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Center for Applied Mathematics
National Engineering Laboratory
U.S. Department of Commerce
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*While performing this research in FY 1982, Provan was an NRC/NAS Postdoctoral Research Associate.

U.S. DEPARTMENT OF COMMERCE, Malcolm Baldrige, *Secretary*
NATIONAL BUREAU OF STANDARDS, Ernest Ambler, *Director*

ABSTRACT

We consider in this paper the d-algorithm of J. P. Roth, which tests for specific faulty behavior in an integrated circuit. We develop a formal and general mathematical description of the algorithm, which allows a large degree of flexibility and extension in its implementation. We discuss a subsequent FORTRAN coding of such an extended d-algorithm, along with some sample testing.

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1. Introduction

The advent of very large scale integrated circuits (VLSI) has intensified the interest in all aspects of testability, including test generation, self-testing, and testability measures, as well as the impact of these on design for testability and reliability of VLSI's. This report deals with a special aspect of test generation which is often referred to as "fault specific" test generation. By this we mean a procedure which generates — for a specific circuit and a suspected single malfunction or "fault" associated with that circuit — a test which detects the absence or presence of that malfunction in the circuit. The main tool for fault-specific test generation continues to be the d-algorithm. Developed by Roth in 1966 [19], the d-algorithm has been the target of continual development over the succeeding twenty years since its introduction.

This is a report on work of the Operations Research Division in developing a formal and general mathematical description of the d-algorithm, in designing a more flexible version based on this formalism, and in a subsequent FORTRAN implementation of this algorithm. The algorithmic scheme permits the handling of a very general type of circuit logic geared towards broader levels of circuit descriptions and analysis. It allows the coalescing of groups of components into a single gate, permits description of general fault logic, and allows handling of nonclassical and simultaneous types of faults. The flow of the algorithm itself can be brought partly under control of the user. This provides flexibility in testing specific types of circuits and generally allows for an improvement in the efficiency of the algorithm. Finally,

the same algorithm which is used to generate test vectors for a circuit can be used to check a test vector efficiently in order to determine which faults it can detect. This feature is very useful when it is desired to find a set of test vectors which "cover" a given set of faults. Although the code as it stands is restricted essentially to digital nonsequential circuits, the tools developed up to this point show every indication of being applicable to fault detection in more general devices.

Section 1 gives a description of circuit faults and fault detecting algorithms, and provides a brief summary of work which has been done in the area. Section 2 describes the conventional d-algorithm in detail and develops general terminology used in Section 3. Section 3 describes the ways in which the description given in Section 2 can be generalized to include nonclassical faults and more general search techniques, and Section 4 describes aspects of the computer implementation of the generalized d-algorithm. The appendix describes a particular version of the d-algorithm which was implemented in FORTRAN at the Bureau of Standards, and includes some sample output.

1.1 Circuit Diagrams

Conventional versions of the d-algorithm address digital nonsequential (memory-less) circuits. The description of such a circuit involves two entities--lines, which carry 1-0 (high-low) signals between points of the circuit; and gates which process or generate signals on lines adjoining them. Each gate has input and output lines, along with an explicit description of the signals on the output lines of that gate which result from a specified set of signals on the input lines. Each line goes from the output of a single source gate to the inputs of one or more receiving gates, and indicates that the signal produced by the source gate is to be the corresponding input to the receiving gates. The entire circuit has special gates called input and output gates. A user of that circuit is able to control the circuit only through the sets of signals given to the input gates -called input vectors- and is able to observe the circuit only through signals -called output vectors- emanating from the output gates. Since the circuit has no memory, each gate description is independent of previous history of gate operation, and the gates and lines admit no "feedback," that is, no path of signals returns to a point previously visited. (This is what is meant by being nonsequential.) It follows that for any set of circuit inputs there is a well defined sequence for gate processing producing the unique set of circuit outputs which results from applying these inputs. It is possible to extend the description to include memory and feedback, although that problem is not addressed in this paper.

As an example circuit, we consider the "one-bit adder." It can be described simply as a circuit whose inputs are two one-bit binary numbers, and whose output is a two-bit binary number representing the sum of the inputs. One circuit which functions as a one-bit adder is shown in Figure 1.1. The gates are of five types and are interconnected with lines as shown. Input lines always enter on the left of the gate and output lines leave on the right. The gates marked "input" and "output" have no function other than to apply given inputs or to record the appropriate outputs. The remaining gates are processing gates and process inputs as their name indicates. Thus, a "not" gate simply reverses the input signal from 0 to 1 or from 1 to 0, the "or" gate produces a 1 output if at least one input has value 1, 0 otherwise, and the "and" gate produces a 1 output if both inputs have value 1, 0 otherwise. Of course, the output of these gates depends entirely on the values of the inputs. Further, it is not possible to travel progressively from gate to gate by traversing lines from output to input and return to a point previously visited. Thus, by processing the gates 1 through 5 in the order given, we obtain for any given set of inputs the unique set of outputs which corresponds to the two-bit sum of those inputs. We note, of course, that there may be many circuits which yield the same function as the circuit of Figure 1.1 but whose circuit description is essentially different. Figure 1.2 shows one of these circuits. This circuit is made up entirely of "nand" gates, whose function is exactly opposite that of the "and" gate. Clearly, both the gate description of the circuit and the actual physical layout of this circuit on a chip can affect the functioning of the circuit and the types of faults which can be expected to occur when operating such a circuit.

