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Research Priorities for Improving the Effectiveness of Active Solar Hot Water and Space Conditioning Systems

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U.S. DEPARTMENT OF COMMERCE, Malcolm Baldrige, Secretary NATIONAL BUREAU OF STANDARDS, Ernest Ambler, Director



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1. INTRODUCTION

1.1 Background

In 1980, a Department of Energy (DOE) program plan was developed to address the reliability and maintainability (R&M) of active solar energy systems [1]*. The goal of this R&M program was to "accelerate the removal of reliability and maintainability as major concerns impeding the widespread adoption of solar energy systems." Primary objectives of the program were to:

- o Provide all groups that have solar R&M concerns with the information that is available to the program and that is necessary to alleviate those concerns.
- Assist the solar energy industry in improving levels of R&M performance in state-of-the-art solar energy systems, components, and materials.
- Assist in the early development of a viable infrastructure for the design, manufacture, installation, and maintenance of reliable, maintainable, and durable solar energy systems.
- Assist in the development of appropriate standards, code provisions, and certification programs relating to the R&M performance of solar energy systems, components, and materials.
- Develop the information required to support the other activities within the R&M program.

In addition to reliability and maintainability, the 1980 program plan [1] recognized that other factors such as thermal performance, cost and site constraints were also important components of "system effectiveness" (Fig. 1). In order to maximize system effectiveness, the designer or manufacturer must often consider tradeoffs between these various factors.

1.2 Scope

In 1983, the DOE Active Solar R&M program was renamed the "Systems Effectiveness Research" (SER) program. The objective of the program was to identify, assess and initiate research into those factors which influence the effectiveness of solar space conditioning systems. As part of the FY 1983 SER program coordinated by the Solar Energy Research Institute (SERI), the National Bureau of Standards (NBS) was assigned responsibility for developing research priorities for improving the effectiveness of active solar hot water and space conditioning systems. To carry out this responsibility, NBS in cooperation with various industry representatives, organized and conducted two meetings in August 1983. With support from TPI, Inc., the first meeting was held at NBS on August 2-3, 1983 and covered all major aspects of state-of-the-art active solar hot water and space conditioning dealt only with solar

^{*} Numbers in bracket refer to references listed in Section 5.



- System Efficiency
- Subsystem Efficiency
- Component Efficiency

- Design Cost
- Equipment Cost
- Construction Cost
- Operating Cost
- Maintenance Cost

- System Availability
- Durability
- Maintenance

- Climate
- Load Characteristics
- System/Load Integration

Figure 1: Components of System Effectiveness

control subsystems and was held at NBS on August 9-10, 1983. Support for this meeting was provided by the Solar Environmental Engineering Company, Inc.. Recommendations obtained in these meetings are presented and discussed in Section 2. Recommended research priorities for addressing the effectiveness of advanced active solar systems (not dealt with at August 1983 meetings) are presented in Section 3. A summary of recommended research priorities for improving the effectiveness of state-of-the-art and advanced active solar systems is provided in Section 4.

1.3 Meeting Participants

Solar industry representatives (manufacturers, contractors, architects, engineers) who participated in the ranking of recommended research areas at the August 2-3, 1983 were:

- o Donald Bowden Solar Unlimited, Inc. Huntsville, Alabama
- Edward Butler
 Sunrise Solar Services., Inc.
 Suffield, Connecticut
- o Brad Davis Marc Energy Corporation Cinnaminson, New Jersey
- o Webb Farber U.S. Solar Corporation Hampton, Florida
- o Joseph Frissora Sunmaster Corporation Corning, New York
- o Susumu Karaki Colorado State University Ft. Collins, Colorado

- o Andrew Parker Mueller Associates, Inc. Baltimore, Maryland
- o Richard Rittleman Burt Hill Kosar Rittleman Associates Butler, Pennsylvania
- o Robert Spears Reynolds Metals Company Richmond, Virgin
- Burt Swerdling
 Grumman Energy Systems, Inc.
 Melville, New York
- o Raymond Yaeger Synergic Resources Corporation Bala Cynwyd, Pennsylvania

Government and government contractor staff participating in this meeting included:

- o John Avery Los Almos National Laboratory Los Almos, New Mexico
- Robert Dikkers
 National Bureau of Standards
 Gaithersburg, Maryland
- o Ed Gray JRB Associates McLean, Virginia

- Chuck Kutscher
 Solar Energy Research Inst.
 Golden, Colorado
- o Terry Logee Vitro Laboratories Silver Spring, Maryland
- o William Schertz Argonne National Laboratory Argonne, Illinois

- o Robert Hassett Department of Energy Washington, DC
- o Oscar Hillig ETEC/Rockwell International Canoga Park, California
- o William Kennish TPI, Inc. Beltsville, Maryland

- o Morris Skalka Department of Engery Washington, DC
- o Dave Waksman National Bureau of Standards Gaithersburg, Maryland

The following persons (controls manufacturers, government staff, etc.) took part in the August 9-10, 1983 meeting:

- o Bob Aasen Honeywell/TSC Roseville, Minnesota
- o Rick Boers Dynatech Energy Controls Lakewood, Colorado
- o Cliff Carwile Department of Energy Washington, DC
- o Gibb Conover Independent Energy Inc. East Greenwich, Rhode Island
- o Robert Dikkers National Bureau of Standards Gaithersburg, Maryland
- o Hunter Fanney National Bureau of Standards Gaithersburg, Maryland
- o Robert Hassett Department of Energy Washington, DC
- o Peter Herczfeld Drexel University Philadelphia, Pennsylvania
- o Bill Huston Solar Environmental Engr. Co. Fort Collins, Colorado
- o Peter Jacobs Novan Energy, Inc. Boulder, Colorado

- o Joseph Mibelli Rho Sigma, Div. of Watsco Hialeah, Florida
- o Dennis Miller Johnson Controls Milwaukee, Wisconsin
- o Daryl Myers Solar Energy Research Inst. Golden, Colorado
- o David Parks Heliotrope General Spring Valley, California
- o Paul J. Pekrul Rockwell International/ETEC Canoga Park, California
- o Kent Reed National Bureau of Standards Gaithersburg, Maryland
- o Shari Rossi Vitro Laboratories Silver Spring, Maryland
- o Morris Skalka Department of Energy Washington, DC
- o C. Byron Winn Solar Environmental Eng. Co. Fort Collins, Colorado

1.4 Meeting Organization and Methodologies

Approximately one month prior to the August 2-3, 1983 meeting, various background information was sent to the invited meeting participants. This information package included a discussion of system effectiveness, a listing of proposed research areas, and a proposed methodology for prioritizing research areas. Detailed information on the proposed prioritization methodology and the methodology which was used at the August 2-3, 1983 meeting is discussed in Appendix A.

Similarly, prior to the August 9-10, 1983 meeting, a background paper on solar heating and cooling control subsystems was prepared and distributed to the invited participants. This paper (Appendix B) contained a review of control theory, a literature review and recommended research areas. The prioritization methodology used at the earlier meeting was not employed at the August 9-10, 1983 meeting. Instead, recommended solar control research activities were developed on the basis of individual presentations and working group discussions.

2. RESEARCH RECOMMENDATIONS FOR STATE-OF-THE-ART ACTIVE SOLAR ENERGY SYSTEMS

2.1 Introduction

The purpose of this section is to present recommended research priorities for improving the effectiveness of state-of-the-art active solar energy systems which were developed at the two meetings held in August 1983. Section 2.2 presents the recommendations from the general meeting held on August 2-3 and Section 2.3 discusses the recommendations from meeting held on August 9-10 which focused on solar control subsystems.

2.2 General Meeting Recommendations (August 2-3, 1983)

Eighteen proposed research areas which were considered and ranked are listed in Table 1. The prioritized list of research areas as developed by the industry participants is shown in Table 2. Out of the eighteen research areas evaluated, the top three ranked areas were: (1) installer training; (2) designer training; and (3) packaging and installation methods. As shown, industry participants believed these important areas contribute to systems effectiveness and should be addressed by the solar community. Energy distribution was the only other area which federal government support was deemed to be inappropriate or not needed. A brief summary of the key points relating to each research area is presented in the following paragraphs.

Installer Training. The training of competent installers has been a major problem in the past. Poor or incorrect installation of various subsystems, such as controls, has accounted for a significant loss in performance and system failure. Improvement in this area has considerable potential for enhancing field performance and a relatively high probability of success. The cost is relatively small and the time for its effect to be felt upon the industry should be quick. Although this area ranks as the top priority, most major manufacturers train their own distributors and do not feel that this is an area where DOE could contribute significantly. Table 1. List of Proposed Research Areas (Not prioritized)

1.	Absorber Development - Selective Surface Materials	-	Plate Design
2.	Glazing Development - Thin Film - Degradation of Polymers - Reduction of Thermal Losses	1 1	Durability Under Impact Anti-Reflective Coatings
3.	Controls - Control Strategy Development - Reliability - Calibration Techniques - Sensors		Variable Speed Pumps & Fans Standardized Strategies Small Programmable Controllers Monitors
4.	Storage - Liners - Stratification Methods - Phase Change	1 1 1	Tank Durability Annual Cycle System Losses
5.	Machines - Absorption Chiller Development - Desiccant System Development	1	Rankine Development Heat Pumps
б.	Energy Distribution - Heat Exchangers - Piping - Leakage - Parasitics - Pumps/Fans - Low Cost Piping - Flexible Coupling, Sealants, Expansion	1 1 1	Flow Balancing Ducts - Leakage Low Cost Ducting High Quality/Low Cost Air Flow Controllers
7.	Heat Transfer Fluids - Freeze Protection - Air Vapor Blockage	-	Corrosion Refrigerants
8.	Systems Performance - Hot Water - Cooling - Side by Side Comparisons		Heating Field Data Acquisition Load Profile
9.	Modeling and Simulation - Components	-	Systems
10.	Design Tools		
11.	Test and Evaluation Procedures - Materials - Systems	-	Components

Table 1. List of Proposed Research Areas (CONTINUED) (Not prioritized)

- 12. Designer Training Programs
- 13. Packaging and Installation Methods
- Installer Training Programs 14.
- 15. Consumer Awareness Programs
- 16. Insulation
 - Collector - Piping
 - Storage

- 17. Technology Transfer
- 18. Mirror Reflectivity/Durability

Table 2. Industry Ranking of Systems Effectiveness Research A

	Research Area	Overall Weighted <u>Score*</u>	Federal Government Support Appropriate
1.	Installer Training	161.1	No
2.	Designer Training	157.1	No
3.	Packaging and Installation Methods	155.0	No
4.	Controls	154.3	Yes
5.	Insulation	150.1	Yes
б.	Design Tools	150.0	Yes
7.	Systems Performance	148.4	Yes
8.	Technology Transfer	145.2	Yes
9.	Energy Distribution	143.8	No
10.	Absorber Development	140.9	Yes
11.	Storage	140.2	Yes
12.	Modeling and Simulation	137.3	Yes
13.	Test and Evaluation Procedures	135.5	Yes
14.	Consumer Awareness	132.2	Yes
15.	Heat Transfer Fluids	128.9	Yes
16.	Mirror Reflectivity and Durability	126.8	Yes
17.	Glazing Development	114.9	Yes
18.	Machines	94.0	Yes

* See Appendix A for the methodology used in developing these weighted scores.

