# NATIONAL BUREAU OF STANDARDS REPORT 

9651

ALLOCATING SERVICE PERIODS TO MINIMIZE DETAY TIME
by
W.A. Horn

Technical Report
to

Northeast Corridor Transportation Project


U.S. DEPARTMENT OF COMMERCE<br>NATIONAL BUREAU OF STANDARDS

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## U.S. DEPARTMENT OF COMMERCE

NATIONAL BUREAU OF STANDARDS

# ALLOCATING SERVICE PERIODS TO MINIMIZE DELAY TIME 

W.A. Horn

## National Bureau of Standards

## ABSTRACT

Consider a facility which must divide its services, during the time interval $[0, T]$, among $N$ streams of arrivals. The problem treated j.s that of finding a pattern of service which minimizes total delay to the members of the streams, taking into account the "dead time" which begins each service period. For each stream, it is required that final queue size equal initial size, and that the queue be empty sometime in $[0, T]$. Conditions for feasibj.lity of solutions are given in the case where the instantaneous service rates are bounded above by known constants. In the event that all streams have constant arrival rates and are to be served the same number of times, an optimal service pattern is derived using a recent result of R. Rangarajan and R.M. Oliver.

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key words
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Transportation theory, queueing theory, traffic flow, switching theory, scheduling, allocation.

# ALLOCATING SERVICE PERIODS TO MINIMIZE DHLAY TIME 

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## 1. PROBLEM STATEMENT

This paper presents a further investigation into the type of problem studied in [l]. The problem pertains to the allocation of servicing times among several incoming streams which require "processing" of some kind by a single "server" capable of handling only one stream at a time. The server might for example be a switching point or a congestion point (e.g., a tunnel entrance) in a transport network, in which case "serving" a stream simply means permitting passage to its flow. Or, the server might be a computer handling reservations being arranged at several points, or exercising control on a real-time basis over operations along several liniks.

The time period during which servicing occurs is assumed to be $[0, T]$, where $T>0$. The rate at which "customers" arrive at stream $i$ is assumed to be the known continuous function $a_{i}(t)$, while the outflow or service-rate function $s_{i}(t)$, which will be defined below, is bounded above by the constant $C_{i}>0$, the capacity when servicing stream i. It is further assumed that $a_{i}(t)$ crosses the level $C_{i}$ at most a finite number of times in [O,T7. That is, $a_{i}^{-1}\left(C_{i}\right)$ is a set with a finite number of connected components.

The size of the waiting queue in stream $i$ at time $t$ is designated by $Q_{i}(t)$, and we let $q_{i}=Q_{i}(0)$, where it is assumed that each $q_{i}$ is non-negative. Then clearly

$$
\begin{equation*}
Q_{i}(t)=q_{i}+\int_{0}^{t}\left(a_{i}(\tau)-s_{i}(\tau)\right) d \tau \tag{I}
\end{equation*}
$$

A cumulative waiting time function $W_{i}(t)$ is defined for each $i$ by

$$
W_{i}(t)=\int_{0}^{t} Q_{i}(\tau) d \tau
$$

and a total waiting time function $W(t)$ is defined by

$$
W(t)=\sum_{i=1}^{N} W_{\dot{i}}(t)
$$

where N is the number of streams.

Since $s_{i}(t)$ will depend on the times at which servicing actually occurs, it is clear that $W_{i}$ and $W$ also depend on these variables. Furthermore, $W_{i}$ and $W$ depend on the quantities $q_{i}$. These functional dependencies may be expressed explicitly when convenient.

Next we define $s_{i}(t)$. As a preliminary, we further limit the generality of the problem by assuming that a given stream i is serviced, within $[0, T]$, only during a finite set of closed intervals $\left\{\left[x_{i j}, y_{i j}\right]\right\}_{j=l}^{m(i)}$ where $m(i)$ is the total number of such intervals of service to stream i . No two intervals of servicing, for any streams. may overlap except at their endpoints, and the set of all service intervals for all streams covers [0,T]. (The endpoints of these intervals comprise the switching pattern.) Furthermore, for some set of positive constants $\left\{\dot{\alpha}_{i}\right\}$ called the "dead" times, it is assumed that $x_{i j}+d_{i} \leq y_{i j}$, for $i=1,2, \ldots, \mathbb{N}$, and $j=1,2, \ldots, m(i)$.