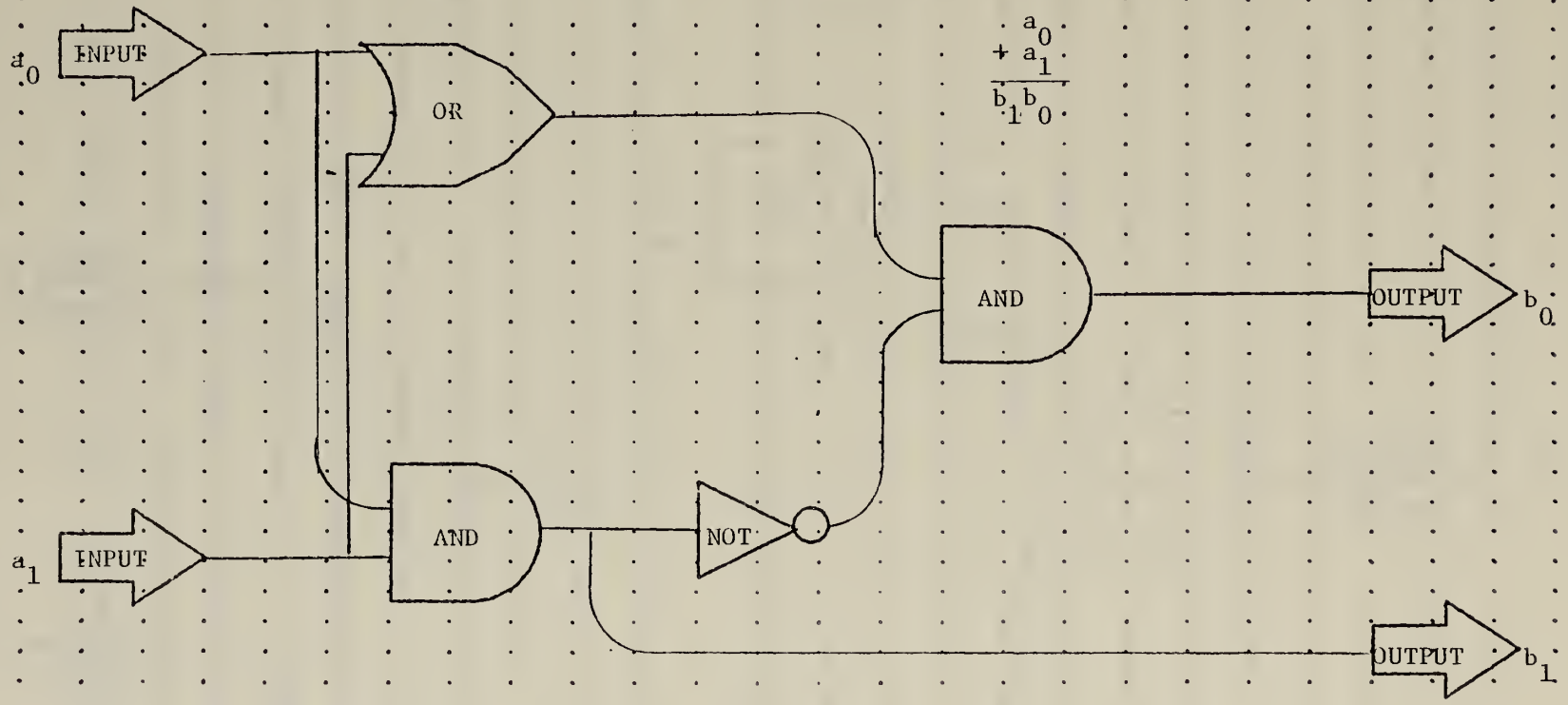

Figure 1.1: A realization of the 1-bit adder

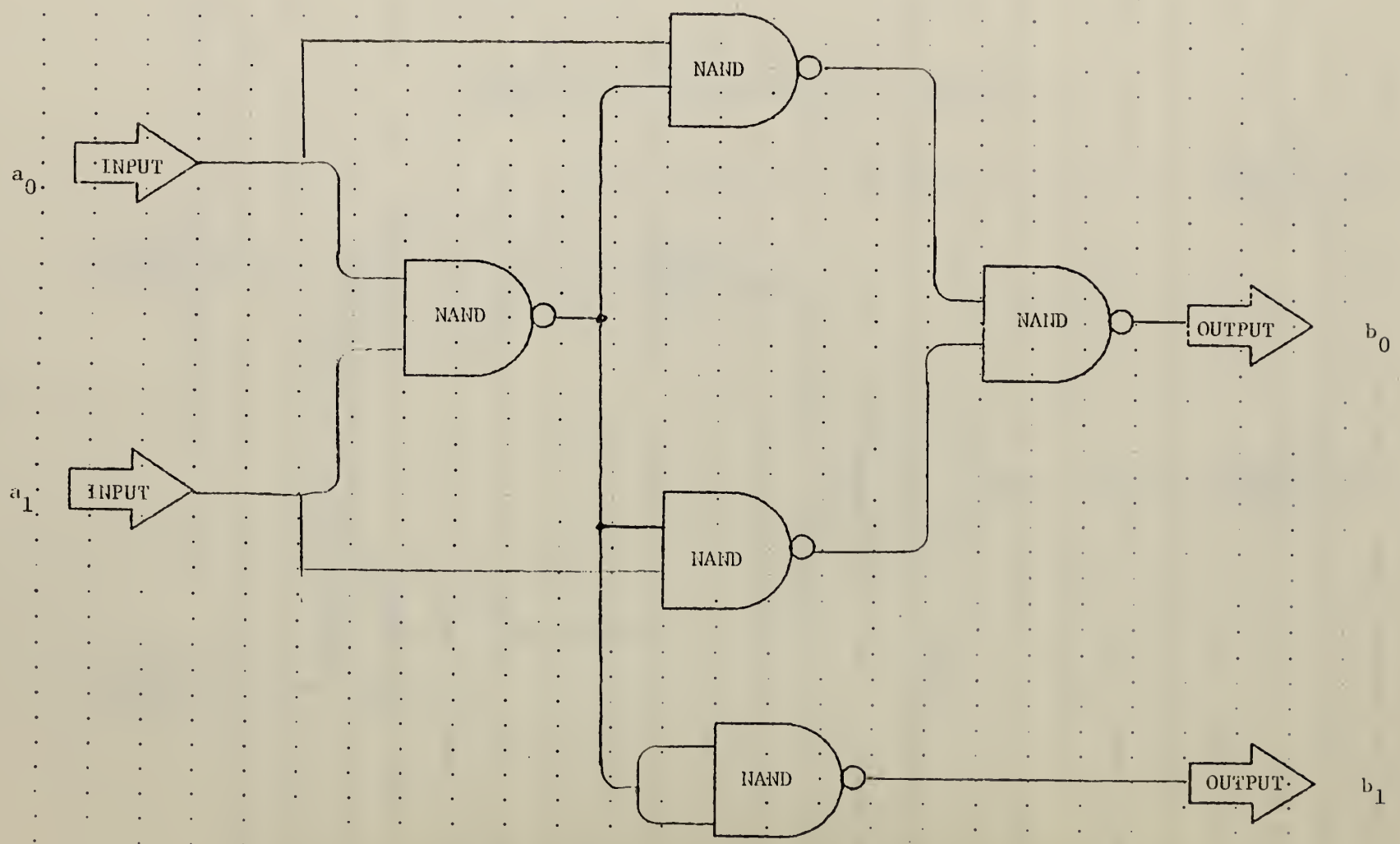

Figure 1.2: An all "NAND" gate realization of the 1-bit adder

1.2 Faults and Test Vectors

A fault is any change in the internal structure of a circuit which affects the normal functioning of that circuit. In order that we have a demonstrable method of detecting faults in a circuit, we insist that a fault, when it occurs, has a well-defined and consistent functional effect on the gates and lines associated with it. Thus, for example, "intermittent" faults--that is, faults which occur at random times in circuit operation--are not considered here. One can, in fact, think of a fault as being a "pseudogate" in the circuit which processes lines and/or replaces gates in the system. This pseudogate, unlike normal gates, functions in one of two "modes"--the first corresponding to the normal functioning of the circuit and the second corresponding to the functioning of the circuit when the fault occurs. The mode in which the pseudogate functions, of course, is unknown to the user, except when it causes a discrepency in the outputs from the normal function of the circuit.

As examples, we describe two types of faults which occur naturally in connection with physical malformation of circuits, namely, the stuck-at faults and the cross-wire faults. The classified faults previously studied are the stuck-at faults which correspond to breaks or shorts in a line and have the effect of producing a constant signal at the terminal of the line regardless of the signal impulse at the beginning of the line. We, therefore, can speak of stuck-at-1 faults and stuck-at-0 faults. They can be described by placing on the line a pseudogate with one input and one output, which under normal operating mode simply passes the proper signal through and under fault mode

outputs a constant 1, or respectively an 0, regardless of the input (see Figure 1.3).

A cross-wire fault, (or bridging fault) as its name implies, occurs when two wires in close proximity inadvertently relay signals to each other. A cross-wire "and" fault occurs when a low (0) signal dominates a high (1) signal. The result can be described by placing on the two lines a pseudogate with two inputs and two outputs which under normal operating mode simply passes the respective signals through, and under fault mode outputs to both lines the signal corresponding to the "and" of the inputs (see Figure 1.4). A cross-wire "or" fault occurs when the high signal dominates the low signal, and the corresponding pseudo-gate described above acts in fault mode as an "or" gate.

The types of faults described above represent some of the standard types of faults which might occur on a circuit. They are, furthermore, "local" faults in the sense that they affect a relatively small number of signals in a small area of the circuit. One can imagine more complicated types of faults. A simultaneous fault, for example, consists of several individual faults occurring simultaneously in different parts of the circuit, and this often requires substantially different test finding procedures than simply testing for the faults individually. Other faults may involve certain complex types of gate malfunctions which have been observed only empirically and are described primarily by example. More general classes of faults will be discussed later in the paper.

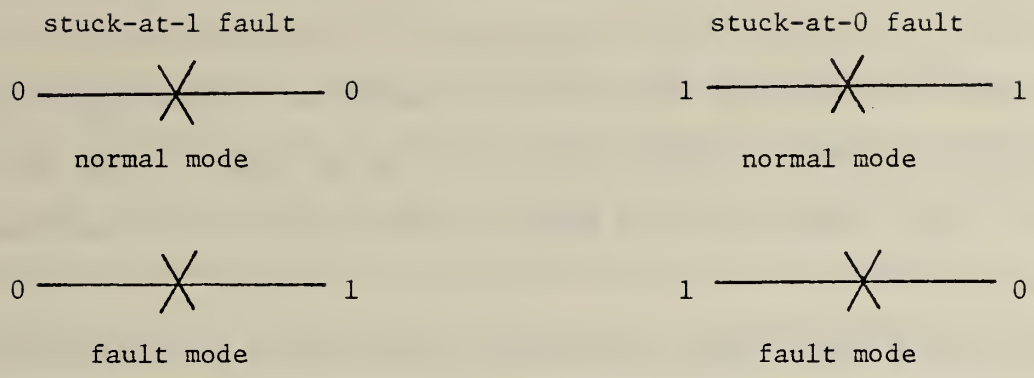

Figure 1.3: The stuck-at faults

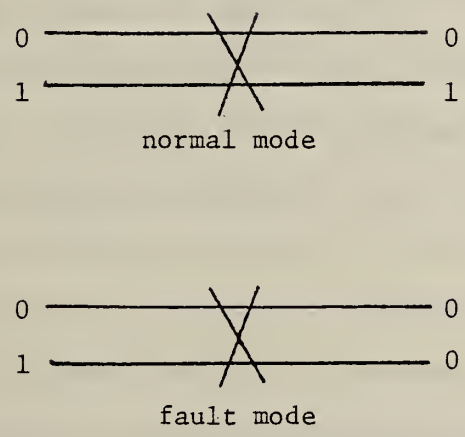

Figure 1.4: The cross-wire "and" fault

A test vector for a circuit and associated fault is an input vector whose output vector in the fault mode is different in at least one output from the output vector in the normal mode of circuit operation. A test vector, then, distinguishes the case when that fault occurs and no other from the case where no fault occurs. This is what is meant, in this report by the term "detects the fault."

The simultaneous fault concept allows one to distinguish the occurrence of several individual faults occurring simultaneously from the case where none of the faults occur.