Designer Training. Another major contributor to poor performance of installed systems has been the lack of experience or training of the designers of the system. Often the projects were first efforts for the designer and therefore mistakes were made. Although this applies primarily to larger systems where a designer is more heavily involved, it has also been experienced in smaller residential systems.

Industry has overcome much of the problem in residential applications by going more toward packaged systems. Even space heating systems are becoming more packaged. Commercial systems will continue to be a problem as long as the number of jobs is few. Design courses are available throughout the country but are not attended because of the lack of market pressure. There is not any significant role for DOE to play in the training of designers although the development of design tools and other technical resource material for designers is appropriate as discussed later. The solar community can assist when the need forces designers to solicit help.

Packaging and Installation Methods. Installation has been problem in active solar applications since the industry first began to develop. The need to piece together complicated systems and the lack of trained installers has resulted in many poorly functioning or non-functioning systems in the field. In response to this problem, manufacturers have gone to packaged designs and simple installation methods. This has been most successful on small systems (domestic hot water and small space heating) where close control over the product distribution network is exercised by the manufacturer. This is an area which must be addressed by any solar company that expects to be successful but does not require support from DOE.

<u>Controls</u>. The control subsystem of a solar system include those active and passive elements which govern the operation of the system. Sensors, controllers, actuators, dampers, vents, drain valves, etc. are all components of the controls subsystem. Virtually all of these components have experienced problems in the past.

Sensors have had one major problem which is yet to be resolved--sensor drift. The output of a sensor is not necessarily stable over time. Therefore, measurements, and especially differential temperature measurements, become inaccurate and result in improper system operation. The lack of a reliable and accurate low flow, non restricting flow meter has been a problem primarily for measuring system performance but this does not currently play a significant role in most control systems. This may change as more sophisticated variable flow control strategies are developed in the future.

The controller itself has had failure problems due to manufacturing and environment problems but these problems seem to be disappearing as experience is gained. Better units are now available with much better reliability. Back dampers, vents and other control devices have caused problems but these are also being solved through the natural evolution of the industry.

DOE could provide support in two major areas. First, recommended test methods and evaluation procedures which would aid industry in developing reliable controllers and sensors should be prepared. In this regard, other agencies should be surveyed for related research. Second, DOE should investigate the use of advanced control strategies to determine if substantial gains in <u>overall</u> HVAC and solar system performance could be realized. This will include the use of variable collector flow to preserve storage stratification, use of offpeak rates, and in general overall system optimization. This work will probably not be pursued by industry. (Note: Additional detailed research recommendations on solar control subsystems are also presented in Section 2.3.)

Insulation. The long term integrity of insulating materials used in solar systems, especially those exposed to higher temperatures, needs to be determined and probably improved. However, this offers little potential for cost reduction or performance improvement. If the demand is sufficient, industry will carry out this role. Other technology activities should be monitored by DOE to identify insulation advances. In addition, compilation and dissemination of available information on recommended insulation materials and installation practices for various applications (collectors, piping, thermal storage) would be helpful to the solar industry.

Design Tools. Many of the installed systems in the field today are poorly designed. Poor collector area/storage volume ratios, pump sizes, HVAC interface requirements, etc. have all led to inefficient operation. Because of the trend toward packaged systems, much of the need for this type of information has been alleviated. However, for field assembled systems there still remains a need for better design guidelines.

With respect to sizing and performance analysis many companies develop and disseminate design tools. DOE's most appropriate role should be the validation of these design tools, which has not been completely accomplished to date.

Systems Performance. Although system performance testing of advanced concepts is extremely important, the monitoring of field systems seems to be relatively non-productive. Not only are the monitoring programs extremely expensive but the results have been of little use by practitioners in improving cost or performance. Even when system performance data is reported, the uncertainty and format of the data render it virtually useless. In future field monitoring programs, more emphasis should be placed on the performance of components and subsystems so that manufacturers can determine those areas which work well. The possibility of a manufacturer replicating a system configuration exactly as well as the environmental conditions under which it operated are almost nonexistant and therefore the overall system data are not as important as component or subsystem data.

System and component testing should support the design tool development and validation efforts, test and evaluation procedure development activity, and modeling and simulation work. System testing should not, however, generate performance data only for the sake of creating the data but should be more strongly driven by the other research activities. DOE should support this work, as needed since industry is not typically in a position to do so.

Technology Transfer. As noted in other areas previously discussed, adequate information may exist but is not being successfully disseminated

to potential users. This, in general, is the case in active solar energy applications. Tremendous quantities of information are generated annually but fail to reach the designers, manufacturers, owners and installers in a meaningful format. Because of the current fragmented industry, this function will not be performed outside of DOE. A concentrated effort in gathering available technical information and disseminating it to the industry is needed.

Energy Distribution. A problem which has degraded the potential performance of active systems in the past has been the lack of adequate integration with the conventional system. This includes the auxiliary back-up subsystem as well as the distribution subsystem. Much of the problem is due to poor design which should get better as more experience is gained. Although problems do exist, DOE funded research is not justified. Anticipated improvements will come from training, experience and technology transfer.

Absorber Development. The performance of state-of-the-art absorbers and selective surfaces is high and could be improved little. The cost and durability of the absorber materials, however, must be improved but industry will do this on their own. Turbulence enhancers and non-linear α/ϵ coating materials to avoid high stagnation temperatures are areas of possible research but realistically offer little potential benefit.

<u>Storage</u>. Three fundamental problems appear to exist with storage: durable liners for liquid tanks, heat loss from storage (air and liquid) and improved stratification in liquid systems. Information on which liners perform well needs to be disseminated based upon field performance. Better techniques for insulating storage containers need to be developed. Often the problem of excessive heat loss is the result of poor installation practices. The improvement of stratification in tanks may require further research although maximum use should first be made of available information.

<u>Modeling and Simulation</u>. Few of the systems currently installed require the use of detailed modeling and simulation. Most of the research involving parameter and configuration studies for conventional solar systems has been done and one can expect to gain little through additional modeling. The exceptions to this are simulations which may be required to develop improved design tools and to evaluate the performance of tested systems for rating purposes. Work is done in this area will not be performed by industry but might be performed by academicians without significant support from DOE.

Test and Evaluation Procedures. With DOE support, considerable progress has been made in the development of standard test methods and evaluation procedures for various materials, components and solar hot water systems. Several of these test methods are being used in industry rating and certification programs. However, there is a need for converting the results of the standard tests to long-term thermal performance estimates and ratings. Because of the unique characteristics of different systems, rating methods have been developed which are inappropriate for all systems, such as those which use noon instantaneous efficiencies or clear day data only. Research is required to define improved rating procedures as well as methods for converting test results into thermal performance estimates. Industry has not successfully accomplished this and may build in system biases if left to their own. DOE should play an active role here in cooperation with the various rating and certification groups.

<u>Consumer Awareness</u>. Although consumer awareness is a major factor in the ultimate market success of solar products, it has little to do with system effectiveness research. DOE should, however, recognize the adverse effect that published poor performance results have had in the past. These results are extrapolated by consumers to all solar systems thus making it difficult for quality systems to penetrate the market. This is another reason why the test programs should be carefully designed. Information on systems performance should point out the successes as well as the problems.

<u>Heat Transfer Fluids</u>. The development of new fluids with all the desirable characteristics required by indirect solar systems (i.e., nontoxic, non-boiling or freezing, non-corrosive, etc.) would be helpful to some manufacturers but does not represent significant potential for cost or performance improvements.

Mirror Reflectivity and Durability. Due to the unique potential advantages of systems using evacuated tube collectors with reflectors, research on mirror materials, emphasizing reflectivity, durability and cost, should be pursued. Because of the small size of the industry segment manufacturing evacuated tube collectors, this type of basic materials research will probably not be adequately performed without DOE support.

<u>Glazing Development</u>. Performance improvements due to glazing development are doubtful for state-of-the-art flat plate collectors. The development of low cost, thin film collectors was not considered here because it was assumed to be a part of an advanced system development program. The use of polymers rather than glass offers some potential for improvements in cost, weight and safety but durability remains a major problem. The small potential gains do not warrant an expensive polymer development program.

<u>Machines</u>. The development of more cost effective and better performing machines relates primarily to solar cooling. Because of the extremely high cost and poor performance of these components, considerable potential exists for improving the situation. However, it is doubtful that changes to current cooling system machines will ever successfully reduce cost sufficiently. A Second Law analysis has also indicated that bench test performance of the single effect machines are as high as can be expected, thus only field performance can be improved.

2.3 Control Subsystem Meeting Recommendations (August 9-10, 1983)

2.3.1 Problem Areas

Control subsystem problem areas that inhibit the effectiveness of active solar energy systems are listed and prioritized in Table 3. An indication is also given as to whether the problem area should be addressed by DOE or manufacturers. DOE-sponsored controls research would help to:

- 1. ensure that satisfactory products and methods are developed; and
- 2. quantify the benefits of controller products (hardware and logic) so that industry can make appropriate decisions regarding the design and manufacture of controllers.

Table 3. Problem Areas for Active Solar Control Subsystems

Priority	Suggest	ed Activity for	Problem Area or Solution Needed
FLICTICY	DVD	TAILACCALCE	DVANDAVIS LIGYTEM
1	#		Control strategies to provide optimum performance of system types (including sensitivity analysis).
2	#		More complete models and their validation.
3	#		Algorithms and implementations to result in correct set point or mode selection.
4	#		System fault detection and indication concepts.
5	#		Recommended practices for testing and installation.
6		쁖	Sensors fail catastrophically.
7	#		Sensors are incorrectly placed.
8		#	Sensor calibrations drift.
9		#	System integrators/installers do not understand the operating benefits of potential control functions. Need education.
10		#	Installation practices are poor.
11		#	Oustomer Service.
12		#	Strategies to meet consumer and utility needs have not been identified. Potential problem.
13		#	Control system usability by consumer-man/machine interface.
		#	Incorrect strategies.
		#	Controllers fail or cause failures.
		#	Controllers and related component hardware are not designed for the application - fail to follow good design practice.
	#		Lack of standard specifications.