If stream $i$ is not being serviced at time $t$, then $s_{i}(t)$ is defined to be 0 . If $t$ lies in the service interval $\left\lceil x_{i j}, y_{i j}\right\rceil$, then $s_{i}(t)$ is defined by

$$
\begin{gathered}
0: t_{\epsilon}\left[x_{i j}, x_{i j}+d_{i}\right], \\
s_{i}(t)=\quad C_{i}: t_{\epsilon}\left(x_{i j}+d_{i}, y_{i j}\right] \text { and } Q_{i}(t)>0, \\
\min \left(C_{i}, a_{i}(t)\right): t_{\epsilon}\left(x_{i j}+d_{i}, y_{i j}\right] \text { and } \\
Q_{i}(t) \leq 0 .
\end{gathered}
$$

「It is clear from ( 1 ) that $Q_{i}$ depends on $s_{i}$, whereas the above definition states that $s_{i}$ depends on $Q_{i}$, at least on the intervals $\left(x_{i j}+d_{i}, y_{i j}\right]$. Thus it is necessary to show that there exist unique functions $s_{i}$ and $Q_{i}$ which satisfy ( 1 ) and the equation for $s_{i}$. This will not be detailed here, although it is quite simple due to the particular form of $a_{i}(t)$. Briefly, the proof consists of constructing the unique $s_{i}$ and $Q_{i}$ by breaking up each interval $\left(x_{i j}+d_{i}, y_{i j}\right]$ into subintervals where either $a_{i}(t) \leq C_{i}$ or $a_{i}(t)>C_{i}$. The functions $s_{i}$ and $C_{i}$ are then defined in the natural way and easily shown to be unique. 1

The above definition of $s_{i}$, together with the fact that $q_{i} \geq 0$, assures that $Q_{i}(t) \geq 0$ for all $\left.t_{\epsilon} \Gamma 0, T\right\rceil$, since if $Q_{i}(t)<0$ for some $t$ then there would exist $t^{\prime}<t$ such that $Q_{i}\left(t^{\prime}\right)=0$, by the continuity of $Q_{i}$. Let $t_{0}^{\prime}$ be the greatest such $t$ ! Then $Q_{i}(r) \leq 0$ for all $r$ such that $t_{0}^{\prime} \leq r \leq t$, and so $a_{i}(r)-s_{i}(r) \geq 0$ in this interval, by the definition of $s_{i}$. This contradicts the fact that

$$
0>Q_{i}(t)=Q_{i}\left(t_{0}^{\prime}\right)+\int_{t_{0}^{\prime}}^{t}\left(a_{i}(r)-s_{i}(r)\right) d r .
$$

The general problem to be considered is that of finding a finite set of intervals $\left[x_{i j}, y_{i j}\right]$ of service, as defined and restricted above, such that the total waiting time $W(T)$ is a minimum, given the initial values $q_{i}$.

We will consider a variant of the general problem in this paper by introducing the restrictions (for $i=1,2, \ldots, N$ )
(2)

$$
\begin{align*}
& q_{i}=Q_{i}(0)=Q_{i}(T), \\
& Q_{i}(t)=0 \text { for some } t_{\epsilon}[0, T], \tag{3}
\end{align*}
$$

and by alllowing the minimization not only over the intervals of servicing but also over the parameters $q_{i}$ as well. That is, the $q_{i}$ will not be considered fixed but variable, subject to (2) and (3). Constraints (2) and (3) are called the feasibility constraints, and a solution is feasible if it satisfies them.

Imposing constraint (2) has the property of making the problem periodic, in the following sense. If we suppose that $a_{i}$ is defined for all $t \geq 0$, rather than for $t_{\epsilon}[0, T]$, with $a_{i}(t+T)=a_{i}(t)$, and that the switching pattern is extended in such a way that stream i is being serviced at time $t+T$ if and only if it is also being serviced at time $t$, then $Q_{j}(0)=Q_{i}(\mathbb{I})$ implies

$$
Q_{i}(t+T)=Q_{i}(t)
$$

It is also seen from this that

$$
W_{i}(T+t)-W_{i}(t)=W_{i}(T),
$$

or,

$$
W_{i}(n T+\theta)=n W_{i}(T)+W_{j}(\theta)
$$

This in turn implies that

$$
W(t) / t \rightarrow W(T) / T \quad \text { as } \quad t \rightarrow \infty,
$$