A testing scheme for a circuit will consist of a set of test vectors applied to a circuit which will be able to detect any of a given set of faults. Since these faults may occur in any number of simultaneous combinations, the scheme should ideally be able to test not only each individual fault, but any subset of faults occurring simultaneously, and should further more be able to isolate which of the set of faults are occurring in any specific malfunction. The construction of such a testing scheme is beyond the scope of this paper. Henceforth we are interested in simply producing a test vector which will identify a given specific malfunction in the circuit, and no other. It will turn out that this problem alone is difficult enough for an entire report.

1.3 The d-Algorithm: Description and History

The general goal of the d-algorithm is: given the description of an integrated circuit and a fault which can be expected to occur on the circuit, find a test vector, for the circuit which detects the occurrence of this fault in terms of discrepancies in the outputs elicited from the circuit. Specifically, given a circuit description with a fault pseudogate (or set of simultaneous fault pseudo-gates), a given set of inputs detects the given fault if the outputs obtained when the pseudogate (or all pseudogates) are operating under fault mode differ from the corresponding outputs obtained when the pseudogate (or all pseudogates) are operating under normal mode.

It is clear that any digital nonsequential circuit can be tested completely by applying all possible inputs and observing the corresponding outputs for discrepencies between normal and fault mode operations. This is dependent only on the functional description of the circuit and detects all possible faults which affect the correct functional operation of the circuit. For large enough circuits, however, the number of such inputs would far exceed any reasonable amount of testing time alloted for the circuit. A method is needed for efficiently designing tests for certain "key" faults expected to occur in the circuits. One property that such an algorithm must take advantage of is the local nature of most circuit faults. In particular, the algorithm should be able to design a test for a fault by beginning at the fault site or sites and working towards the extremities (inputs and outputs) for the circuit.

Such algorithms naturally proceed in two stages: the propagation (or observational) stage, which insures that the fault can be seen as a discrepency in the outputs, and the justification (or generation) stage, which insures that there exist inputs which are consistent with the fault propagation found during the first stage.

The first attempt at such an algorithm, based on results by R. D. Eldrid [10] and unpublished work by Steiglitz and Armstrong, is the path sensitization method of fault detection. Path sensitization is used primarily for stuck-at faults on circuits made up of simple logic gates (such as and, or, not, nand, and nor). The object of the algorithm is to construct a "sensitized path" from the fault to a circuit output and subsequently derive inputs which support such a path. It is based on the fact that for each gate of the above type and each input line to be "sensitized," there is a unique signal which can be placed on the other input line (if any) which allows the input signals on the sensitized line to be distinguished by the signal on the output line. For an "or" gate, as an example, a given input can be distinguished at output by placing an "0" signal on the other input. The output value then exactly matches the signal of the sensitized line. Note that if "1" signal is placed on the other input, the gate output registers "1" regardless of the signal of the sensitized input, and so this configuration cannot pass through a sensitized input. For a "nand" gate (one whose output registers the opposite of the "and" of its inputs) and given input to be distinguished, placing a "1" on the other input allows it to be distinguished at the output. The output here registers the opposite signal to the input, but can nonetheless distinguish the signal on the given input.

The path sensitization algorithm starts at the stuck-at fault by fixing a value to the line which will distinguish the fault mode operation on that line from the normal mode operations--specifically, a 1 signal for a stuck-at-0 fault and a 0 signal for a stuck-at-1 fault. It then proceeds to construct a sensitized path from the fault to a circuit output by setting the unused input at each successive gate to the proper sensitizing value. The consequence of sensitizing such a path is that now the change in the line signal resulting from a fault is able to propagate through succession lines in the path until it is registered at the output gate as the opposite signal from the normal signal expected for that output. In fact, it follows that a sensitized path will register the appropriate stuck-at fault on <u>any</u> line of the path and thus the construction of long sensitized paths is an efficient way of detecting a large number of faults by a small number of tests. If, after the sensitized path has been constructed, the inputs can be assigned values which are consistent with (that is, produce the correct values for) the lines assigned in producing the sensitized path, than these input values constitute a test vector for the fault.

Two problems need to be resolved concerning the path sensitization algorithm as described above. The first is a procedural one, namely, how to structure the search for a sensitized path and subsequently justifying inputs. A search must, in particular, be efficient in searching for or discarding conditions for sensitized paths and input values, and at the same time insure that an exhaustive search has been made for such a path. A second and more fundamental problem is that certain faults may not be able to be tested by a single sensitized path (See Subsection 2.4). This is especially true of

simultaneous faults or non-classical faults such as the cross-wire faults, but is true of single line faults as well. A complete propagation/justification type algorithm must therefore be able to "sensitize" an arbitrary number of lines of a circuit in order to be able to do a complete search for test vectors for a fault.

Both problems were effectively answered by Roth [19] with a procedure known as the d-algorithm. The d-algorithm can be thought of as a multi-path sensitization algorithm, although the description must be more elaborate and the record keeping mechanisms more sophisticated. It has the further property that it either finds a test vector for the given fault or demonstrates that the fault is undetectable, that is, that no input values are capable of registering a discrepency in any of the outputs as a result of the presence of that particular fault. Roth's work provides both a way of describing the action of a fault on a circuit and a effective method of manipulating the operation of the circuit in order to find the appropriate input values. It has therefore been an invaluable seminal paper for research in the field of circuit reliability. Section 3 describes some of the methods used to speed up the search and processing so as to make the test generation as efficient as possible.

A great deal of research has been done in the area of circuit testing following the Roth paper. A good sample of the directions this research took is found in [36]. As an indication of the amount of interest in the field, we refer the reader to twelve annual IEEE Conferences on Fault-Tolerance Computing [45] -[56], nine issues of IEEE Transactions on Computers devoted to fault-tolerent computing [36] -[44], several books on the subject [32] -[36],

and lists of compiled literature [16], [26]. Some specific extensions of Roth's work include: structural factors in fault diagnosis [1], [2], [23], multiple fault diagnosis [3], [5], [7], [9], sequential circuit testing [21], fault location and coverage [6], [14], [31], and more general circuit and fault models [4], [10], [17]. Recent work has tended to be in the areas of design for reliability and testability [1], [8], [12], [13], [30], and tests for specific types of circuits [11], [12], [18], [27], [28], whereas and relatively little research has been devoted to further development of fault-specific test generation algorithms [20], [21], [22]. This is partly due to the fact that the problem of fault-specific test generation has a large degree of inherent intractibility. Another reason, however, is that an understanding of the d-algorithm has remained relatively inaccessible to the general scientific community. This is due partly to the fact that the d-algorithm has never been presented in a general mathematical format and papers have retained machinery and terminology specific to the task of fault-specific test generation in combinatorial circuits. This is unfortunate, for the d-algorithm concept has great potential for use in more general types of electronic fault-testing as well as for applications to system maintenance and reliability outside the electronics industry. It is with these thoughts in mind that we attempt to present the d-algorithm in a more general setting, one which, we hope, will encourage it to be put to use in a wider scope than it has been in the past.

2. The Conventional d-Algorithm

In this section we give a more specific description of the d-algorithm as it is commonly implemented at the present time. Our description will stress a formal structure of the algorithm and will be in a form appropriate for generalization in Section 3.

Subsection 2.1 introduces a general search procedure known as the "backtrack algorithm," which is found as an underlying principle in a large number of combinatorial algorithms which require exhaustive searches.

Subsection 2.2 deals with a description of gate and fault functions which allows implementation of the propagation and justification formats described in Section 1.

Subsection 2.3 combines the concepts of Subsections 2.1 and 2.2 in presenting a specific description of the d-algorithm, with an example in Subsection 2.4.

2.1 Backtrack Algorithms

A "backtrack algorithm" describes a general search technique for exhaustively considering a sequence of alternatives in order to achieve a desired solution. The goal of a backtrack algorithm in any application is to discard undesirable alternatives as quickly as possible while still maintaining a complete search among all of the available alternatives. The general format for a backtrack algorithm involves a set of decision points which are usually encountered in a fixed order and at which the algorithm must choose among one or more alternatives. The alternatives are provided by a decision list available at each decision point. Any backtrack algorithm proceeds from decision point to decision point, choosing the first available alternative on each decision list. If at any decision point the alternative chosen is found to be inconsistent with the alternatives chosen at previous points —that is, the set of alternatives chosen thus far cannot possibly yield the desired solution --then the next alternative on the decision list is considered. If a decision list is exhausted so that no alternative at that point is consistent with the alternatives chosen at previous points, then the algorithm backtracks to a previous decision point and chooses the next available alternative in the decision list for that point. If a set of alternatives is found, one for each decision point, which gives the desired solution, then the algorithm stops and exhibits such a solution. If the algorithm completes the entire search, that is, finally exhausts the decision list at the very first decision point, then the algorithm has covered every possible choice of alternatives for all decision points and therefore no solution exists to the problem. Figure 2.1 gives a flow chart for the general backtracking algorithm.