2.3.2 Objectives

Recommended objectives for a DOE-sponsored controls research program are as follows:

- 1. Develop control strategies and more accurate models for improved system performance.
- 2. Develop standard test methods and evaluation procedures for:
 - a. Controller hardware
 - b. Controller interfaces
- 3. Perform sensitivity studies to determine the effects of sensor drift, sensor placement, etc.
- 4. Develop system fault detection and indication (hardware and software).
- 5. Improve the reliability of sensors.
- 6. Improve the understanding of system integrators and installers.
- 7. Develop standard specifications for sensors and controllers.

2.3.3 Status of Current Research

A background paper on control research has been prepared and is included as Appendix B of this report. It includes a review of control theory, a comprehensive literature review, and recommendations for further research. The interested reader may wish to refer to Appendix B for further details. However, a concise review of current research activities pertinent to the above-mentioned objectives is contained in this section. These activities address key areas, and are the basis for recommended future research activities.

A. CONTROL STRATEGIES FOR IMPROVED PERFORMANCE

Recent simulation work conducted at the University of Wisconsin, Madison, Wisconsin, has indicated that significant improvements in solar domestic hot water (SDHW) system performance may be realized by decreasing the collector flow rate in order to achieve a greater degree of thermal stratification. The increase in collector efficiency due to lower collector inlet temperatures more than offsets the decrease in the collector heat removal factor due to the lower flow rates. Flow rates less than one-fifth the normally recommended flow rates are being considered. The lower flow rates may also result in lower parasitic losses.

The results of the simulation studies have been verified to a certain extent by experiments performed at the SDHW test facility at NBS. During tests of six independent SDHW systems, it was found that the highest fractional energy savings were realized by a single-tank thermosypon direct system and that the high perforamnce was due to low collector flow rates that, in turn, resulted in thermal stratification of the storage medium. This is very important work in that it indicates that the system designers, manufacturers, and installers may not be using the best flow rates and, in fact, are perhaps off by a factor of two or greater. When parasitic losses are considered, the flow rates being used at present may be too high. Although the results obtained so far are significant, the work is not complete. The optimal flow rates should be determined for a wide variety of system types, both for space heating and SDHW systems and in various locations. In particular, indirect systems should be analyzed, and parasitic losses should be considered in all analyses. The effects of the hot water load profile on the optimal flow rate should also be examined, along with devices that promote stratification. It is important that this area be investigated in more detail since the recommended flow rates are so far different from those presently being used in typical installations.

As mentioned in the Appendix B, adaptive control has important applications in solar heating when the building parameters are not accurately known. Adaptive controllers utilizing real-time estimation techniques, although not as common as the digital and analog controllers, have been developed and evaluated in a commercial scale building. Further analysis and modeling is needed to determine the cost effectiveness of the increased performance of these controllers.

B. TEST METHODS FOR CONTROLLERS

Recent tests performed at the Solar Energy Research Institute (SERI) have revealed various problems with controller hardware. Sensors failed to meet published specifications after going through characterization and stagnation tests. At low temperatures, the responses of the thermistors varied by as much as 4 degrees F. The self-heating of the thermistors caused changes on the order of 2 degrees F. The quality of construction of the thermistors caused certain types of thermistors to be seriously affected by the stagnation tests.

Functional tests of the controllers showed deviations from the published manufacturers' specifications. The differential temperatures for the starting and stopping of the pump varied with the temperature of the sensors. When the sum of the deviations from specifications for the sensors and controller is considered, it is possible for the value of the collected energy to be negative.

These tests are important to the controller manufacturers. However, the tests should be expanded to include more controller types and additional environmental conditions. A review committee, comprised of manufacturers and DOE/SERI/NBS personnel, should be formed to provide advice regarding the tests to be performed.

In addition, sensitivity studies should be conducted in order to ascertain the effects of sensor drift, sensor placement, and controller set points on system performance for the types of systems presently being used. *In the SERI tests, a failure was considered to have occurred if the sensor drifted out of its specified accuracy. This may not have led to any degradation in

 ^{*} One recently published study is "An Analysis of the Effects of Active Solar Energy System Control Sensor Degradation on System Performance," R. B. Farrington, W. Short, SERI/TR-253-2185, July 1984.

system performance. For example, the two degree drift of sensors due to the self-heating may not have an impact on the performance of the controller if both the collector and the storage sensor have the same drift rates (the absolute temperature measurement would be in error, but the relative measurement between sensors would be within specifications).

Controller manufacturers vary in recommended sensor location. Location of sensors and controller set points must be considered as a set. Collector sensors are normally placed on the absorber plate or in the fluid return immediately adjacent to the collector. Storage sensors are normally placed near the bottom of the storage tank (either inside or out) or next to the storage tank in the return fluid line to the collector. The sensor response time for the various sensor locations, combined with the optimum controller set points, needs to be reviewed to ensure proper performance under real world environmental and material conditions.

C. FAULT DETECTION

Several manufacturers presently include monitoring and display systems with their controllers. This is a marked improvement from the initial bang-bang controllers which usually had a small LED to tell when the system was collecting energy. The present day monitoring controllers still rely on the thermistor to provide the technician with temperature readings for system analysis. None of the existing controllers have the capability to determine if the sensors have drifted since installation, a possible problem identified by SERI.

There are controllers that can record maximum and minimum temperatures, number of times the pump was turned on, measure the approximate heat output of the solar system, and identify shorts or open thermistor circuits, lowflow or no flow conditions, reverse thermosyphon flow and low supply voltage. These controllers are a step in the right direction toward builtin-test-equipment and fault-detection systems. However, these systems rely on proper sensor installation and accurate sensor performance. Faultdetection systems need to be independent of the controller sensor and be capable of verifying the performance of the controller.

D. MODELING

The prime method for evaluating various control strategies and determining the accepted practices for controllers is the modeling of the system based on real world examples. First, the component and the system models are developed; the driving functions, control objectives and the control execution are determined; and sensitivity of the model established by computer simulation.

The model then needs to be verified and validated by testing at facilities such as SERI, NBS or other qualified laboratories. Environmental limits of operation could be determined that would assist in developing specifications for the controllers and their sensors. Simulations could be run that would assist in determining the validity of fault detection concepts. Controller set points could be provided for the various sensor locations.

2.3.4 Recommended Research Activities

Recommended research activities that are required in order to solve control subsystem problems (Table 3) and address the objectives stated earlier are listed below.

Task 1. Control Strategies

- 1.1 Determine the optimal mass flow rates for solar space heating and DHW systems.
- 1.2 Investigate the controller function based on stagnation temperature (see Appendix B, p. 55).
- 1.3 Determine the effects of cycling on system performance (see Appendix B, p. 56).
- 1.4 Determine partial excitation characteristics of pumps and blowers in relation to proportional controllers (see Appendix B, p. 56).
- 1.5 Examine the performance of multi-rate circulators (see Appendix B, p. 57).
- 1.6 Examine proportional, proportional-integral-differential (PID), and adaptive controllers for the distribution of energy (see Appendix B, p. 59).

Task 2. Test Methods

- 2.1 Develop standard test methods and evaluation procedures for controller hardware.
- 2.2 Develop standard test methods and evaluation procedures for controller interfaces.

Task 3. Sensitivity Studies

- 3.1 Determine system performance sensitivities to sensor drift.
- 3.2 Determine system performance sensitivities to sensor placement.
- 3.3 Determine system performance sensitivities to set point.

Task 4. Fault Detection Methods

- 4.1 Develop fault detection methods for anti-freeze systems.
- 4.2 Develop fault detection methods for water systems.
- 4.3 Develop fault detection methods for sensors.
- 3. RESEARCH RECOMMENDATIONS FOR ADVANCED ACTIVE SOLAR ENERGY SYSTEMS

In a recent DOE Active Program Research Requirements (APRR) Study [2] a number of advanced heating and cooling systems were identified as promising concepts for the year 2000. These systems are listed in Table 4.

Table 4. Primary APRR Advanced Systems

- 1. Residential Direct Heating and Hot Water, Liquid
- 2. Residential Direct Heating and Hot Water, Air
- 3. Residential Open Cycle Solid Desiccant Cooling, Heating, DHW
- 4. Commercial Solid Desiccant/Vapor Compression Hybrid Cooling and Heating
- 5. Commercial Absorption Cooling
- 6. Commercial Rankine Power Generation and Cooling
- 7. Ground Coupled Solar Assisted Heat Pump Community Heating (96 Apts.)

While the APRR study identified costs and performance of these systems, reliability issues were not addressed. Accordingly, it is the purpose of this section to identify research requirements for addressing potential reliability problems with these advanced systems.

In many cases, these advanced systems will face the same reliability problems as conventional systems. Since these problems are addressed elsewhere, this section will focus only on new reliability issues unique to the advanced systems. Each system will be discussed separately with both system and component reliability issues addressed in each case. It should be understood that since these advanced systems have not yet been built, the identification of reliability issues involves a considerable amount of hypothesis and speculation. Wherever possible, this speculation will be an extrapolation of what we know about the reliability problems of existing systems [3].

3.1 Residential Direct Heating and Hot Water-Liquid

This system consists of a closed collector piping loop with drainback to the storage tank whenever the pump shuts off for freeze protection. A significant feature of this system is the use of plastic pipe, chlorinated poly (vinyl chloride) (CPVC) or polybutylene (PB), in place of more expensive copper pipe. These plastics are typically limited to 200 F and cannot be attached directly to a stagnating absorber plate. Usually acetal or brass fittings are used to connect lengths of PB pipe while CPVC pipes are typically joined by adhesives. The reliability of these joints is an important research area.

Several different collector concepts have been proposed to lower costs. Thin film collectors must be capable of withstanding stagnation temperatures (as must any of the collector concepts) and must be able to withstand the local steam pressure produced when the collector is filled. For drainback systems not employing a trickle flow, the collector must be able to withstand the system vapor pressure and the elevation head present at the base of an array of collectors connected in series. Since a major thrust is to use materials less expensive than copper, the corrosion of these materials must be addressed. This is largely a system reliability concern since proper inhibitors must be employed in the collector loop. For collectors using plastic materials the long term effects of ultraviolet radiation and high temperatures must still be addressed as well as compatibility with corrosion inhibitors. Thermal stability of adhesives and selective surfaces are also critical.

Several of the advanced concepts call for the use of a heat pipe heat exchanger on the load (DHW) side to reduce pumping power. Since this is a new concept, the reliability of this component needs to be addressed.

Several of the liquid systems are to employ low cost storage tanks. A drainback system need not employ a tank that can withstand 125 psig. A lower pressure tank would need only to withstand about 15 psig in a closed drainback configuration for a residential application and could potentially be less expensive than a 125 psig tank. Whether such a tank would be as reliable as conventional pressurized DHW tanks needs to be determined. Plastic tanks would have problems similar to those of plastic piping.