so that, in a sense, minimizing $W(T)$ and thus $W(T) / T$ is equivalent to minimizing the "long-term average delay". The motivation for this restriction is that the applications we have in mind refer to ongoing systems rather than isolated occurrences. It seems of little practical use (except for emergency evacuation operations and the like) to formulate the problem as if what happened after time $T$ were of no concern: Condition (2), at least for periodic arrival patterns, implies stability in the sense of "repeatability" for the situation, in particular ruling out unbounded growth of queues over the long run. It might prove worthwhile to investigate the problem variant in which (2) is replaced by

$$
Q_{i}(T) \leq Q_{i}(0),
$$

but this version will not be studied here.
2. FEASIBILITY AND CONSISTENCY CONDITIONS

So far it is not known whether there exist feasible solutions of the problem of section 1 . This section will be devoted to finding necessary and sufficient conditions for the existence of such solutions.

Since we are considering the problem where not only the points of switching are allowed to vary, but also the $q_{i}$, the first question which arises is how much freedom the $q_{i}$ have, for a given switching pattern, so that conditions (2) and (3) may still be satisfied. The following two lemmas answer this.

LEMMA 1. Let $Q_{i}$ and $Q_{i}^{\prime}$ be the queue-size functions associated with the initial values $q_{i}$ and $q_{i}^{\prime}$, respectively, and having the same switching pattern. Then $\left|Q_{i}(t)-Q_{i}^{\prime}(t)\right|$ is a nonincreasing function of $t$.

PROOF. First, $Q_{i}-Q_{i}^{\prime}$ does not change sign. For if $Q_{i}(a)-Q_{i}^{\prime}(a)>0$ and $Q_{i}(b)-Q_{i}^{\prime}(b)<0$, where $a<b$, then by continuity $Q_{i}(t)=Q_{i}^{\prime}(t)$ for some $t_{\epsilon}(a, b)$. But then $Q_{i}(\tau)=Q_{i}^{\prime}(\tau)$ for all $\tau \geq t$, contradicting $Q_{i}(b)<Q_{i}^{\prime}(b)$.

Now suppose (say) $Q_{i}(0)>Q_{i}^{\prime}(0)$. Then $Q_{i}(t)-Q_{i}^{\prime}(t)=\left|Q_{i}(t)-Q_{i}^{\prime}(t)\right|$, by the above. But

$$
Q_{i}(t)-Q_{i}^{\prime}(t)=q_{i}-q_{i}^{\prime}+\int^{t}\left(s_{i}^{\prime}(\tau)-s_{i}(\tau)\right) d \tau,
$$

and since $s_{i}^{\prime}(\tau) \leq s_{i}(\tau)$
for all $\tau \in[0, T]$ because $Q_{i} \geq Q_{i}^{\prime}$, we have that $\left|Q_{1}(t)-Q_{i}^{\prime}(t)\right|$ is non-increasing. Similarly if $Q_{i}(0)<Q_{i}^{\prime}(0)$ or $Q_{i}(0)=Q_{i}^{\prime}(0)$.

LEMMA 2. Let $Q_{i}$ and $Q_{i}^{\prime}$ be two queue-size functions associated with the same switching pattern during $\lceil 0, T\rceil$ and both satisfying (2). Then $Q_{i}$ and $Q_{i}^{1}$ differ by a constant. Hence there exists at most one feasible solution for each switching pattern.

PROOF. From lemma l,

$$
\left|Q_{i}(0)-Q_{i}^{\prime}(0)\right| \geq\left|Q_{i}(t)-Q_{i}^{\prime}(t)\right| \geq\left|Q_{i}(T)-Q_{i}^{\prime}(T)\right| \text { for all }
$$

$t_{\epsilon}[0, T]$. But by (2), $\left|Q_{i}(0)-Q_{i}^{\prime}(0)\right|=\left|Q_{i}(T)-Q_{i}^{\prime}(T)\right|$.
Hence, by the continuity of the queue-size functions, $Q_{i}(t)-Q_{i}^{\prime}(t)=q_{i}-q_{i}^{\prime}$, a constant.

Now if two solutions having the same switching pattern are both feasible, then they satisfy (3) in addition to (2). But if $q_{i}>q_{i}^{\prime}$, for example, then $Q_{i}(t)>Q_{i}^{\prime}(t) \geq 0$, by the above, and $Q_{i}$ is not feasible. Therefore $q_{i}=q_{i}^{\prime}$ and so $Q_{i}=Q_{i}^{\prime}$.