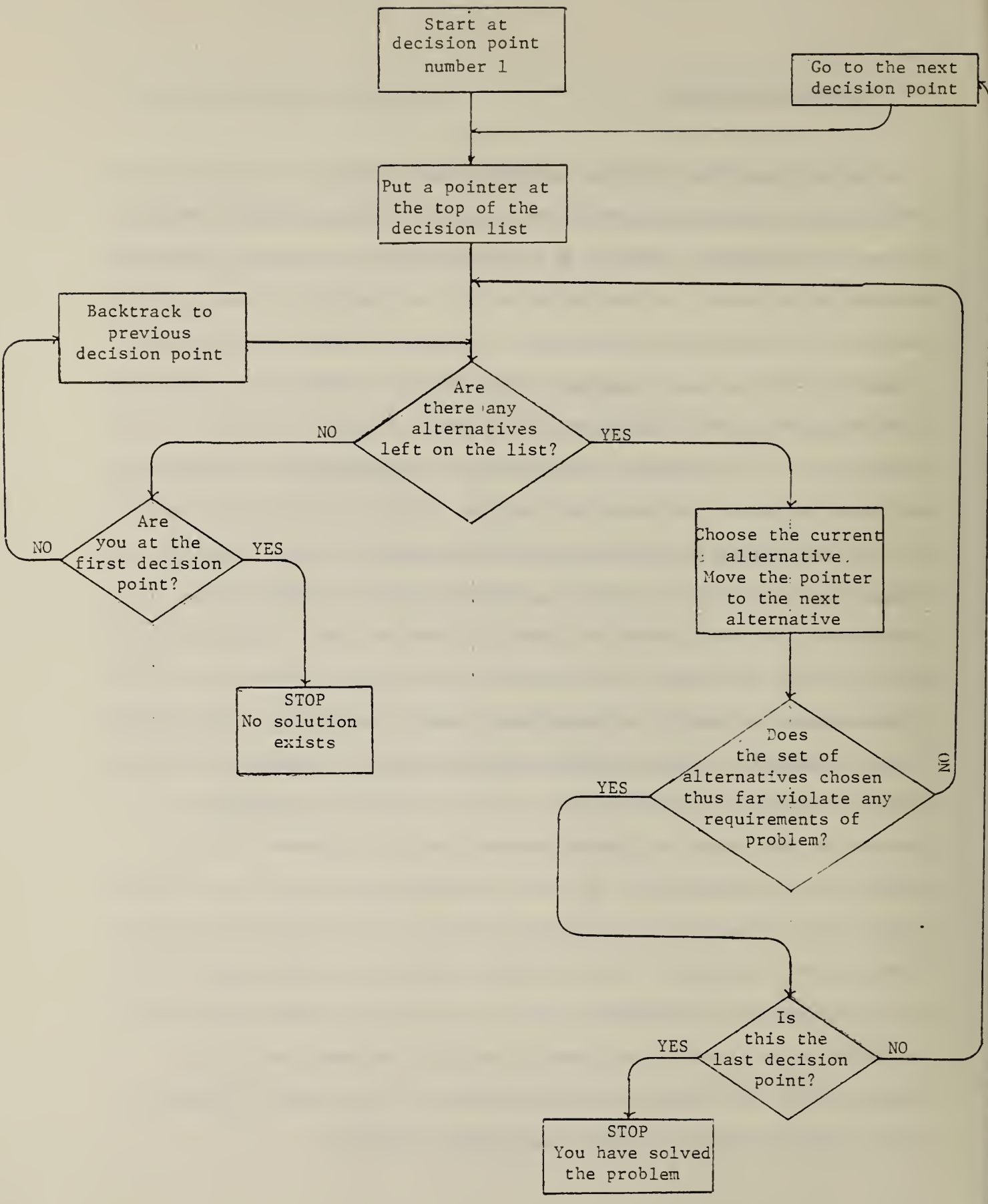

Figure 2.1: A general backtrack algorithm

We now give a broad description of the backtracking mechanism inherent in the d-algorithm, the details of which will be related in succeeding subsections. The decision points are the gates of the circuit (including pseudogates associated with faults), and the decision list associated with each gate is an assignment of "values" to the lines adjacent to that gate. The format of the decision list is called a cube for the gate, and it is explained in Subsection 2.2. The algorithm "processes" gates in some order, that order to be explained in Subsection 2.3 and in more detail in Section 3 and 4. At each gate, a set of line values is chosen for that gate which satisfies:

(1) it is consistent with the logical function of that gate;

(2) it is consistent with decisions made at previous gates, in that the line values chosen agree with the line values of every other gate on that line.

If the algorithm can find a set of values which satisfies these criteria, then it moves on to process the next gate. If it cannot find an acceptable set of values, then it backtracks to the previous gate considered and continues processing this gate. If a set of line values is chosen for all gates which is consistent from gate to gate and detects the given fault, then the algorithm stops and produces the test vector. If the decision list is exhausted for the first gate processed, then the algorithm stops and no set of inputs can detect the fault.

A backtrack algorithm may have to consider an enormous number of alternatives before it can ascertain whether or not a test vector exists for a circuit

fault. In particular, if every possible sequence of decisions is considered, the algorithm would have to test as many alternative sequences as the product of the lengths of the decision lists for every decision point. For example, if a backtrack algorithm had twenty decisions to make consisting of two alternatives each, as many as 2^{20}, or approximately one million possibilities would have to be considered. The most important property of a good backtrack algorithm is the ability to discern at the earliest possible decision point when a sequence of alternatives is inconsistent with the desired solution. This may depend on features such as the order in which decision points are considered, the order in which the decision lists are scanned, and even the types of decisions which are made at each point. Subection 2.3 and Section 4 will address some of the methods which were considered in this study to improve the efficiency of the backtrack algorithm when applied to test generation and the d-algorithm.

2.2 Cube and Fault Propagation

We now describe more precisely the structure of the decision lists, or "cubes," associated with each gate. A cube is simply an assignment of line values to lines adjacent to the gate which is consistent with the logical function of the gate. Cubics are of two types; logic cubes and d-cubes. A logic cube defines the basic logical structure of the gate and does not have any bearing on fault propagation in the system. It is associated with a logical type rather than a particular gate and comprises simply a list of the input values and associated output values which result when the particular logical operator is applied to that particular set of inputs. Table 2.1 shows the logic cube for an "or" type gate and for a "1-bit adder" type gate.

	Inputs 1	2	Outputs 3
1.	0	0	0
2.	0	1	1
3.	1	0	1
4.	1	1	1

An "or" cube

	Inputs 1	2	Outputs 3	
1.	0	0	0	0
2.	0	1	0	1
3.	1	0	0	1
4.	1	1	1	0

A "1-bit adder" cube

Table 2.1: Two Logic Cubes

A logic cube completely describes the logic of a gate and has the additional property that if the signals for any subset of the inputs and outputs are known, then a list can be supplied of all remaining inputs and outputs which is consistent with the set of known signals. For example, if it is desired to have a signal of 0 on line 3 of the "or" gate given above, then the only set of signals for the input lines which is consistent with this signal is the single pair (0,0). If, however, a signal of 1 is desired on output line 3, then any of the three pairs (0, 1), (1, 0), and (1, 1) are consistent with this signal. What this means is that the circuit need not necessarily be processed in input to output order, and that when a gate is processed it may produce a list of possible signals rather than a unique vector. It will be this type of list which constitutes the decision list in the justification phase of the d-algorithm.

Faults and fault propagation add a new dimension to cubes and necessitate an extension of the logic cube to accommodate the presence of faults in the circuit. We begin by investigating the description of a fault pseudogate. Such a gate, as indicated in Subsection 1.2, requires two simultaneous descriptions, namely, the functioning of the pseudogate under normal operation and its functioning when a fault occurs. To facilitate such a simultaneous description, we introduce two new "signals," d and $\overline{d}$. A signal d assigned to a line means that when the fault is present the line will have the value 1, and when no fault is present the line will have the value 0. The signal $\overline{d}$ assigned to the line means precisely the opposite. The d and $\overline{d}$ signals represent the discrepancy which is necessary to distinguish the fault mode from the normal operation, and therefore it will be these types of signals which will need to propagate to the outputs.

Once a careful description is made for a fault pseudogate in terms of normal and fault mode operation, it is easy to translate this description into a cube description by using the symbols d and $\bar{d}$. This is called the d-cube for the fault. Table 2.2 shows the d-cubes for a stuck-at-1 fault and a stuck-at-0 fault.

Input	Output	Input	Output
0	d	0	0
1	1	1	$\bar{d}$
stuck-at 1		stuck-at-0	

Table 2.2: The stuck-at fault d-cubes

In the stuck-at-1 fault, an input signal of 0 will produce an output signal of 1 (stuck) when the fault occurs and 0 otherwise, and hence its output value will be represented by the symbol d. An input signal of 1 produces an output signal of 1 in either normal or fault mode. In the stuck-at-0 fault, it is the 1 input which causes the discrepancy in the output, and this is indicated by using the symbol $\bar{d}$ as the corresponding output. The cross-wire faults and other nonclassical faults are discussed in Section 3.