3.2 Residential Direct Heating and Hot Water - Air

This advanced system would be a typical air heating system but would employ a less expensive air collector, such as a fibre mat absorber with plastic glazing. Although the biggest question about this type of collector is performance, reliability issues associated with the details of assembly need to be addressed.

As in the advanced liquid systems, a new heat pipe load side heat exchanger warrants investigation. Other than the heat exchanger and collectors, this air system is essentially conventional and one can expect the typical reliability problems associated with air systems, e.g. leaks.

3.3 Residential Open Cycle Solid Desiccant Cooling, Heating, DHW

This is an open cycle system of the Munters type which uses a desiccant wheel to dry air which can then be evaporatively cooled. Even the "conventional" version of this system is still experimental. The advanced system would employ a parallel passage dehumidifier wheel. Reliability issues include the maintaining of passage spacing with time and the long term durability of the parallel passage base material (e.g., Mylar) and the desiccant material when exposed to temperature and humidity cycles. Maintenance of the seal between supply and return air is also a critical factor. Although a rotary heat exchanger and evaporative cooler are conventional components, their maintenance in a residential systems environment needs to be addressed.

Because this is a multi-component air system, leakage can be expected to emerge as a major reliability concern. Also the control system in any combined heating/cooling system is relatively complex and can be a source of problems.

3.4 Commercial Solid Desiccant/Vapor Compression

This system combines the dehumidification of a desiccant system and the sensible cooling of a vapor compression subsystem. Potential reliability

problems for the desiccant subsystem are similar to the previous system. The addition of two more components to the air stream increases leakage sites, and the control system is somewhat more complex. Research is needed to develop low cost leak-free dampers and simplified controls. Since the vapor compression unit is modified and not simply off-the-shelf, its reliability would be in question.

3.5 Commercial Absorption Cooling

This system uses a solar-fired absorption chiller which contains an integral gas backup boiler. Because of the high firing temperature of the chiller, high performance collectors (e.g., of the evacuated tube/CPC type) are required. These are still in the development phase and durability of the tubes and reflectors are serious questions. The integral absorption chiller/gas boiler is new, especially when one considers that the chiller design is thermodynamically advanced (e.g., double effect). Further complication results from the need for a heat rejector in the collector loop.

As in any absorption cooling system, but particularly for this advanced design, controls can be expected to emerge as a major reliability concern. This system is extremely complex because of the effects of chilled water and cooling water temperatures, interaction of gas backup, and use of storage (hot side and/or cold side).

3.6 Commercial Rankine Power Generation and Cooling

This system uses solar heat to run a Rankine cycle engine which drives the compressor of a heat pump to supply cooling and also spins a motor/generator to produce electricity. Both the Rankine and vapor compression cycles would share the same evaporatively cooled condenser.

Like the absorption chiller system, the Rankine cycle system requires high collector delivery temperatures. The SERI low cost parabolic trough concept is considered the collector of choice. This collector is cabledriven on the rim, and its accuracy is affected by the durability of the cable. Like any trough the reliability of the tracking/drive system is critical and the reflector surface and substrate can degrade with time. If the system is designed such that boiling takes place in the collectors, the reliability of water quality control comes into question.

A major area of reliability concern is the Rankine cycle engine itself, particularly the seals. Development of a long lasting turbo-compressor will be needed for this type of system to work. As in the case of the absorption chiller, control complexity is high, particularly if variable speed pumps and fans are used.

3.7 Ground Coupled Solar Assisted Heat Pump Community Heating

This system uses a dual source heat pump (low cost collectors and the earth) for the heating of community buildings. An array of deep wells containing U-type heat exchangers is employed, and the ground is used as storage for seasonal carryover. Thin film plastic collectors open to the atmosphere are used with a lined sheet metal tank for storage, plastic piping, and drain-back protection. Reliability issues are similar to those of liquid direct heating systems with the additional complications of the heat pump and ground-coupling. Ground heat exchangers have traditionally faced problems associated with various soil conditions.

Degradation of the contact between the heat exchanger and the ground, and freezing of the ground can have a significant impact on heat transfer. Drying of the soil due either to thermal cycling or shielding of rainfall by surface insulation can reduce performance. Underground leaks are also a potential reliability issue. Since the heat exchange wells are covered by insulation and the collector array, access for maintenance can be a problem. As in the case of the liquid direct heating system, reliability of thin film plastic collectors is a serious issue.

4. SUMMARY

4.1 State-of-the-Art Systems

Based on recommendations presented in Section 2, the following research areas (listed in priority order) are recommended for DOE support in order to improve the effectiveness of state-of-the-art active solar hot water and space conditioning systems.

- 1. <u>Control Subsystems</u>. This includes investigation of control strategies, development of test methods and determination of system performance sensitivities and fault detection systems.
- 2. <u>Materials</u>. For various materials (e.g. insulation, piping, ducts, tank liners, heat transfer fluids, reflectors, glazing, absorptive coatings), research should be conducted to develop:
 - o <u>Durability data</u> under various in-use conditions;
 - o <u>Test and evaluation procedures</u> to aid in long-term performance predictions; and
 - <u>Material selection guidelines</u> to assist in choosing materials for various system applications.
- 3. <u>Systems Performance</u>. In regard to the collection and evaluation of field performance data, more emphasis should be placed on subsystems or component performance, cost, reliabililty and maintainability. Field and laboratory testing of systems should continue, as appropriate, to support modeling and simulation, design tools, and test and evaluation procedure development.
- 4. <u>Technology Transfer</u>. Available research data and information is not being successfully disseminated to potential users. Accordingly, more government effort is needed to gather available information and to transmit it to industry in a useful and timely manner.
- 5. <u>Design Tools</u>. The development and validation of better design tools and guidelines is another high priority area which should be emphasized in the DOE research program.

4.2 Advanced Systems

In regard to the advanced active solar energy systems presently being studied by DOE (Section 3), the following research areas (not listed in priority order) are recommended for DOE in order to address important systems effectiveness factors (thermal performance, cost, and durability/reliability).

- 1. <u>Materials</u>
 - o Plastic piping (including joints)
 - o Plastic glazing and absorber plates
 - o Dessicants (solid and liquid)

2. <u>Components</u>

- o Thin film collectors
- High temperature collectors (including reflectors and tracking devices)
- o Heat exchangers
- o Controls
- o Open-cycle regenerator/collectors
- o Absorption chillers/heat pumps
- o Dessicant chiller/dehumidifiers
- 5. REFERENCES
- "Program Plan for Reliability and Maintainability in Active Solar Heating and Cooling Systems," Mueller Associates, DOE/CS/36010-01, October 1980.
- "Active Program Research Requirements (APRR)," Final Report, Vol. 1, W. B. Scholten, J. H. Morehouse, Science Applications, Inc., DOE/SF/11573-T1 (Vol. 1), October 31, 1983.
- 3. "A Summary and Assessment of Historical Reliability and Maintainability Data for Solar Hot Water and Space Conditioning Systems," Gary J. Jorgenson, Solar Energy Research Institute, SERI/TR1-253-2120, May 1984.

APPENDIX A

DEVELOPMENT OF A PRIORITIZATION METHODOLOGY FOR THE SYSTEM EFFECTIVENESS RESEARCH PROGRAM AT THE U.S. DEPARTMENT OF ENERGY

1.0 INTRODUCTION

The System Effectiveness Research (SER) Program has emerged from an earlier DOE program which dealt with reliability and maintainability of solar systems. The new definition of SER, however, encompasses additional factors which impact on a system's ability to provide cost effective service. Figure 1 illustrates the many elements which combine to determine the system effectiveness. The two key elements are thermal performance and annualized cost. These two factors combine to determine the cost per million BTU's the system realizes.

The goal of the SER program is to conduct research which will improve this cost effectiveness figure for solar systems. Because of the large number of proposals for research which are encountered relative to a limited budget, it is necessary to prioritize the areas of research based on a rational set of criteria. This appendix describes a methodology for accomplishing this prioritization and discusses its preliminary use during the August 2-3, 1984 NBS meeting. It is suggested that the methodology be refined and used in future planning cycles.

1.1 Elements of the SER Program

Figure A-1 suggests that there are two key factors to system effectiveness; thermal performance and cost. Many elements comprise each of these areas. To facilitate the evaluation process the elements under thermal performance have been separated into two categories; those which represent improvements to a state-of-the-art properly operating system and those which represent improvements of field installed systems so they can operate closer to the expected performance.

Annualized costs can also be thought of as being comprised of two factors; those which reduce the cost of the system and those which extend the life of the system. A discussion of each of these areas is presented below in section 1.2.2.

1.2 Method for Prioritizing Research Areas

Research, by definition, involves the acquisition and interpretation of new knowledge. This suggests that the prioritization of research activities will inherently be fraught with uncertainty of success and benefit. However, this does not necessarily mean that the prioritization cannot be undertaken systematically with bounds applied to at least the potential benefit of each activity. The methodology developed for this study seeks to establish these bounds and provide initial evaluation of priorities. The methodology and conclusions can then be reviewed by other researchers and managers to obtain consistently formatted input.

The methodology consists of a number of phases. The first deals with the identification of factors which contributed to either a reduction of thermal performance from an ideal system or the incurrence of a cost. As shown in Figure A-1, these two areas are the elements which comprise the "system effectiveness".

The second phase involves the establishment of bounds for improvements in each of these areas. This provides an appreciation of the relative



Sources of Degradation

- Parameters
 - . Nonideal design parameters
 - . Installation effects on parameters
 - . Changes in material properties
- Nonoptimal Design
 - . Design tool error
 - . Wrong parameter values
 - . Site constraints
 - . Errors in weather data
 - . Control strategy
- Downtime
 - . Component Failure
 - . System Replacement
- Inefficient Operation
 - . Leaks
 - . Control system malfunction
 - . Load profile

Sources of Performance Improvement

- Collector
 - . Absorber
 - . Glazing
 - Back and edge coefficients
- Storage Losses
- Load Profile
- Control Strategy

Figure A-1. Factors in System Effectiveness

Sources of Incurred Costs

- Component Materials
 - . Collectors
 - . Controls
 - . Storage
 - . Plumbing (pipes, valves, etc.)
 - . Pumps
 - . Heat exchangers
 - . Fluids
 - Conversion Equipment (heat pumps, chillers)
 - . Support structure
 - . Ducting
- Overhead and Profit
- Installation
- System Design
- Maintenance (component life)
- Replacement (system life)
- Parasitics
 - . Pumps
 - . Fans
 - . Controls
 - . Other Equipment

potential for various activities. It is expected that these bounds will be a function of application and system type.

The third phase involved subjecting each area to screening factors which determine if work in this area falls into the general purview of the DOE Solar Heat Technology System Effectiveness Program.