The next question to be treated is which patterns of switching times admit feasible solutions.

THEOREM 3. Suppose that stream i is serviced during successive intervals of length $L_{i 工}, L_{i 2}, \ldots, L_{i m}(i)$, and let $\alpha_{i}$ be the dead time for stream i . Then a necessary and sufficient condition that a set of $q_{i}$ exist for which the given switching pattern produces a feasible solution is

$$
C_{i} \sum_{j=1}^{m(i)} L_{i j} \geq \int_{0}^{T} a_{i}(t) d t+m(i) C_{i} d_{i}
$$

for all i.

PROOF. Let the above inequality be satisfied. It is clear that, when $q_{i}$ is sufficiently large, $Q_{i}(t)>0$ for all $t_{\epsilon}[0, T]$. Then, by definition, $s_{i}(t)=0$ during non-service intervals and during a part $d_{i}$ of each service interval, and $s_{i}(t)=C_{i}$ otherwise. Thus for such $q_{i}$,

$$
\begin{aligned}
\int_{0} s_{i}(t) d t & =C_{i} \sum_{j=1}^{m(i)}\left(I_{i, j}-d_{i}\right) \\
& =C_{i} \sum_{j=1}^{m(i)} I_{i j}-C_{i} m(i) d_{i} \\
& \geq \int_{0}^{T} a_{i}(t) d t,
\end{aligned}
$$

so that

$$
\begin{aligned}
Q_{i}(T) & =q_{i}+\int_{0}^{T}\left(a_{i}(t)-s_{i}(t)\right) d t \\
& <q_{i} .
\end{aligned}
$$

On the other hand, for $q_{i}=0$ it is clear that $Q_{i}(T) \geq q_{i}$.
But for a fixed switching pattern, $Q_{i}(T)$ is a continuous function of $q_{i}$. (In fact, by lemma $1,\left|Q_{i}(T)-Q_{i}^{\prime}(T)\right| \leq\left|q_{i}-q_{i}^{\prime}\right|$.) Thus there exists a $q_{i}$ for which $Q_{i}(T)=q_{i}$.

Let $q_{i}^{0}$ be the infimum of all such $q_{i}$ satisfying $q_{i}=Q_{i}(T)$ for the given pattern of switching. Let

$$
b=\inf \left\{Q_{i}(t): t_{\epsilon}[0, T], Q_{i}(0)=q_{i}^{0}\right\}
$$

If $b=0$, then $q_{i}^{0}$ gives a feasible solution. But if $b>0$, then using the value $q_{i}=q_{i}^{0}-b / 2$ as the initial queue size, we find that $Q_{i}(t) \geq b-b / 2=b / 2$ for all $t_{\epsilon}[0, T\rceil$, by lemma 1 . Thus by the definition of $s_{i}$ we have the same value of $s_{i}(t)$, for each $t_{\epsilon}[0, T]$, for the two initial values $q_{i}^{0}$ and $q_{i}^{0}-b / 2$. But this implies that the solution with initial value $q_{i}^{0}-b / 2$ also satisfies (2), contradicting the definition of $q_{i}^{0}$.

This proves sufficiency.

Necessity follows from (2), via the inequality

$$
\begin{aligned}
\int_{0}^{T} a_{i}(t) d t & =\int_{0}^{T} s_{i}(t) d t \\
& \leq C_{i} \sum_{j=1}^{m(i)}\left(I_{i j}-d_{i}\right) .
\end{aligned}
$$

LEMMA 4. Suppose there exist numbers $\mathbb{T}_{i}>0$ such that

$$
\sum_{i=1}^{N} T_{i}=T
$$

and

$$
C_{i} T_{i} \geq \int_{0}^{T} a_{i}(t) d t+m(i) c_{i} d_{i}
$$

Then there exists a feasible solution for which stream $i$ is serviced exactly $m(i)$ times (some of which may be consecutive), and there exists an optimal such solution relative to the particular $m(i)$ 's.