To propagate a fault through the circuit, we need lastly to modify the cubes for the normal gate types to allow them to transmit the discrepancy signals d and $\bar{d}$. This will be the d-cube for the gate type. The modification of the logic cube of the gate to a d-cube involves a simple argument for each case of the sort "if the fault occurs, then...," and "if the fault does not occur, then..." We give as an example the extension of the logic cube for the "or" gate shown in Table 2.3:

	Inputs 1	2	Output 3
1.	0	0	0
2.	0	1	1
3.	1	0	1
4.	1	1	1
5.	0	d	d
6.	0	$\overline{d}$	$\overline{d}$
7.	1	d	1
8.	1	$\overline{d}$	1
9.	d	0	d
10.	d	1	1
11.	d	d	d
12.	d	$\overline{d}$	1
13.	$\overline{d}$	1	1
14.	$\overline{d}$	0	$\overline{d}$
15.	$\overline{d}$	d	1
16.	$\overline{d}$	$\overline{d}$	$\overline{d}$

Table 2.3: The "or" gate d-cube

Take, as a case, the row whose inputs are d and 0. We may argue as follows: "If the fault is present, then the first input will be 1 and the second input will be 0, so that the output is 1. If the fault is not present, then the first input will be 0 and the second input will be 0 so the output will be 0. Thus, when the fault exists, the output will be 1 and when the fault does not exist, the output will be 0. The output, therefore, is assigned the value d

in this row." Of course, the complete description of the cube is fairly long, and we have made some effort to abbreviate this description in the coding of the d-algorithm (see Section 4). We note that for d-cubes, as for logic cubes, any set of values for a subset of input and output lines for a gate induces a sublist of the d-cube which is consistent with the assigned value. Thus, for example, an assignment of d to the first input of an "or" gate produces the list of possible assignments of the remaining inputs and outputs given in Table 2.4

	Inputs 1	2	Output 3
9.	d	0	d
10.	d	1	1
11.	d	d	d
12.	d	$\overline{d}$	1

Table 2.4: A Restricted Cube for the "or" Gate

It will be this type of list which constitutes the decision list in the propagation mode.

2.3 Description of the d-Algorithm

We can now describe in a more precise fashion the general d-algorithm. We are given the circuit as described in Subsection 1.1, including as gates the fault pseudogates described in Subsection 1.2. We are also given d-cubes for the fault pseudogates and both logic and d-cubes for the standard gates in the circuit. The gates can technically be processed in any order, and some discussion on the merits of one ordering over another is undertaken in Section 4. Virtually every implementation of the d-algorithm, however, has the following restrictions on the ordering of gates:

1. All fault pseudogates and gates which are on a path originating from a fault pseudo-gate comprise the first set of gates to be processed. This is the propagation stage of the algorithm.

2. The remaining gates are then processed. This is the justification stage of the algorithm.

3. In the propagation stage, no gate is processed unless it is a fault pseudogate or until at least one gate (or pseudogate) immediately preceding that gate has been processed.

4. In the justification stage, no gate is processed until at least one gate (or pseudogate) immediately succeeding that gate has been processed.

Thus, gates are in general processed in forward order from the faults and then in backward order from the faults. This insures a sense of connectedness and direction to the problem. The general backtrack scheme, however, does not require such an ordering, and with modifications, the d-algorithm could accept gates in any conceivable order. This flexibility will be important to keep in mind when we deal with simultaneous faults.

The "decision list" for a gate is simply the cube for that gate, or more precisely, the restriction of the cube to assignments consistent with previous values assigned to input or output lines of that gate. The gates processed in the propagation stage are assigned decision lists derived from d-cubes. Gates in the justification stage, however, are assigned lists from logic cubes, reflecting the fact that no fault signals occur on that part of the circuit. Consequently, output lines from a justification stage gate must be assigned a logical value, even if they are input lines to a propagation stage gate. The decision lists vary accordingly, both by the location of the gate and by the values which have been assigned to the adjacent lines up to that point in the algorithm.

The gates are processed in the order given and with the decision lists as described above, thus insuring that line values are consistent both with gate logic and with respect to adjacent gates. One further check must be made to insure that these values can actually detect the fault. This check is done in the propagation stage on leading lines —that is, an output lines from processed gates for which at least one successor gate to that line is either an output gate or an unprocessed gate. The rule which must be applied here is:

Propagation Rule: At least one leading line must have a value d or $\bar{d}$.

The d-algorithm proceeds in the format of the backtracking algorithm described in Subsection 2.1, checking, in the propagation stage, the propagation rule, until it either makes a consistent assignment to the final gate or backtracks through all of the gates without finding a consistent assignment. In the former case, the input gate assignments indicate the test vector to be applied, and the assignment to the output gates--which are the only remaining leading gates--insure that at least one d or $\bar{d}$ assignment has occurred, so that this vector actually detects the fault. In the latter case, it follows that every possible assignment has been tried subject to circuit consistency and fault detection, so that no possible set of input vectors could detect the fault. Figure 2.2 gives a flow chart for the d-algorithm.

The d-algorithm, then, is guaranteed either to find a vector which detects the fault or verify that no such test vector exists. In this sense, it is superior to the path sensitization algorithm, which may fail to find a test vector when one actually exists. The added power of the d-algorithm is due to the freedom allowed to gate assignments which is not available to the path sensitization algorithm, so that many lines with d or $\bar{d}$ values may be propagated simultaneously. It is also important to note the improvement in efficiency of the d-algorithm over a straightforward enumeration of input vectors. The backtrack algorithm, starting from the point of fault, insures that the only assignments made are those which could lead to fault detection. It may, therefore, backtrack before it even assigns input values and generally

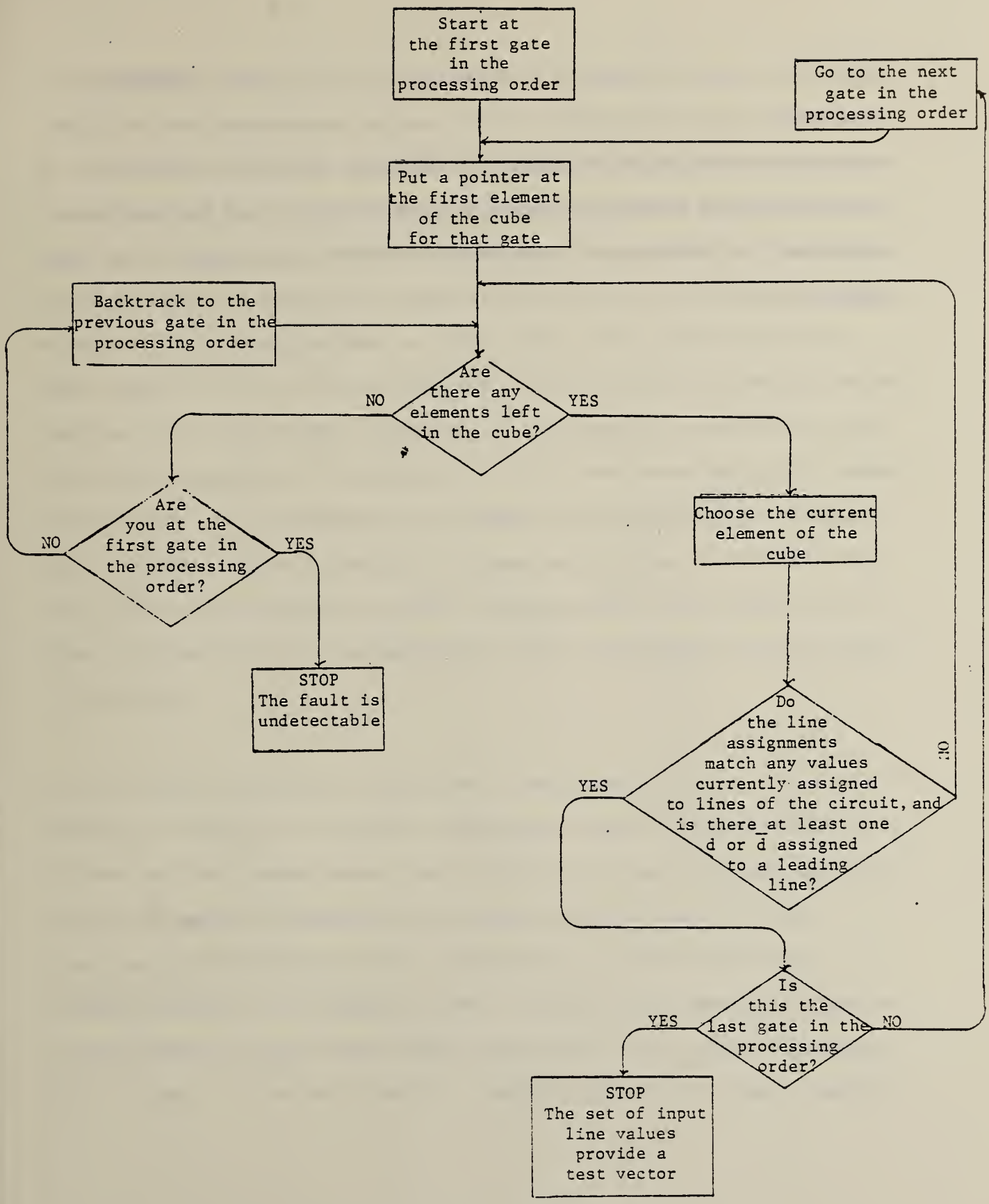

Figure 2.2: Format for the d-algorithm

assigns only a small proportion of these values to an invalid test before establishing that it is invalid. It is therefore considerably more efficient than straight enumeration of inputs. By improving the order in which the gates are searched (within the restrictions given above), and the ease with which gates can be processed, we can make substantial improvement in the basic d-algorithm.