The fourth phase is the evaluation of each area of research which passed the screening criteria with respect to a number of evaluation criteria. The results of this evaluation can then be used to rank the research activities.

1.2.1 Identification of Factors

Figure A-1 illustrates the typical factors which affect the thermal performance and annualized cost of an active solar system. The importance of each of these factors varies from system to system and application to application. It is recommended that the list shown in Figure 1 (page 2) be made system specific for future planning cycles by consulting industry and research personnel.

1.2.2 Establishment of Bounds

The lists in Figure A-1 provide an overview of the factors which affect cost and performance, but they do not indicate the potential gains which could be achieved by performing research in any one of the areas. An understanding of the limits of improvement for any one activity area allows the development of rational priorities amongst activity areas. For example, research on selective surfaces for flat plate absorbers might be a very interesting area to fund research but if the research is directed toward improving thermal performance then the limit to improvement over current systems might be determined to be quite low.

It was not possible to establish these bounds for thermal performance improvement for all system types in such a short period of time. However, what was determined was that for properly operating, state-of-the-art active solar systems of most types and applications, the system efficiency should be 35-45%. Field data of numerous sites indicates that installed systems are realizing an efficiency of 0 to 41% with most below 25%. (See Table A-1). This discrepancy indicates that substantial gains might be possible in improving performance toward the expected performance. The areas where performance degradation is taking place must be identified and serve as a basis for future research prioritization.

In a manner similar to the breakdown of performance degradation described above, the costs over the lifetime of a system should be broken out to identify what costs could be reduced and by how much. If distribution networks are imposing high overhead costs on solar systems, then a simple reduction in collector costs may not accomplish proportional reductions in system costs. Thus a thorough understanding of cost and pricing structures within the solar industry should be prepared to better prioritize projects aimed at cost reductions. Several studies (Booze Allen, DHR) have performed such a study but these need to be updated and performed for more system types to allow project prioritization.

Table A-1. Measured System Performance of NSDN Sites (% Efficiency)

Space Heating & DHW

	Liquid	Air	DHW	Space H&C/DHW
	25	13	41	7
	21	13	35	5
	18	13	34	4
	12	10	33	3
	12	8	32	3
	12	7	31	2
	11	5	28	2
	11	3	28	0
	10	3	27	0
	7		26	0
	6		25	0
	5		24	-1
	5		24	
	2		23	
			22	
			21	
			13	
			13	
			13	
		•	12	
			4	
AVERAGE	11	8	24	2

Projects aimed at extending the life of the system is an effective method for improving the cost effectiveness of the systems. Component reliabilities for field installed systems must be understood to base prioritizations in future plans.

The thermal performance and cost data described above will serve as guidelines in developing research priorities. However, there are a number of factors which require more subjective input. To accomplish this, screening and evaluation criteria have been developed. The evaluation criteria allow the integration of the quantitative performance and cost data described above with the subjective factors such as probability of success, etc. These criteria are described in the following sections.

1.2.3 Screening Criteria

A research activity undertaken by a program within the DOE should meet general suitability requirements imposed by the stated mission of the Department. The current administration has indicated that the DOE should be involved in long-term, high risk research which would not be accomplished by other organizations if not funded by the DOE. This broad policy statement can be put into two "Screening Criteria" which must be passed before an activity can be considered for funding. These screening criteria are:

- o High Risk/Long Term Payoff
- o Not Performed by Industry or Elsewhere

These criteria are self explanatory and reflect the current administration's policy.

1.2.4 Evaluation Criteria

Assuming that a number of research areas are identified which pass the Screening Criteria it then becomes necessary to evaluate the relative worth of each area to DOE in achieving its system effectiveness objectives. The following Evaluation Criteria are recommended in this methodology:

- Potential Contribution Toward Achieving Cost Reductions (5)
- Potential Contribution Toward Achieving Performance Improvements (4)
- o Probability of Success (3)
- o Cost to Program (2)
- o Time to Complete Research or Reach First Major Milestones (3)

These criteria reflect the importance of an activity area but they are not necessarily of <u>equal</u> importance. To account for this, weighting factors are used to indicate the relative importance of one criterion to another. The weighting factors used in this evaluation are shown above in parenthesis. To arrive at a total weighted score for a research area the criteria score's (0 - 10) are multiplied by the weighting factors, and then the products are summed.

2.0 USE OF METHODOLOGY (AUGUST 2-3, 1983)

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Major factors (thermal performance and cost) affecting the effectiveness the various types of active solar energy systems was the initial topic at the August 2-3, 1983 meeting. Although the pre-meeting information package contained a preliminary quantification of: (1) various sources which cause degradation or improvement in system performance and (2) system costs, the industry participants believed the current data base on system performance and costs was inadequate and could not be used at this time for establishing research priorities.

The second item discussed was a list of proposed research areas which would be considered for prioritization. The final list which was developed by the participants contained 18 research areas (Table 1). Proposed evaluation criteria and weighting factors for ranking the list of research areas was the next item considered. After discussion, the proposed evaluation criteria and weighting factors were revised. The revised values are shown in Table A-2 and were used by the industry participants to establish the prioritized list of research areas at the August 2-3, 1983 meeting (see Table 2).

> Table A-2. Evaluation Criteria and Weighting Factors Used At August 2-3, 1983 Meeting

	Evaluation Criteria	Factors
•	Potential contribution toward achieving cost goals	4
•	Potential contribution toward achieving performance goals	4
•	Probability of success	3
•	Cost of program	3
	Criticality to technology success	4
•	Time to complete research or reach first major milestone	2
	Durability and reliability	4

The following guidance was also given in determining criteria scores:

<u>Criteria Number</u>	Comment
1,2,7	0 = Strong negative importance 5 = Neutral 10 = Strong positive importance
3	<pre>10 = Strong positive importance 0 = Poor probability</pre>
4	0 = High cost to DOE 10 = Low cost to DOE
5	0 = Not critical 10 = Critical
6	0 = Long time 10 = Short time
APPENDIX B

Solar Heating and Cooling Control Subsystems

by

C. Byron Winn and Peter Armstrong

June 1983

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1. INTRODUCTION

This paper has three main sections: "Review of Control Theory," "Literature Review," and "Recommendations for Further Research." The objective of the "Theory" section is to provide readers with a common knowledge base of control concepts and nomenclature. Some readers may skip most of this section by quickly scanning it for underlined words and noting their usage. The objective of the "Literature Review" section is to show where research in solar heating and cooling controls now stands. While the list of cited references is fairly comprehensive the discussion is necessarily limited, being mainly an effort to enumerate the control topics that solar researchers have addressed and show how the work of different researchers is related.

The objective of the "Further Research" section is to stimulate thought and discussion. It is a frankly biased catalogue of promising areas of controls research that would benefit the solar industry and, in some cases, the electric utilities and other providers of back-up energy. Readers are invited to suggest additional research topics.

2. REVIEW OF CONTROL THEORY

The control of solar energy systems is quite similar to the control of any dynamical system that is subjected to disturbances. A great deal of work has been done in this area and it may be applied to controllers of solar energy systems. Before examining specific types of controllers used in solar energy systems we shall first review some basic control theories. Consider first an example of a classical control problem as illustrated in Figure 1.

The objective is to vary the energy input to the heater in order to control the enclosure temperature T_E . Usually the enclosure temperature is controlled in order to maintain some desired temperature, T_D . The deviation of T_E from T_D should be small regardless of the magnitude of disturbances, G (sunshine), T_A (outside temperature), and V_W (wind speed). There are several ways to do this.

The simplest form of control is "<u>open loop</u>" control. In this case the heater is energized on some schedule regardless of the current enclosure temperature. Obviously this type of control would not result in very high comfort levels.

An improved type of open loop control is possible by measuring G, T_A , and V_W . A predetermined function of these variables is then computed and the furnace is energized if the function exceeds some predetermined threshold. This type of closed loop control will perform well if the function and threshold are properly selected (not an easy task) and provided no disturbances (such as open windows) are introduced. Also the need to measure these variables is a burden.

The controller is simplified and the comfort level is improved by using "<u>closed loop</u>" control, as illustrated in Fig. 2.















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Bang-Bang Control

In this case the thermostat serves as the first element of the controller and compares the actual room temperature, as sensed by the thermostat, with the desired room temperature, as set in the thermostat.

The final control element, the furnace, has only two "states" - full on or off - depending on the state - closed or open - of a switch (relay) operated by the thermostat. When the temperature at the thermostat falls below the desired temperature, the switch is closed, causing the furnace to operate, and consequently increasing the room temperature T_E . When T_E exceeds T_D the switch is opened and the furnace is shut off.

This would also be an undesirable controller since it would lead to rapid "<u>cycling</u>" (on and off) of the furnace. That is, the controller would turn the furnace on whenever the enclosure temperature is sensed to be less than the desired temperature, no matter how small the difference. This could result in a rapid increase in T_E , depending on the furnace output and the ambient conditions, such that T_E exceeds T_D and the furnace is turned off. This type of controller is referred to as a bang-bang controller. It has only the two states, on or off. It is represented in Figure 3. The building temperature response that would result from use of this controller is illustrated in Figure 4.

The enclosure temperature is maintained at the desired value but at the cost of excessive cycling of the furnace. The cycling rate may be reduced by introducing a "deadband" into the controller. The effect of the deadband is that the controller will not turn the furnace on until the enclosure temperature drops below the "bottom of the deadband;" the controller will then keep the furnace on until T_E increases to beyond the "top of the deadband". This is illustrated in Figure 5. The control





Fig. 5. Time variation of temperature (bang-bang controller with deadband).





Fig. 6. Bang-bang control with deadband.



Fig. 8. Proportional controller (with saturation and offset).



Fig. 9. Block diagram of PID controller.

function (often referred to as the "control law") is illustrated in Figure 6, and may be expressed analytically as

$$u = \begin{cases} u_{MAX}, T_{E}^{-T}T_{D} \leq -DB/2 \\ 0, T_{E}^{-T}T_{D} \geq DB/2 \end{cases}$$
(1)

The bang-bang controller with deadband does not maintain as precise control of T_E as does the bang-bang controller without deadband, but it results in much less cycling. However, it also results in "overshoot;" that is, the enclosure temperature will exceed the top of the deadband and fall below the bottom of the deadband. Normally this is of little consequence in building heating systems. However, with the advent of buildings having large "thermal capacitances," the problem of overshoot becomes more significant. Cycling and "overshoot" are characteristics of bangbang controllers, regardless of the system being controlled.