PROOF. By Theorem 3, if $\left\{L_{i j}\right\}$ is a set satisfying

$$
\sum_{j=1}^{m(i)} L_{i j}=T_{i},
$$

where each $L_{i j} \geq d_{i}$, then $L_{i j}$ represents a feasible solution. By lemma 2, $q_{i}$ is uniquely determined by the switching pattern. But the vector of switching times is a point of

$$
[0, T]^{5 m(i)}
$$

a compact set. The conditions(given in Theorem 2) defining those switching patterns which correspond to feasible solutions are linear inequalities in the $\mathrm{L}_{i j}{ }^{\text {s }} \mathrm{s}$, and so in the switching times themselves;
thus the minimization is to take place over a closed subset of the compact set.

Now it may be shown that $W(T)$ depends continuiously on the switching times. In fact, $W(T)$ is uniformly continuous in the vector of switching times. (The proof, which is lengthy but not difficult, will not be given here. However, briefly, the following argument is used. $\operatorname{Let}\left\{\left(x_{i j}, y_{i j}\right)\right\}$ and $\left\{\left(x_{i j}^{\prime}, y_{i j}\right)\right\}$ be two feasible switching patterns which differ, for any stream i, in at most one term. If the first pattern, for example, results in less service to stream $i$, let $q_{i}$ be the initial value for $Q_{i}(t)$ associated with this pattern. Apply the second pattern to this starting value, obtaining a new $Q_{i}(T)=q_{i}^{\prime}$. It can be shown that this $q_{i}^{1}$ is the initial value of the i-th queue associated with the second pattern.)

Since $W(T)$ depends continuously on the switching times, which in turn range over a compact set, an optimal solution must exist.

The last result permits us to state explicit conditions for the existence of an optimal solution in the simplest case, namely for constant $a_{i}$.

COROLLARY 5. Suppose $a_{i}(t)=a_{i}$, a constant. If $\left\{I_{i j}\right\}$ are the service interval lengths of a switching pattern such that
(4) $\quad \sum_{j=1} I_{i j} \geq m(i) d_{i}+a_{i} T / C_{i}$,
then the pattern is feasible. Furthermore, if numbers $T_{i}>0$ exist such that

$$
\sum_{i=1}^{N} T_{i}=T
$$

and

$$
T_{i} \geq m(i) d_{i}+a_{i} T / C_{i}
$$

then an optimal feasible solution exists.

PROOF. From Theorem 3 and Lemma 4.

Now let $o_{i}=a_{i} / C_{j}$ and $d=\sum_{i=1} m(i) d_{i}$. Then we have the following.

THEOREM 6. For constant $a_{i}$, the following conditions are necessary and sufficient for the existence of a feasible solution with $m$ (i) servicings of stream $i$ which is optimal with respect to the given $\operatorname{set}\{m(i)\}$ :
(5)

$$
\mathrm{N}
$$

$$
\sum_{i=1} \rho_{i}<1
$$

(6)

$$
T \geq \frac{d}{1-\sum_{i=1}^{N} \rho_{i}}
$$

PROOF. If $\left\{L_{i j}\right\}$ is feasible, by Lemma 5 it must satisfy (4). Summing (4) over all i , we get

$$
T \geq \sum_{i=1}^{N} m(i) d_{i}+T \sum_{i=1}^{N}\left(a_{i} / c_{i}\right)
$$

$$
\begin{equation*}
=a+T \sum_{i=1}^{N} \rho_{i}, \tag{7}
\end{equation*}
$$

or equivalently

$$
T\left(1-\sum_{i=1}^{N} \rho_{i}\right) \geq d>0 .
$$

N
Since $T>0$, we have $1-\sum_{i=1} o_{i}>0$, proving (5), and also

proving (6).

Now suppose (5) and (6) are satisfied. Then (7) is also satisfied. Thus it is possible to find $T_{i}>0$ such that

$$
T_{i} \geq m(i) d_{i}+a_{i} T / C_{i} .
$$

The result follows from Corollary 5.

## 3. OPTIMAL SOLUTITONS FOR CONSTANT ARRIVAL RATES AND EQUAL $m(i)$ 's

This section will deal with the special case in which each $a_{i}(t)$ is a constant function, and the $m(i)$ are all equal to some common value $m$. This case was treated in [l], with the further provision that $m=1$, that is, that each stream was serviced exactly once.