2.4 An Example

As an example to illustrate the functioning of the d-algorithm as presented in the subsection 2.3, we consider the circuit shown in Figure 2.3. The large gates are all "or" gates, whose logic cube was given in Table 2.1, and whose d-cube was given in Table 2.3. (Input lines will always be numbered from top to bottom. The triangular gates are "not" gates. They simply invert the input signal ($0 \rightarrow 1$, $d \rightarrow \bar{d}$) and hence will not be considered separately in the backtrack. The circles will contain the values assigned to the lines as the d-algorithm progresses. It is desired to find a test vector which will detect the stuck-at-0 fault represented by the square box in Figure 2.3, and whose fault cube was given in Table 2.2. The gates are numbered in the order they will appear in the backtrack, and this ordering satisfies the restrictions 1-5 given in Subsection 2.3. The cube elements will be scanned in the order given by the tables.

We now proceed to apply the d-algorithm. Since leading lines must have d or $\bar{d}$ assigned to them, gate 1 (the fault pseudo-gate) must be assigned element 2 of its cube. We then process gates 2 and 3 choosing for each the first element in its cube for which the associated line values are consistent with lines already assigned (elements 6 and 5, respectively). Gates 4 and 5 are processed similarly with elements 13 and 1 respectively. (Note that there is no requirement that gates 4 and 5 have outputs of d or $\bar{d}$, since the leading line from gate 3 alredy has value d.) Assigning element 9 to gate 6 completes

the propagation stage. Figure 2.4 shows the assignments made thus far, with the number above each gate representing the cube element assigned to that gate.

For the justification stage, we assign gate 7 with its only consistent logical cube element 1, and then gate 8 has a unique consistent cube element 2. This gives the situation shown in Figure 2.5. But now gate 9 has no cube element which is consistent with its adjacent lines, and so the algorithm begins backtracking. Gates 8, 7, and 6 have no further consistent cube values, and gate 5 is now assigned element 2. Now gate 6 has inputs d and 1, and so cannot be assigned a cube element for which its output line -the sole leading line - has value d or $\overline{d}$. The algorithm backtracks to gate 5, for which there is no further element whose unassigned input line (to a justification stage gate) takes on a logical value. Thus the algorithm backtracks to gate 4 and gives it the next available consistent cube element 14. Gate 5 now goes through its cube once more, and the first available consistent element is 9. Gate 6 is now assigned element 11, and we arrive at Figure 2.6. We enter the justification mode once more, and again gates 7 and 8 have unique element assignments 1 and 2, respectively. Now, however, gate 9 has cube element 1 consistent with the assigned lines. Symmetrically, gates 10 and 11 are assigned cube elements 2 and 1, respectively. The algorithm now reaches the end of the gate proceeding order, and stops with all gates having consistent cube assignments as shown in Figure 2.7. The input vector (0,0,0,0) is

therefore a test vector for the fault, as required. This completes the example.

The circuit given in this section was developed by P. R. Schneider [25], and has the property that no single path of d's and $\bar{d}$'s is sufficient to detect the fault given. The algorithm, as just used, in fact, tried all possible ways of "sensitizing" the single path through gates 1, 2, 3, and 6, and finally applied the cube elements which produced two such paths simultaneously to produce a test vector.