Proportional Control

The overshoot may be eliminated by using "proportional control." In the case of proportional control, the output of the furnace is proportional to the difference between the enclosure temperature and the desired temperature. Thus, if the room temperature is very low, the furnace will work hard to overcome the temperature error. However, as T_E approaches T_D , the output of the furnace will decrease, thereby preventing overshoot from occurring to the extent it occurs with a bang-bang controller. The control law for the proportional controller may be written as

$$\mathbf{u} = \begin{cases} \mathbf{k}_{p} (\mathbf{T}_{E} - \mathbf{T}_{D}), \ \mathbf{T}_{E} \leq \mathbf{T}_{D} \\ \mathbf{0}, \ \mathbf{T}_{E} > \mathbf{T}_{D} \end{cases}$$
(2)

and is illustrated in Fig. 7. The slope of the line, k_p , is referred to as the controller gain.

The principal disadvantage of the proportional controller, as

illustrated, is that it would cause the furnace to operate continuously as long as T_E is less than T_D . This problem can be avoided by including an "offset," as illustrated in Fig. 8. In this case, the controller will not turn the furnace on until T_E is less than T_D by the amount OS. The control is proportional to the magnitude of the temperature error, $|T_E-T_D|$, for $T_E-T_D < -OS$. It then remains constant at the value U_{min} until T_E exceeds T_D . There will still be some overshoot with this controller.

Integral Control

An additional type of control that may be used is "<u>integral con-</u> <u>trol</u>." An integral controller is designed to increase the controller output (the furnace output in our example) in proportion to the time integral of the error. That is, the longer the enclosure temperature remains below the desired temperature, the more the furnace output will be increased. This is represented analytically as

$$\mathbf{a} = \mathbf{k}_{\mathrm{I}} \int_{\mathbf{t}_{\mathrm{O}}}^{\mathbf{t}} [T_{\mathrm{E}}(t) - T_{\mathrm{D}}(t)] dt$$
(3)

An integral controller does not result in a fast response, but does have a stabilizing effect on system response.

Derivative Control

If quicker responses are desired, then "<u>derivative control</u>" may be used. A derivative controller leads to a control output that is proportional to the rate of change of the error. That is

$$U = k_D \frac{d}{dt} (T_E - T_D).$$
(4)

Thus, the controller output increases as the time rate of change of the error increases. Derivative controllers lead to quick responses, but tend to be unstabilizing and are strongly affected by noisy signals.

PID Controllers

The above control types may be combined to result in a "proportional-integral-differential controller," known as a PID controller. The control law is expressed as

$$u = k_{p}(T_{E}-T_{D}) + k_{I} \int_{t_{O}}^{t} (T_{E}-T_{D}) dt + k_{D} \frac{d}{dt} (T_{E}-T_{D})$$
(5)

A PID controller can potentially reduce energy consumption in three ways. First, it reduces overshoot in heating the space (an improved method of thermostat "anticipation.") Second, if it is desired to implement a proportional actuator, the PID controller could increase the average steady state efficiency of a given size combustion heat exchanger by operating the burner at less than nominal rating most of the time. And third, the PID controller may increase transient efficiency by reducing on-off cycling and reduce flue losses by causing the heat exchanger to be at a temperature that is well below the nominal design temperature at the end of each "on" cycle.

Using the concept of a transfer function, which is defined as the ratio between the output and the input, both expressed in the frequency domain, the equation for the PID controller may be written as

$$\frac{U[s]}{E[s]} = k_{p} + \frac{k_{I}}{s} + k_{D}s$$
(6)

The "<u>transfer function</u>" is shown in block diagram form in Figure 9. Design of Controllers

There are two basic approaches to the design of controllers. The first is referred to as trial and error, while the second is referred to as the analytical design approach. These are briefly described below.

Trial-and-Error Design

The "trial and error method" is illustrated in Figure 10. The trial and error method is the method that is most often used in the design of control systems. This is further illustrated by Figure 11, which depicts a unity feedback control system. In this figure, the output from the system, c(t), represents the controlled output. The desired response is represented by the input to the block diagram and denoted as r(t). The controller is a proportional feedback controller and is represented by the gain, k_n , acting on the error signal, e(t). The desired response could be interpreted as the enclosure temperature in our example. In the classical trial and error design procedure, one would select a set of performance specifications and then attempt to adjust the controller gain so that the performance specifications would be satisfied. A typical set of performance specifications relative to a step input to a second order system is illustrated in Figure 12. For the building heating problem discussed previously, one would be primarily concerned with overshoot and final error. The trial and error design process tends to be inefficient and expensive and, when one selects a set of performance specifications, one has no way of knowing whether or not those performance specifications can be satisfied.

Some general guidelines, drawn from experience, can ameliorate these problems somewhat by suggesting a reasonable initial control strategy. Design Guidelines

Almost all the temperature control problems in solar applications are heat transfer problems, and are characterized by long time constants and slow reaction rates. Distance-velocity lag (also known as dead time) is common. The measurement lag can pose a serious problem. The measurement time constant depends on the mass and surface area of the sensor or probe



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Fig. 10. Trial and error design procedure.

 γ_{i}



Fig. 11. Block diagram of a "classical" proportional controller.



Fig. 12. Typical time domain performance specifications.

assembly, the fluid being measured, and its velocity past the probe.

Processes dominated by one large capacity, for example, storage tanks in air heating systems, can be controlled with on-off controllers.

Proportional-plus-reset control is used in smaller capacity systems where load changes are large and where distance-velocity and measurement lags are important. Most hydronic collectors and shell and tube heat exchangers fall into this category. Derivative control becomes helpful provided the distance-velocity lag is not the dominant secondary dynamic element, for example, as with an air heating collector.

Controlling temperature by mixing hot and cold streams is more nearly a blending problem than a heat exchange problem. Good mixing and fast temperature measurement are the keys to simplifying the control job. Proportional-plus-integral controllers should be used.

In general, the following guidelines can be used in selecting controllers. Use proportional control where

o the cycling action, due to on-off control, is undesirable;

- o set-point changes are small or infrequent; and
- o the steady-state deviation between the set point and the process variable, that is, the offset, can be tolerated.

Use integral control where

o the offset must be reduced or eliminated, and

o the set point changes are frequent.

Do not add integral control when

- o start-up overshoot must be eliminated, and
- o the process can be controlled with high-gain proportional control.

Add derivative action to proportional control when

o the distance-velocity lag (for example, dead time in the pipes) is smaller than either of at least two linear lags (for example, storage tanks) in the process loop. Do not use derivative control if

o the distance-velocity lag is significant;

o the process is noisy.

It is not at all uncommon for considerable amounts of money to be spent on computer simulations in attempting to select a set of gains for selected controllers in order to meet a set of performance specifications. It is often more efficient to use an analytical design process in which the guesswork is eliminated and where one can determine directly the control strategy that will result in optimizing system performance.

Analytical Design

In applying the "<u>analytical design</u>" process, one selects a cost function to be optimized. Hence, it is often referred to as "<u>optimal con-</u> trol."

A typical formulation of the optimal control problem is the "linear regulator" problem. This type of control is applicable to situations where the objective is to bring a control variable, such as $(T_E - T_D)$, to zero.

A linear regulator for this application could be designed to minimize the weighted sum of the root-mean-square deviation from the set point and the mean energy input:

$$T = \int_{0}^{t} f(A(U(t))^{2} + R(E(t))^{2}) dt$$
(7)

where the deviation from the set point, E(t), is related to the controlled energy input, U(t) (and to other factors, such as weather and occupant behavior, which are both treated as noise) by a set of differential equations that governs the dynamic behavior of the heated space and backup heating plant. The chief parameters of concern in these governing equa-

tions are the room parameters, the resistance to heat loss (R) and the thermal storage capacitance (C).

One of the issues raised by the integration of backup heaters with solar heated buildings is the interaction of controls. In particular, passive solar heated buildings present a number of problems. First, the "time constants" (T = RC) of rooms in such buildings are usually much longer than in conventional buildings because both R and C are much greater. The thermal capacitance effect alone has a major significance: any overshoot of the setpoint by the backup heater controller represents a relatively large quantity of energy absorbed by thermal capacitance elements. This overshoot will then persist (decay very slowly) because of the large time constant of the heated space. It is therefore apparent that significant energy savings can be realized by reducing overshoot and by reducing thermostat deadbands.

The quadratic criterion represented by equation (7) helps to reduce overshoot because increasing deviations, E(t), are penalized with progressively increasing severity. The solution to (7) will also yield a control law with small final error because the first term penalizes deviations of the set point deviation. Since these penalties are integrated over time the resulting control law will involve some integral feedback which will tend to reduce final error. Another useful feature of the optimal regulator is reduced peak demand. The quadratic penalty on U(t) tends to limit parasitic or auxiliary power.

3. CONTROLS LITERATURE REVIEW

Some of the major review papers on solar energy controls include: Kutscher et. al. (1982) and Su and Castle (1979) both emphasizing solar IPH control; Winn (1982) covering mainly residential systems, the determination of cycling rates for on/off controllers and control laws for proportionalonly control of collector circulation based on the Pontryagin maximum principle; Kent, et. al. (1980) on residential DHW controls; and Dorato (1979) on application of on/off singular linear quadratic and periodic optimal control theory to solar energy systems. Control and measurement references, germane to, but not dealing specifically with, solar energy applications include Tierstein (1978), Roots (1969), Johnson (1964) and Shinsky (1974).

Selection of offset and deadband parameters (i.e. $(\Delta T_{ON} \text{ and } \Delta T_{OFF})$ for differential, on/off control of collector blowers or pumps is discussed by Davis (1975), Schiller, et al. (1980), Duffie and Beckman (1980), Alcone (1981) and Winn (1982). On/off control strategies are compared to proportional control strategies using simulation by Herczfeld and Fischl (1977) and Lewis and Carr (1978) and Schiller et al. (1980) and in field tests hy Schlesinger (1978).

Some of the problems encountered with complex solar heating and cooling systems controlled by multi-function set point and differential on/off controllers are discussed by Guynes (1978) and Karaki and Armstrong (1978). The simulations of systems with such complex controls are discussed by Orbach et. al. (1978), by Armstrong and Bechtel (1979) and by Piessens et. al. (1981). Design of and operating experience with a hardware programmable (not microprocessor based) controller used to "breadboard" complex control logic based on set point and differential comparisons has been reported by Bechtel et. al. (1979).