A method of finding the optimum service period length for each stream was found in [ 1$]$, and this is the result to be generalized here. It will be shown that an optimum (not necessarily the optimum) switching pattern is obtained for the case $m(i)=m, a_{i}$ constant, when the interval [O,T] is broken up into $m$ subintervals of equal length, the switching pattern is optimized over the first interval $[0, T / m]$ by the methods of [l] with one servicing per stream, and this pattern is repeated cyclically for each of the other $m-1$ subintervals. In addition to this, an auxiliary result of [l] will be used to find the optimum value of $m$.

LEMMA 7. Suppose that in the interval $[s, t]$ the function $f(x)$ is either increasing at a rate $p$ or decreasing at a rate $-q$ almost everywhere. Suppose that $f(s)=f(t)=0$ and that $f(x) \geq 0$ for $x_{\epsilon}(s, t)$. Suppose further that $f$ increases during $\left[s, s+A_{1}\right)$, decreases during $\left(s+A_{1}, s+A_{1}+B_{1}\right)$, etc., where each interval of
increase of length $A_{i}$ is followed by en interval of decrease oi
length $B_{i}$, and each interval of decrease of length $B_{i}$ is
followed by an interval of increase of length $A_{i+1}$, the last
intervals being of length $A_{n}$ and $B_{n}$ respectively. Then

$$
\int_{s}^{t} f(x) \bar{a} x \geq \frac{p(p+q)}{2 q} \sum_{i=1}^{n} A_{i}^{2}
$$

PROOF. The proof is geometric in nature and is by induction on $n$. First, for $n=1$ the inequality reduces to

$$
\int_{s}^{t} f(x) d x \geq \frac{p(p+q)}{2 q} A_{1}^{2}
$$

Referring to figure 1 , we see that $\int_{s}^{t} f(x) d x$ is the area of the triangle whose altitude is $A_{1} P$ and whose base is $A_{1}+B_{I}$, where

$$
B_{1}=A_{1} p / q
$$

Thus $\int_{s}^{t} f(x) d x=\frac{p(p+q)}{2 q} A_{1}^{2}$, proving the case $n=1$.

Assume that the lemma has been proved for $1,2, \ldots, n-1$. Looking at fingure 2, we see that

$$
\begin{aligned}
\int_{s}^{t} f(x) d x & \geq \frac{p(p+q)}{2 q} \sum_{i=1}^{n-1} A_{i}^{2}+\text { Area YWVZX } \\
& \geq \frac{p(p+q)}{2 q} \sum_{i=1}^{n-1} A_{i}^{2}+\Delta X Y Z \\
& =\frac{p(p+q)}{2 q} \sum_{i=1}^{n-1} A_{i}^{2}+\frac{p(p+q)}{2 q} A_{n}^{2} \\
& =\frac{p(p+q)}{2 q} \sum_{i=1}^{n} A_{i}^{2} .
\end{aligned}
$$



$$
\text { Figuere } 1
$$



Figure $\Sigma$

We now state the following notations to be used during the rest of this section. $I_{i j}$ will denote the $j$-th interval of service for lane $i$ during $\Gamma 0, T]$. Because of the cyclic character of the problem we also define

$$
I_{i k} \equiv I_{i j}
$$

where $I \leq j \leq m$ and $k \equiv j(\bmod m)$. We denote the length of $I_{i j}$ by $I_{i j}$. The interval contained between $I_{i j}$ and $I_{i, j+1}$ (or the two intervals, if $j=m$ ) will be denoted by $J_{i j}$ and its length (respectively, the sum of their lengths) by $M_{i j}$.

LEMMA 8. Let $S$ be a feasible switching pattern for a problem with constant $a_{i}$. Then

$$
W_{i}(T) \geq \frac{a_{1} c_{i}}{2\left(C_{i}-a_{i}\right)} \sum_{j=1}^{m(i)}\left(M_{i j}+d_{i}\right)^{2}
$$

PROOF. By definition, $W_{i}$ is the integral of $Q_{i}$, which is always non-negative. Thus $W_{i}$ may be thought of as the area under the curve representing $Q_{i}$. Since $C_{i}>a_{i}$ in order to satisfy feasibility, $Q_{i}$ is either rising at a rate $a_{i}$ (when $s_{i}=0$ ), falling at a rate $-\left(C_{i}-a_{i}\right)$ (when $\left.s_{i}=C_{i}\right)$, or constant at 0 (when $s_{i}=a_{i}$ ). We may represent this as in figure 3. It is also clear that the curve is rising only during the time that lane $i$ is not being serviced, plus the dead time, that is, during intervals of length $M_{i j}+d_{i}$.