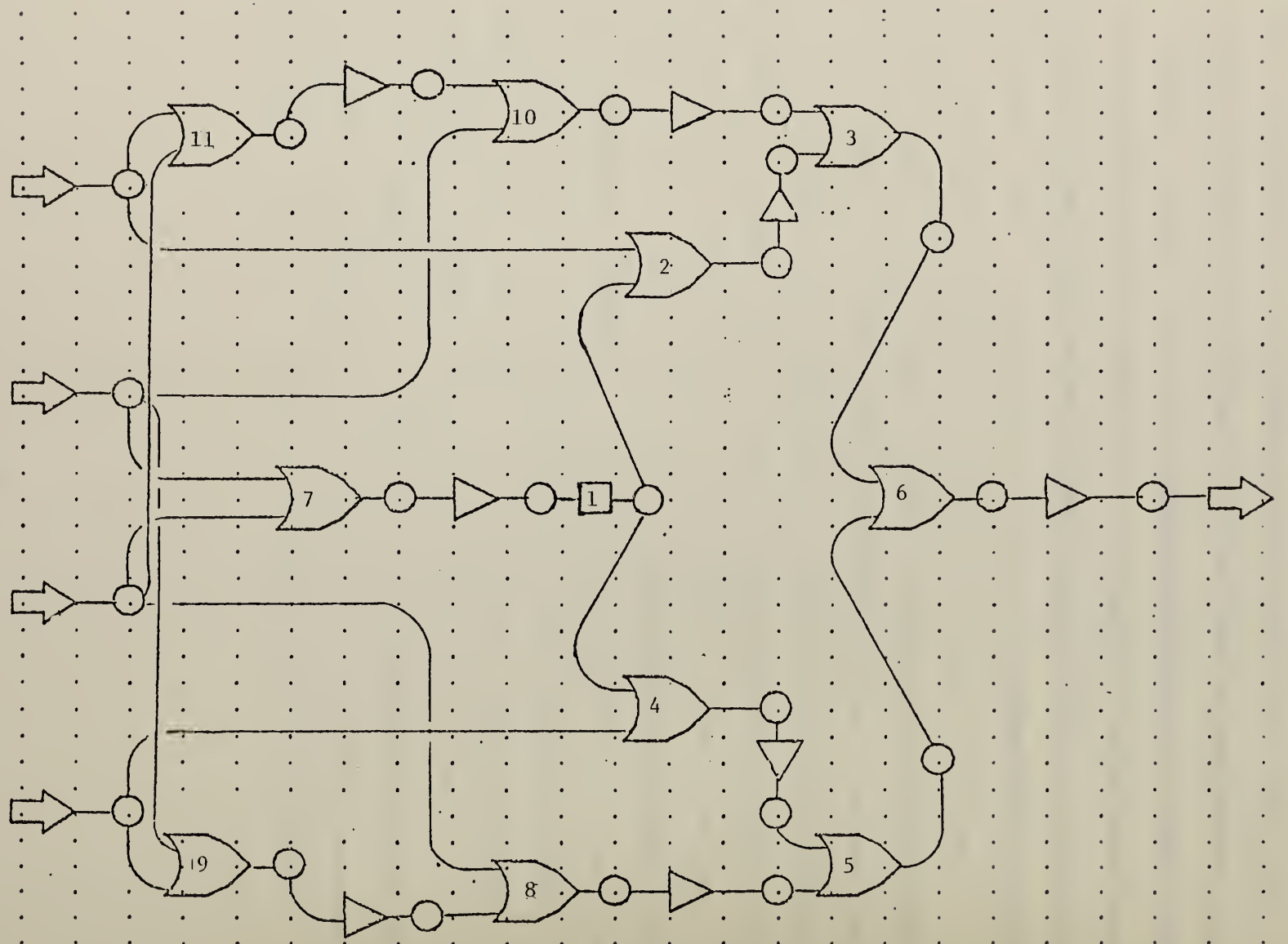

Figure 2.3: The Schneider example

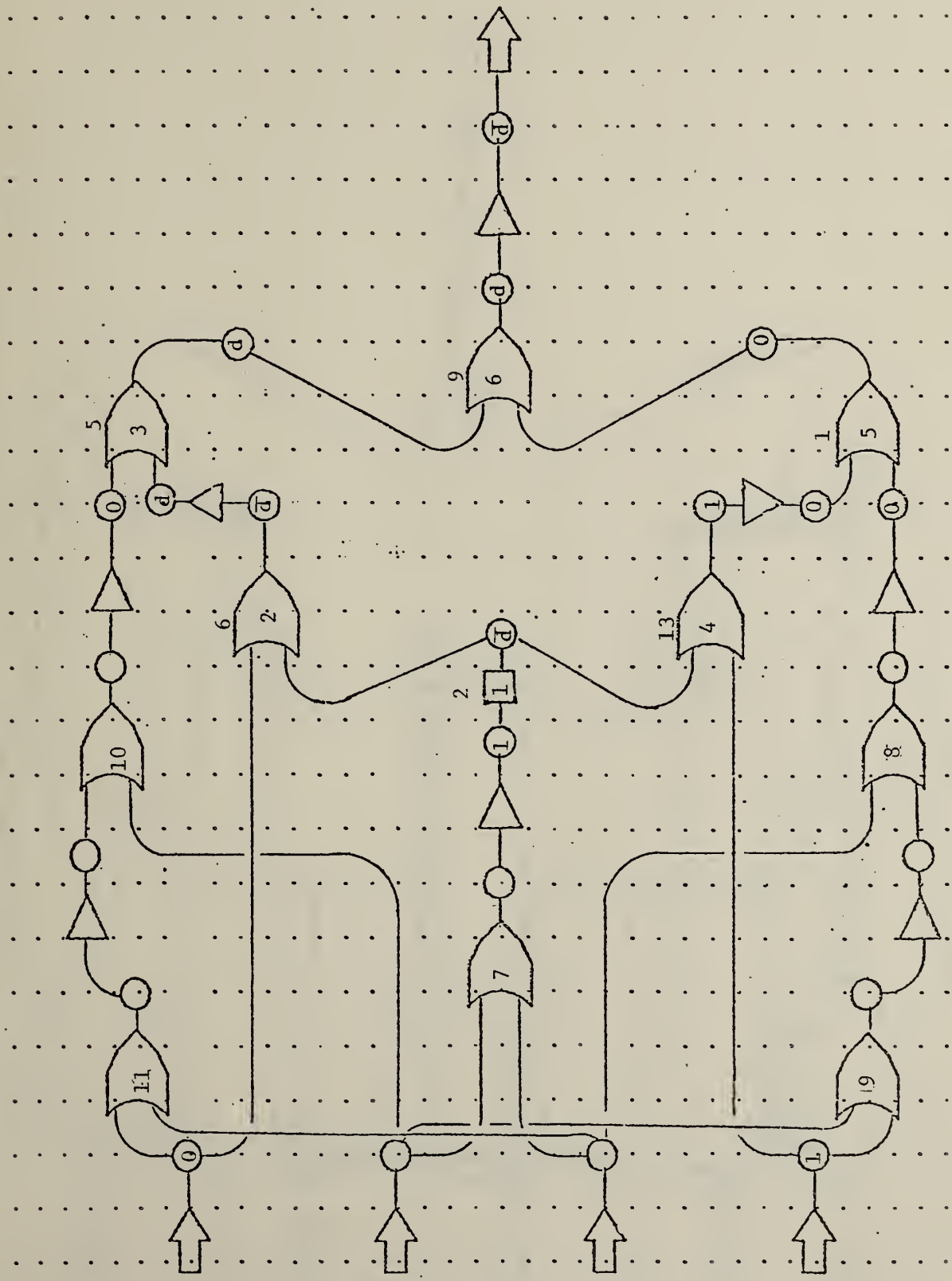

Figure 2.4

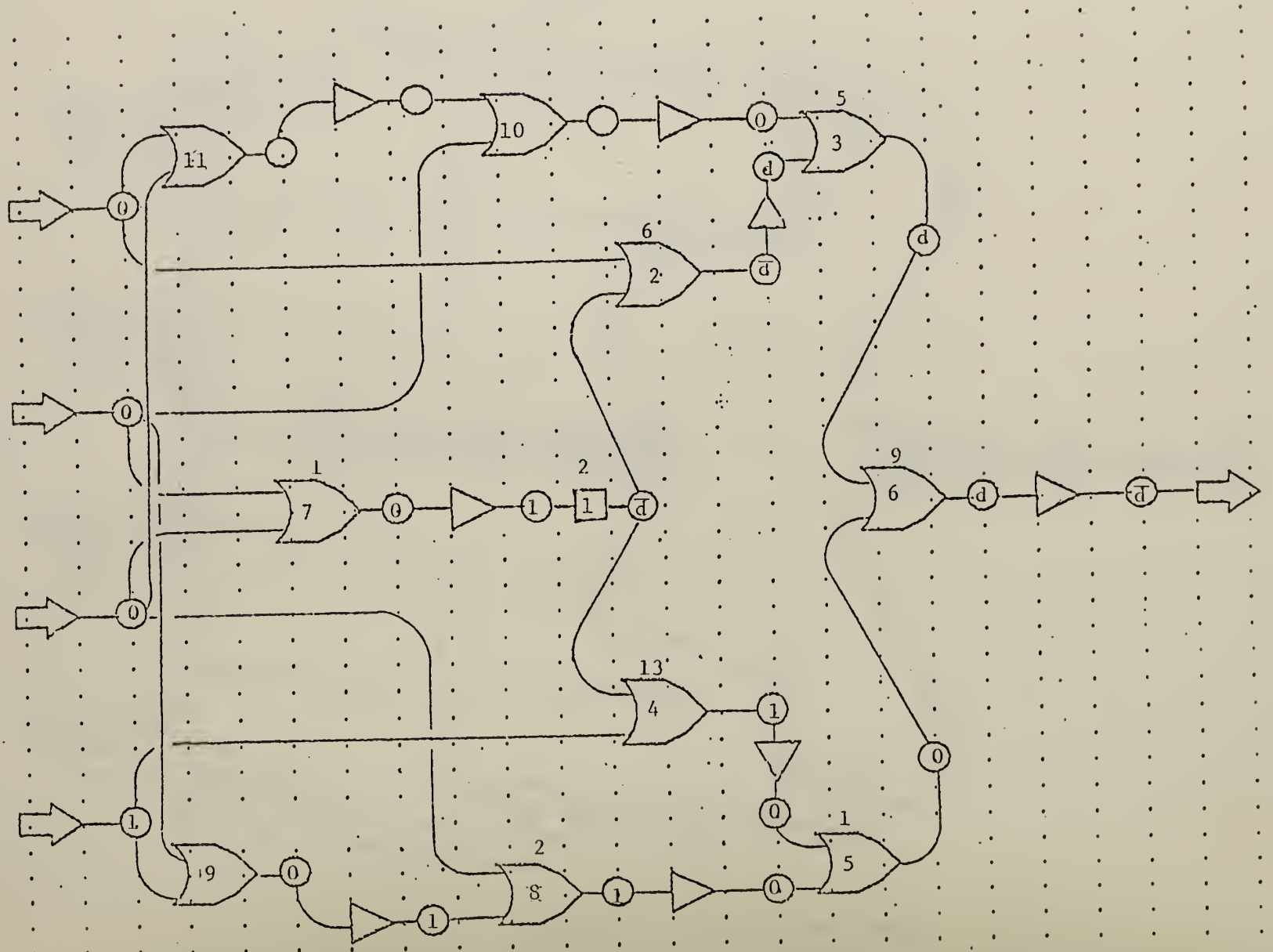

Figure 2:5

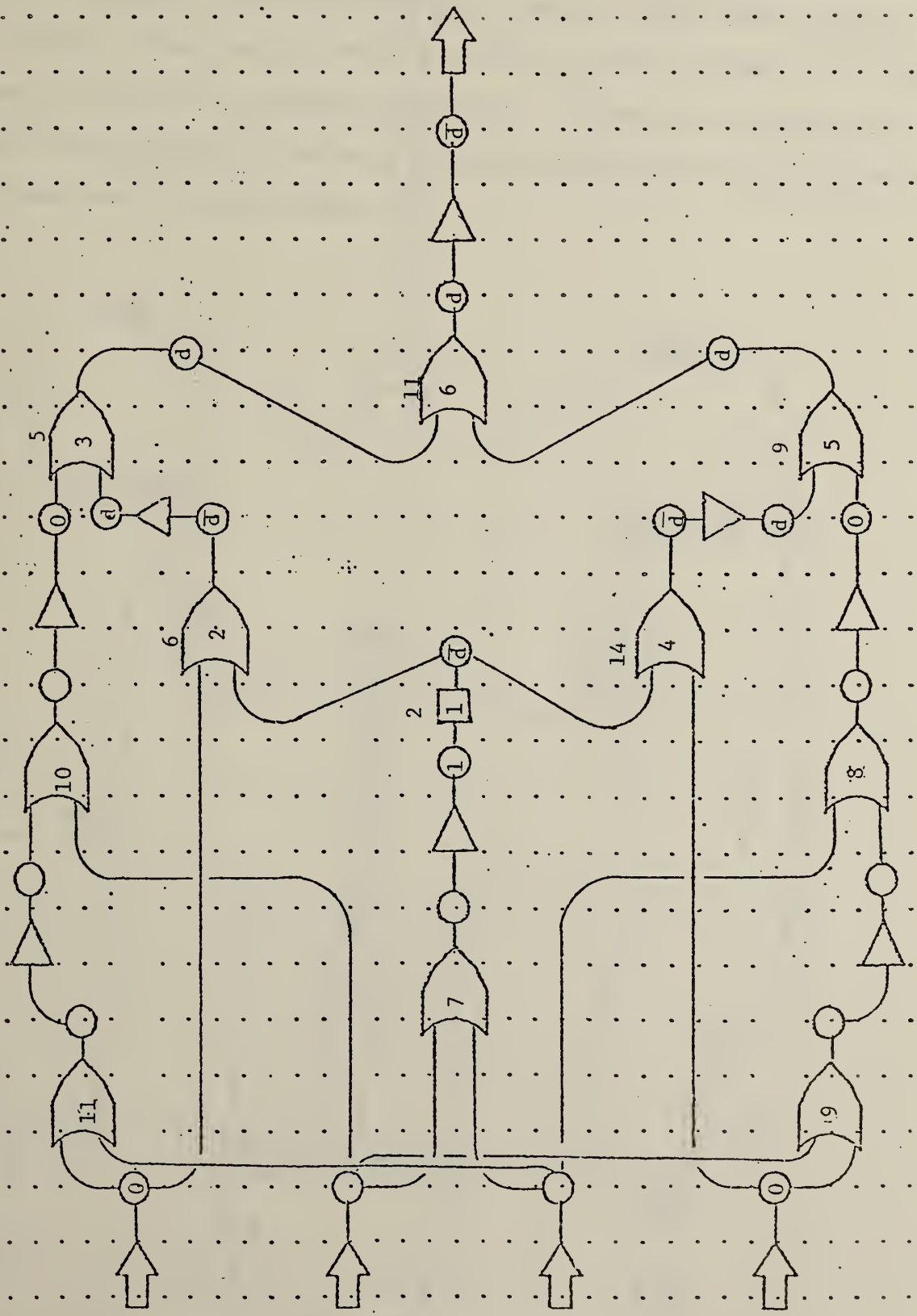

Figure 2.6

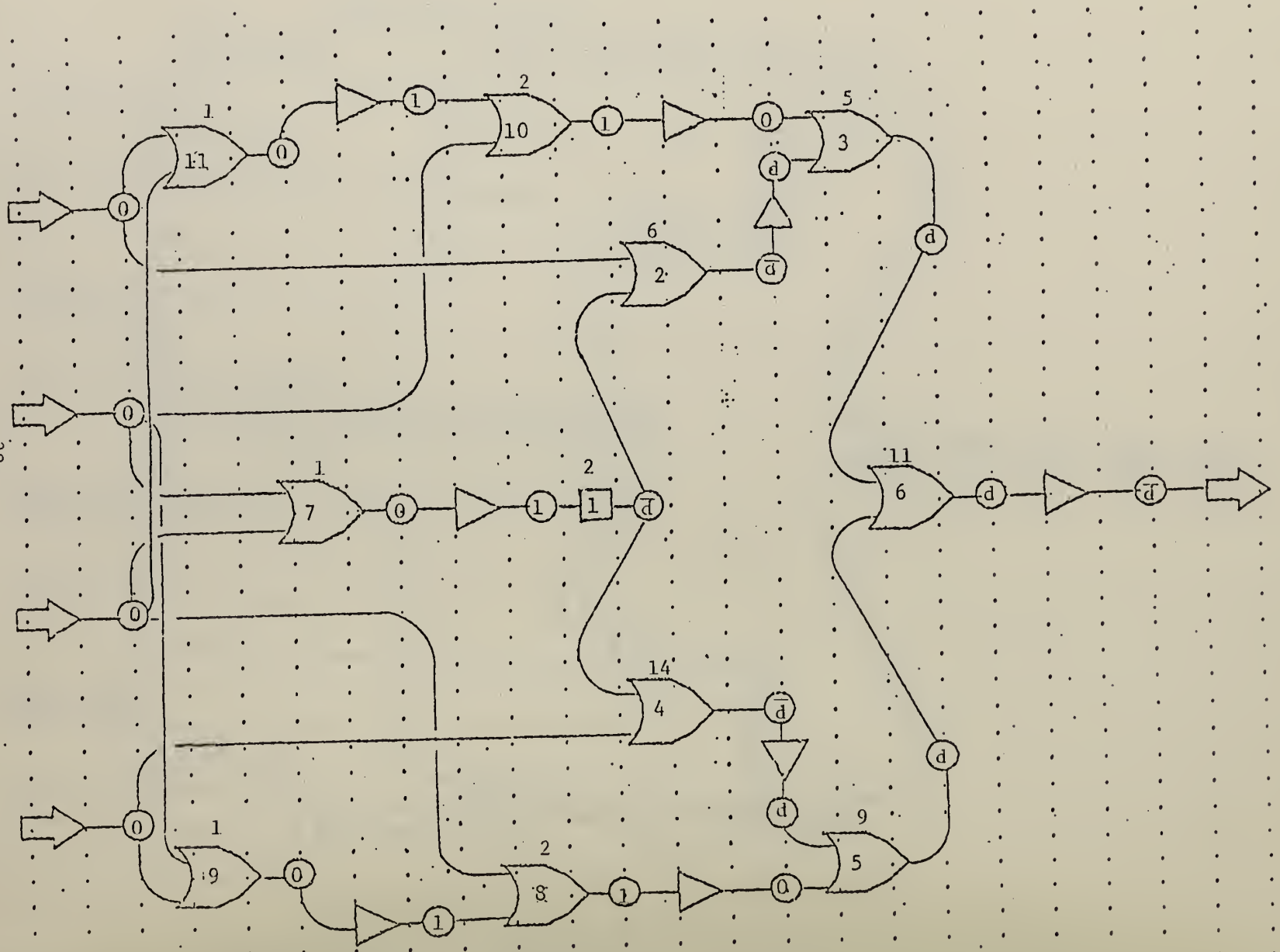

Figure 2.7

3. Generalizations of the d-Algorithm

We describe in this section some important ways in which the d-algorithm described in Section 2 can be generalized to handle a wider class of faults and circuits. Subsection 3.1 covers more general classes of faults, including cross-wire, inductive, and simultaneous faults. Subsection 3.2 covers more general cube descriptions, including abbreviated descriptions and empirical or operational descriptions of cubes.

3.1 Non-classical and Simultaneous Faults

We describe in this subsection three classes of faults — cross-wire faults, gate faults, and simultaneous faults — which are not treated by the standard d-algorithm, but which are of practical concern in circuit testing.

The standard cross-wire faults were described in Subsection 1.2. We can use that description to form cubes for cross-wire "and" and "or" gates as shown in Table 3.1:

Inputs		Outputs	
1	2	3	4
0	0	0	0
1	0	1	d
0	1	d	1
1	1	1	1

cross-wire "or"

Inputs		Outputs	
1	2	3	4
0	0	0	0
1	0	$\overline{d}$	0
0	1	0	$\overline{d}$
1	1	1	1

cross-wire "and"

Table 3.1: The cross-wire faults

A more general type of cross-wire fault frequently tested in circuits is the "inductive" type of fault, where one wire of a set of parallel wires changes signal if both of its neighbors are the opposite signal. A d-cube for a four wire fault is given in Table 3.2, listing only the non-trivial elements.

1----------5

2----------6

3----------7

4----------8

Inputs				Outputs			
1	2	3	4	5	6	7	8
Outputs equal corresponding Inputs							
except for the following elements:							
0	0	1	0	0	0	$\bar{d}$	0
0	1	0	0	0	$\bar{d}$	0	0
0	1	0	1	0	$\bar{d}$	d	1
1	0	1	0	1	d	$\bar{d}$	0
1	0	1	1	1	$\bar{d}$	1	1
1	1	0	1	1	1	$\bar{d}$	1