One of the earliest papers on optimal utilization of solar energy in space heating and cooling applications was by Winn, Johnson and Moore (1974). A control-theoretic approach was used to examine the problem of minimizing the use of auxiliary energy required for space heating and cooling. It was shown that the auxiliary heat supplied to a solar heated house may be minimized by the use of a proportional plus integral state feedback controller. It was demonstrated that the controller that leads to minimizing the auxiliary fuel may be obtained from an application of optimal regulator theory. The possibility of implementing the optimal controller on a microprocessor was also discussed. The gains for the optimal feedback controller must be determined by solving a matrix Riccati equation, which proves to be a nontrivial problem. This situation was examined in more detail (Johnson and Winn, 1975) in order to develop efficient algorithms that may be used for efficient management of a building's energy budget and that may be implemented on a microprocessor. In a simplified analysis of the problem of controlling temperatures in buildings (Winn and Hull, 1978) a comparison between several different heuristic control strategies and an optimal control strategy was presented. The optimal control strategy that minimizes the integral over time of the sum of the building energy requirements and a measure of occupant discomfort was developed and it was shown that energy savings could be realized through implementation of the optimal control strategy. The analysis was extended (Winn and Hull, 1976) to include sensitivity studies and was further extended (Winn and Hull, 1977) to include analysis of the singular control problem.

An early study relating to the impact of solar systems on utilities (Soot, Goldbach, and Winn, 1975) examined the problem of solar domestic water heating in the northwestern part of the United States and the poten-

tial impact on Pacific Power and Light Company.

The above-mentioned control studies dealt primarily with the problem of controlling the solar heating or cooling system from the point of view of minimizing fossil fuel consumption and maintaining occupant comfort. The principal analytical tool that was used in these studies was that of simulation.

Winn (1982) compares the process of selecting controller parameters by trial and error (using simulation to evaluate performance) with penalty function techniques of analytical control synthesis. For example, Johnson (1964) describes a general technique for determining on/off control parameters using a quadratic penalty function. Somasundarum et. al. (1978) made some simplifications to Johnson's approach to obtaining an explicit solution for control of a large solar heating and cooling plant. One of the first attempts to apply the penalty function approach to solar heating systems was by Kovarik and Lesse (1976). Other application studies were by Johnson and Winn (1975), Auslander, et. al. (1979), Blodgett, et al. (1978a) and Winn and Hull (1978). One of the problems with the optimal control approach, pointed out by Auslander et. al. (1979) and Blodgett et. al. (1978b) is the effect of errors in plant parameter estimates on controller performance. The solution to this problem, adaptive control, is discussed later in this review.

Another problem that must be faced regardless of whether the control parameters are selected by trial and error or analytical optimization is simplification in the plant model. For example Schindwolf (1981) shows how to select collector loop flow control parameters based on a lumped capacitance collector model. Orbach et. al. (1981) however show that control parameters derived under the assumption of a lumped capacitance collector

may be considerably in error. Wright (1981) presents a detailed method for determining control parameters based on a distributed capacitance collector model. Lumped load models, on the other hand, have been found satisfactory, e.g. Winn and Hull (1978, 1979) and Rink (1981). However, for the control of auxiliary heat for rooms in <u>passive</u> solar heated buildings, distributed capacitance models may be needed (Winn, 1982).

Some controllers have been built to implement a PID optimal regulator control law. These controllers were installed and tested as reported by Eisenberg et. al. (1977) and by Winn and Hull (1977).

The utility load factor problem was addressed by Winn and Duong, (1977). An optimal control strategy was formulated to reduce the amount of auxiliary energy used and to avoid peak load hours for solar structures. The proposed strategy consisted of three interrelated operations. First, a short-term weather forecasting model based on the Kalman filtering approach was used to obtain the predicted values of the weather parameters (solar radiation, wind speed and ambient temperature). The amount of auxiliary electric energy required to be stored in order to satisfy the predicted heating load requirement for the next day was then determined from the estimated amount of useful solar energy collected, the estimated heating load, the amount of energy available in the storage tank, and the expected losses by heat transfer processes. Finally, a linear programming scheme was used to determine the optimal electric energy consumption sequence and a self-tuning regulator was used to minimize the occupant discomfort. Additional papers that dealt with this problem were (Winn and Duong, 1978), (Lorsch. Oswald and Crane, 1978), (Debs, 1978), (Moe, 1978), (Eltimsahy and Santos, 1977), (Debs, 1979), (Dorato, 1979) (Sebald, et.al., 1980), and (Winn, 1982). Weather prediction models suitable for implementation in

microprocessor based controllers have been studied by Sinha and Sharma (1975) and by Hamlen and Hamlen (1976).

The studies mentioned above dealt primarily with solar heating and cooling systems and only secondarily, in some instances, with off-peak storage type devices. The possibility of using heat or cool storage and off-peak electricity for charging of the storage has not escaped consideration. A Luenberger observer was developed (Hays, Parkinson and Winn, 1979) for accurately predicting ambient temperatures for up to 24 hours in advance and this has been built into the controller for an off-peak heat storage device and operated in one of the Colorado State University solar houses. Some of the hardware and software details for this device were presented in (Winn and Robinson, 1979). Additional energy storage systems were discussed in (Kalhammer, 1979), (Lorsch, 1980), (Winn and Winn, 1982) and (Winn et. al., 1982).

In addition to the controllers, one must have an efficient mechanical system design, and efficient energy conversion hardware. There have been many papers written relative to the subject of efficient energy conversion equipment. In (Grot, 1975) the feasibility of combining various appliances that are now constructed separately into integral assemblies which would permit more efficient energy design, utilizing waste heat and minimizing the impact of appliance operation on heating and cooling systems, was considered. Single zone, single zone variable volume, multi-zone, dual-duct, terminal unit, etc. systems are described in (Shih, 1976) and the interrelationships between the fan systems / hydronic systems, the energy converting machines and the building are presented. Papers dealing specifically with the hardware aspects of controllers in building climate control systems include (McNall, 1976) and (Baitz, 1976) in which recommendations for

government sponsored projects of R and D for energy conservation are presented. Also, in (Vanderweil, 1976) a review of the different types of HVAC systems, including fan coils, unit ventilators, closet units, induction units, self-contained units and incremental heat pumps was presented. Baumann (1979, 1981) describes how pump and valve characteristics affect flow control techniques in fluid loops. Another paper (Gajjar, 1976) described low cost techniques for monitoring and utilization of energy in rooms and zones of structures, and using these techniques to automatically control the temperature of the zones to effect a savings in energy. Heating system controller parameters that influence system efficiency and operating costs and that can be field adjusted, but for which no criteria for optimal adjustment have been developed, were discussed in (Bonne, et. al. 1976). In addition both retrofit and new equipment aspects were covered, together with a breakdown of the operating costs and savings due to changes in fuel and electricity consumption. In another paper (Jones, et. al., 1976) a two stage analysis was conducted in which the energy requirements for an existing office building were examined in detail and the most promising opportunities for conservation were identified and then the potential impacts of the various possible conservation measures were evaluated. In another paper (Mrnka, 1976) various types of controllers were analyzed and their characteristics were described. Enthalpy controllers, anticipatory controllers and olfactory controllers were discussed. An examination of sensor requirements for building control and energy management was presented in (Johnson, 1976). An analysis of the requirements for on-line management and supervisory strategies to control the interaction between system elements in HVAC systems was presented in (Anderson, 1976). Performance characteristics and relative costs of control elements such as

dampers, valves for liquid and vapor, switches, relays, pneumatic and electric evacuators, and communication network requirements were discussed in (McNall and Buchanan, 1976).

As mentioned earlier, adaptive control may have important applications in solar heating and cooling because the plant parameters are not always accurately known. The parameter estimation techniques necessary to implement adaptive control are discussed by Pryor et. al. (1980) and Pryor and Winn (1982). Adaptive controllers utilizing such real-time estimation techniques, and computing in real time the parameters necessary to implement an optimal regulator control were developed by Farris and Melsa (1978) and MacDonald et. al. (1978) and evaluated after implementation in a commercial scale building by Farris and Melsa (1980).

Designs of controllers for industrial process heat applications have been reported by Su and Castle (1979) and Gerwin (1980). Flow control for a high temperature (central receiver) system that could also be applied to low and medium temperature collectors is analyzed by De Rocher et. al. (1982).

Hardware designs for microprocessor based controllers are reported by Johnson and Winn (1975) and by Kent et. al. (1978) and their implementation and testing are reported by Winn and Hull (1977), Eisenberg et. al. (1977), Moen and Lane (1978) and Hays et. al. (1978).

4. RECOMMENDATIONS FOR FURTHER RESEARCH

From the foregoing literature review a number of areas for further research have been identified. Some of the suggested research involves taking previous research topics to their logical completion. In these areas the tasks are fairly well defined. Other topics involve inquiries where the magnitude of improvements in cost or performance are harder to guess in advance. These areas of research will necessarily require of investigators a desire to embark on an uncharted course, defining new tasks and abandoning unpromising control concepts or analytical methods as the work progresses.

Research on Controls for Collecting Solar Energy

Much research has focused on preventing cycling and maximizing solar energy collected or maximizing the difference between solar energy collected and parasitic energy.

Bang-Bang Controls

Davis (1975) gave an expression for differential control set points that maximized the duration of collector operation subject to no ON/OFF cycling under steady state conditions:

$$\frac{\Delta T_{ON}}{\Delta T_{OFF}} \geq \frac{mC_{p}}{A_{c}U_{L}}$$

Alcone (1981) corrected the expression for heat removal factor:

$$\frac{\Delta T_{ON}}{\Delta T_{OFF}} \geq \frac{mC_{p}}{F_{R}^{\prime}A_{c}U_{L}}$$

In the foregoing expressions ΔT_{OFF} is usually determined from the generally accepted constraint, $COP = \frac{Q_{collected}}{P_{pumping}} \ge 1$, which implies: $\Delta T_{\text{OFF}} \geq \frac{\Delta p}{\eta \rho C_{p}}$

where ρC_p is the heat capacity per unit volume of the collector fluid, Δp is the collector loop friction loss and η is the pump efficiency. Obviously the collected energy is maximized where there is no slack in the above constraints (i.e. they become equality constraints). In hydronic systems ΔT_{OFF} is often on the order of $0.5^{\circ}C$. This is as great or greater than the error bounds typically exhibited by thermistor temperature measuring devices. The effect of errors in determining whether or not the collector temperature rise exceeds the desired ΔT_{OFF} (e.g. probe error, thermistor/resistor bridge (mismatch) errors) has never been properly assessed.

Lunde has suggested a method for mitigating these errors by using stagnation temperature instead of collector outlet temperature. With this scheme the COP = 1 constraint gives the same expression for ΔT_{ON} :

$$\frac{\Delta T_{ON}}{\Delta p/\eta \rho C_p} \geq \frac{m/C_p}{F_R^{\prime A_c} U_L}$$

In principle one can make $\Delta T_{ON} - \Delta T_{OFF}$ arbitrarily small since (in contrast to collector outlet temperature) the stagnation temperature is not affected by the pump state (ON or OFF). In practice, however, there is some thermal coupling between the collector fluid and the stagnation temperature sensor (i.e. the sensor suggested by Lunde actually measures some weighted average collector outlet and stagnation temperature). Although the effect of a $\Delta T_{ON} - \Delta T_{OFF}$ of 1°C or so should be small it has never been properly assessed. It will also be necessary to conduct field tests of this improved control strategy before it will be accepted by the industry.