Figure 3

Now let us group the $I_{i j}$ as follows. By condition (3), there exists $t_{0} \epsilon[0, T]$ such that $Q_{i}\left(t_{0}\right)=0$. Let $I_{i j}$ be the interval of service to lane $i$ to which $t_{o}$ belongs. (Obviously $t_{o}$ must lie in some interval of service.) Let $I_{i k}$ be the first interval after $I_{i j}$ during which $Q_{i}(t)$ is again 0 . Then the lengths of the intervals of non-service to $i$ between $I_{i j}$ and $I_{i k}$, namely $J_{i j}, J_{i, j+1}, \ldots, J_{i, k-1}$, will be $M_{i j}, M_{i, j+l}, \ldots, M_{i, k-1}$. If we let $z_{i q}$ represent the right endpoint of any interval $I_{i q}$, then from lemma 7 we have

$$
\int_{z_{i j}}^{z_{i k}} Q_{j}(t) d t \geq \frac{a_{i} C_{i}}{2\left(C_{i}-a_{i}\right)} \sum_{\nu=j}^{k-1}\left(M_{i \nu}+d_{i}\right)^{2}
$$

Summing this inequality over all intervals in which $Q_{i}$ becomes 0 , we get

$$
W_{i}(T)=\int_{0}^{T} Q_{i}(t) d t \geq \frac{a_{i} C_{i}}{2\left(C_{i}-a_{i}\right)} \sum_{j=1}^{m(i)}\left(M_{i j}+\bar{a}_{i}\right)^{2}
$$

This proves the lemma.

THEOREM 9. Suppose that, for constant $a_{i},\left\{I_{i j}\right\}$ represents an optimal feasible solution, where $m(i)=m$. Then there exists an optimal feasible solution $\left\{\bar{I}_{i j}\right\}$ with

$$
\bar{L}_{i j}=(I / m) \sum_{k=1}^{m} L_{i k}, I \leq i \leq n
$$

where $\bar{L}_{i j}$ is the length of interval $\bar{I}_{i j}, I_{i j}$ the length of $I_{i j}$.

PROOF. Consider the solution defined by $\bar{L}_{i j}=(1 / m) \sum_{k=I}^{m} I_{i k}$, where $\bar{I}_{l, l}$ is the first interval and where interval $\bar{I}_{i j}$ is followed by $\bar{I}_{i+1, j}$ for $i<n$, and interval $\bar{I}_{n j}$ is followed by $I_{1}, j+1$. Then we have

$$
\bar{M}_{i j}=\bar{M}_{i}, \quad l \leq j \leq n
$$

By lemma 8, the waiting time for the original solution satisfies

$$
W_{i}(T) \geq \frac{a_{i} C_{i}}{2\left(C_{i}-a_{i}\right)} \sum_{j=1}^{m}\left(M_{i j}+\alpha_{i}\right)^{2}
$$

and the Cauchy-Schwartz inequality yields

$$
\sum_{j=1}^{m}\left(M_{i j}+d_{i}\right)^{2} \geq m\left(\bar{M}_{i j}+d_{i}\right)^{2}=\sum_{j=1}^{m}\left(\bar{M}_{i j}+d_{i}\right)^{2}
$$

Thus it suffices to show that the new solution (which by corollary 5 is feasible) obeys Lemma 8 with equality, i.e. that

$$
\bar{W}_{i}(T)=\int_{0}^{T} \bar{Q}_{i}(t) d t=\frac{a_{i} C_{i}}{2\left(C_{i}-a_{i}\right)} \sum_{j=1}^{m}\left(\bar{M}_{i j}+d_{i}\right)^{2}
$$

From the proofs of lemmas 7 and 8 , it should be apparent that this is equivalent to proving that $\bar{Q}_{i}$ is reduced to $O$ during each service interval $\bar{I}_{i j}$. The condition for this is

$$
\begin{equation*}
\left(c_{i}-a_{i}\right)\left(\bar{L}_{i j}-d_{i}\right) \geq a_{i}\left(\bar{M}_{i j}+d_{i}\right), \tag{8}
\end{equation*}
$$

which will now be demonstrated.

