I$	CNT
NEXT ADMITTANCE FRACTIONAL CHANGE WITH R(3) =	IS	$0.9 \times R(3)$	IS	5.8630-008		
2.7050+003	-5.8000+001	1.2060+005	-1.0900+005	3.4586-008	1.8311-004	3.6301-008
						1.8312-004
						1.5731-009
						-1.2497-009
						2



APPENDIX D FLOW CHART OF MACHINE PROGRAM







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