Winn (1982) has shown that the above constraint on $\Delta T_{ON}/\Delta T_{OFF}$ is conservative because some cycling is permissible (also inevitable since collectors do not operate in steady state) and because thermal capacitance effects result in rather slow cycling when it does occur. Winn derives a cycling time of

$$\Theta(t) = \frac{m}{m} \left[\frac{\frac{mC_{p}/A_{c})\Delta T_{ON}}{G(t)(\tau \alpha) - U_{L}(T_{s}(t) - T_{A}(t))} - F_{R} + 1 \right]$$

Thus the number of pump cycles per day is:

$$I = \int_{t_0}^{t_f} \Theta(t) dt$$

Assuming constant T and T and that

 $G(t) = G_{M} \quad Sin(\frac{\pi}{12} t), \quad 6:00 = t_{1} \leq t \leq t_{f} = 18:00$

the expression for N may be evaluated analytically to give N as a function of G_{M} and ΔT_{ON} . A suitable value of ΔT_{ON} that is less than the value given by $\Delta T_{ON}/\Delta_{OFF}$ may then be selected.

The effect of such reductions in ΔT_{ON} on performance and cost should be evaluated in further research. A set of charts for specifying ΔT_{ON} might also be useful.

Proportional and PID Control

Proportional control is used much less than ON/OFF control in controlling collector blowers and pumps. This is due mainly to lack of information about efficiencies of pumps with motors run on less than rated excitation and thus to uncertainty that parasitic power can be much reduced. Work is proceeding at SERI into this and the related problem of controls and pumps for closed drain down systems where initial head is much greater than steady state head. It will be useful if the partial excitation characteristics of a number of pumps and blowers are characterized in this work.

A control scheme that combines some of the features of proportional control and of bang-bang control involves the use of multi-rate circulators. A multi-speed blower controlled by a microprocessor programmed to maximize the difference between collected and parasitic energy was tested in C.S.U. Solar House 2 by Hays et. al. (1979). In hydronic systems it is practical to run two or more pumps in series or parallel in order to achieve the range of desired flow rates. (This scheme provides additional protection against collector stagnation due to pump failure as well.) A relationship for specifying differential control thresholds for multi-rate circulators based on the steady state criterion for no cycling was derived by Armstrong (1979):

$$\frac{\Delta T_{i} \rightarrow j+1}{\Delta T_{j} \leftarrow j+1} \geq \frac{F_{R_{j}} \stackrel{m}{}_{j+1}}{F_{R_{j+1}} \stackrel{m}{}_{j}} = \frac{1 - \exp(-\frac{A_{c}U_{j}}{\cdot})}{1 - \exp(-\frac{A_{c}U_{j+1}}{\cdot})}$$

where m_j is the mass flow rate with the multi-rate circulator operating at its jth rate, m_{j+1} is the next higher available rate, and the $A_c U_j$, j=0,1,..., are the <u>overall</u> collector loss conductances (corresponding to F'A_cU_L for a collector loop with just one flow rate) at the various flow rates, m_j . The thresholds for transition to lower circulation rates, $\Delta T_{j \leftarrow j+1}$, come from the COP criterion that is used to specify ΔT_{OFF} for the simple bang-bang control, thus:

$$\Delta T_{j \leftarrow j+1} = \frac{\Delta P_{j+1}}{\eta_{j+1} \rho C_p}.$$

Note that this accounts for the nonlinear relation between pumping power

and flow rate which unadorned proportional control does not.

A proper comparison of the costs of and long term performance resulting from use of bang-bang, proportional, and multi-rate controls for collecting solar energy should include analysis of systems with a range of collector, heat exchanger and storage parameters, and systems operating in a range of different climates. Current circulator efficiency curves, especially germane to proportional control, should be used as well as hypothetical efficiency curves that can be anticipated with improved motors and motor speed controllers. Variable speed control involving a nonlinear relation between AT and pump excitation power should be analyzed as well.

A related topic that has received virtually no attention is the use of a PID input stage in a bang-bang or multi-rate output controller.

Winn and Winn (1981) have derived the optimal control that maximizes the difference between collected energy and parasitic energy when parasitic power is not directly proportional to m:

$$J = \int_{0}^{t_{f}} (C_{1}Q_{u} - P)dt$$

where $P = C_2 m^{\alpha}$.

Using an approximation for F_R

$$F_R \approx F' - F'^2 \frac{A_c U_L}{2mC_p}$$

the resulting optimal control is:

$$\mathbf{m}_{opt} = \left[\frac{C_1 f F'^2 A_c U_L}{2 \alpha C_2 C_p}\right]^{1/\alpha+2}$$

where f, the available energy, is zero if $(T_0 - T_s)$ is negative or, if $(T_0 - T_s)$ is positive, determined from either

$$f = mC_p(T_o - T_s)/F_R$$

if the collector fluid mover is on, or

$$f = A_c U_L (T_o - T_s)$$

if the fluid mover is off.

This control is optimal for mixed storage systems. Note that C_1 can reflect the ratio of pumping energy to collected energy values. This may be useful if time-of-day rates apply to parasitic energy.

Recent work conducted at the University of Wisconsin, Madison, has indicated that significant improvements in SDHW system performance can be realized by decreasing the collector flow rate in order to achieve a greater degree of thermal stratification. The increase in collector efficiency due to lower collector inlet temperatures more than offsets the decrease in the collector heat removal factor due to the lower flow rates. Flow rates less than one-fifth the normally recommended flow rates are being considered. The lower flow rates also result in lower parasitic losses. This area should be investigated in more detail since the recommended flow rates are so far different from those being used in typical installations at this time.

Research on Controls for Distributing Energy to the Load

In active space heating systems, Winn and Hull (1979a, 1979b, 1979c) have shown that auxiliary energy use can be reduced simply by reducing overshoot in control of temperatures in the heated space. Optimal PID control laws were used to obtain the control improvements over conventional bang-bang controls. Even greater reductions in auxiliary energy can be expected from auxiliary control improvements in passive buildings because of the larger thermal capacitances and longer time constants. One problem

in developing an optimal control law, however, is the variability of time constants in different heating zones due to the use of moveable insulation. This may be a promising application for adaptive control. The use of parameter estimation to implement such adaptive control should be investigated and the resulting effects on auxiliary energy use, peak demand, and overall heating costs in passive buildings should be evaluated.

Reduction of high coincident demand for auxiliary energy that conventional SHACS impose on utilities has been studied by Winn et. al. (1982). One result of this study was an optimal off-peak storage control law that was then compared, by simulation of the solar space heating system, to a conventional control law and to a suboptimal control law. The resulting solar load fractions, f, and total annual costs of supply, c, were:

Conventional	Suboptimal	Optimal
(no off-peak)	off-peak control	off-peak control
.51	.52	.49
\$2,932	\$2,749	\$2,596

The cost reductions were due mainly to reduced utility capacity costs (i.e. end user demand charges).

f c

Further investigation of the optimal off-peak control is needed because it assumes that the total load and solar energy collected over the on-peak period are known in advance. This typically requires a 12 hour weather prediction. An evaluation of the effect of weather forecast errors should be made.

System Simulation Studies

At the present time there is a need for a simulation program that is useful in studying control strategies for solar heating and cooling systems. The TRNSYS program is perhaps the most widely used solar system simulation program at this time but, although a controller subroutine has been added to the program, it is not sufficiently general and versatile to allow for the study of numerous control strategies of interest. For example, proportional controllers, PID controllers, adaptive controllers, etc. cannot readily be examined using the present TRNSYS program. SIMSHAC, a simulation code developed in 1973-74, was developed for the purpose of conducting control studies, but has not been updated since 1978. EMPSS and EMPS-2 were recently developed to study the impacts of solar heating and cooling systems on the electric utilities, but these programs require modifications to examine controllers. DOE-2 can be used for limited controls studies but is also neither specific enough, nor general enough, to be very useful in studies of controllers.

82.

It is recommended that one of the existing codes be modified to the extent that it may be used in controls studies so that improved strategies may be investigated. It is further recommended that experiments be performed in an existing well-instrumented systems test facility so that the code may be validated and various control strategies may be examined in a complete systems environment.

Hardware Studies

SERI has recently conducted a study of solar domestic hot water systems in which commercially available controllers were purchased and then tested in a laboratory environment. The tests revealed problems with sensor accuracy, sensor failure, controller accuracy, failure to meet

specifications, etc. Also, the tests were limited in scope and did not include a wide variety of controller types. It is recommended that the problems with reliability of SDHW controllers that were identified in the SERI study be resolved and that additional testing be performed, both on the controllers that were examined in the first phase of the work and on additional controllers.

The recommended research activities are summarized in Table 1.

		CONTROLLER FUNCTION/TYPE				
Recommended Research	C	ollecting	Distributing			
	Bang-Bang	Prop. and PID	Bang-Bang	Prop. and PII		
Quantify Parasitic Losses	x	x	X	X		
Investigate Controller Based on Stagnation Temperature	X					
Determine the Effects of Cycling on System Perfor- mance and Cost	X		х			
Develop Charts for Specifying ΔT _{ON}	X					
Determine Partial Excitation Characteristics of Pumps and Blowers		X		X		
Examine Multi-Rate Circulators						
.Test Relationship for Differential Control Thresholds	X	X				
.Compare Costs and Performance	X	X				
.Test the Use of the PID Input State in Mixed Storage Systems	X					
.Test the Performance of Systems at Very Low Flow Rates	X	X				
Test Controllers that Reduce Overshoot				X		
Test Off-Peak Storage Controllers			х	X		
Examine the Use of Weather Prediction in Controls			х	X		
Develop Control Systems Simulated Program	X	X	Х	х		
Testing for Reliability	X	X	X	X		

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10. SUPPLEMENTARY NOTE	S		
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Document describes a	computer program; SF-185, FIP	S Software Summary, is attached.	
11. ABSTRACT (A 200-word o	r less factual summary of most :	significant information. If docum	ent includes a significant
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As part of the FY 1	.983 Department of Ene	rgy Systems Effectiven	less Research Program,
the National Bureau	of Standards (NBS) w	as assigned responsibi	lity for developing
research priorities for improving the effectiveness (i.e., thermal performance, cost,			
reliability and maintainability) of active solar hot water and space conditioning			
systems. To carry out this task, NBS, in cooperation with various industry			
representatives, organized and conducted two meetings in August 1983. The first			
meeting covered all major aspects of active solar hot water and space conditioning			
systems. The secon	d meeting dealt only	with solar control sub	systems. Based on
information obtained from these meetings, recommended research priorities for			
improving the effectiveness of active solar energy systems are presented.			
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