By corollary 5,

$$
m \bar{L}_{i j}=\sum_{j=1}^{m} L_{i j} \geq m \alpha_{i}+a_{i} T / C_{i},
$$

and so

$$
c_{i}\left(\bar{L}_{i j}-d_{i}\right) \geq a_{i}(T / m)=a_{i}\left(\bar{M}_{i j}+d_{i}+\left(\bar{L}_{i j}-d_{i}\right)\right),
$$

implying (8) as desired.

Note that theorem 9 merely establishes the form of one optimal solution. It is clear that we could get a set of optimal solutions by permuting indices. Furthermore, it could probably be shown that these solutions are the only ones which are optimal, but this would involve solving a set of simultaneous linear equations relating the $M_{i, j}$ and $L_{i j}$ and this is not considered here to be worth the trouble.

Also, nothing is said about the case where $m(i) \neq m(k)$. This seems to be a much harder case to analyze generally. However, if $N=2$ the above proof may be modified so that this problem is completely solved. For in that case it is obvious that $m(1)=m(2)$,
since otherwise two servicings of some lane would be consecutive, giving a higher value for $W$ than that obtained by merging the two consecutive servicings into one. Also, $L_{i j}=M_{2, j-I}$ and $L_{2 j}=M_{i j}$. Thus the condition $M_{i j}=M_{i k}$ is equivalent to $I_{i j}=I_{i k}$.

Finally, we shall discuss the optimum value of $m$ to choose in the above problem, given T . Note that if $\left\{I_{i j}\right\}$ denotes an optimal solution on the interval $[O, T\rceil$ as described above, where each lane is serviced once during the interval [O,T/m] and this procedure is repeated $m$ times, then we have

$$
\operatorname{mW}(T / m)=W(T)
$$

This recalls the work of [l] in which the function to be minimized is $W(T) / T$ instead of $W(T)$. ( Of course, for constant $T$, minimizing $W(T)$ is equivalent to minimizing $W(T) / T$, and the first part of [l] considers the problem in this way.) We show how the results of [l] can be applied to the above problem.

Suppose that $T^{\prime}$ is a variable which is allowed to take on only the discrete set of values $T / m, m$ an integer, in the problem where each lane is serviced exactly once during the interval $\left[0, T^{\prime}\right]$. If $W\left(T^{\prime}\right) / T^{\prime}$ attains its minimum value on this discrete
set at the point $T^{T}=T_{O}^{1}=T / m_{O}$, then $W(T)$ in the original problem attains its minimum value over all $m$ for $m=m_{0}$. For we have

$$
\frac{W\left(T / \mathrm{m}_{0}\right)}{T / \mathrm{m}_{0}} \leq \frac{W(T / \mathrm{m})}{T / m},
$$

for $m \neq m_{0}$; or ,

$$
m_{O} W\left(T / m_{O}\right) \leq m W(T / m)
$$

But by the above remariss, $m W(T / m)=W(T)$, where $W(T)$ is calculated for $m$ cycles of service in the interval [ $0, T]$, and similarly for $m_{0} W\left(T / m_{0}\right)$.

Thus it is clear that finding $m_{O}$ such that $W(\mathbb{T})$, optimized over all switching patterns, attains its least value when each stream is serviced $m_{0}$ times, is equivalent to finding $m_{0}$ such that $W\left(T / m_{0}\right) /\left(T / m_{0}\right)$ is a minimum for the optimized solution of the one-cycle case. Now a method is given in $\lceil 1\rceil$ to optimize $W\left(T^{\prime}\right) / T T^{\prime}$ when $T^{\prime}$ is a continuous variable, and it is shown that $W\left(T^{1}\right) / T^{\prime \prime}$ is monotone decreasing to the left of the optimum, $T^{\prime}=T_{0}^{\prime}$, and monotone increasing to the right. Thus if $n$ is an integer such that

$$
T /(n+1) \leq T_{O}^{\prime} \leq T / n,
$$

it is clear that the optimum value $m_{o}$ sought above must be either $n$ or $n+1$. In order to determine which of these values is optimum, it is only necessary to substitute in the expression for the optimized value of $W\left(T^{\prime}\right) / T^{\prime}$, also given in [l]. Thus $m_{0}$ is easily determined.

## RFFERENCE

「1] R. Rangarajan and R.M. Oliver, "Allocations of Servicing Periods that Minimize Average Delay for $N$ Time-Shared Traffic Streams", Transportation Science,Vol. I (1957), pp. $74-80$.



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