Figure 3.2: A four-wire "inductive" fault and its d-cube

Any number of other types of signal switching faults can be described using this same format.

A second type of fault which can be handled in the format of the generalized d-algorithm is the gate fault. This type of fault is useful when one is faced with circuits made up of complex gates whose faulty behavior may not be attributable to simpler faults. Here one must construct a fault cube for the entire gate which reflects the faulty behavior, and then substitute for the

gate cube this fault cube. For example, suppose that the 1-bit adder described in Table 2.1 was known to have as one of its more frequent faults the inclination to add 1 to 1 and produce outputs (0,0). It may not be clear what in the internal circuitry of the adder has produced such a fault. It is nevertheless easy to describe the fault succinctly, as is done in Table 3.3.

Inputs		Outputs	
1	2	3	4
0	0	0	0
1	0	1	0
0	1	0	1
1	1	$\overline{d}$	0

Table 3.3: The cube for a faulty "1-bit adder"

By simply replacing this cube for that of the standard logic cube shown in Table 2.1 we can incorporate the fault into any "1-bit adder" type gate which might be suspected of having this type of fault.

The final type of fault is the simultaneous fault. This is mentioned frequently in the literature as a type of fault which is difficult to incorporate into test generation algorithms. In the context of a backtracking algorithm, however, simultaneous faults can be tested with only slight modification. A simultaneous fault is actually a set of faults which occur simultaneously at various locations of the circuit. It is important to distinguish this composite fault from the individual faults themselves since a test vector for a simultaneous fault distinguishes the case when all of these

faults occur from the case where none of the faults occur. Simultaneous faults are likely to occur in equipment which is being used for the first time or which has been assembled by hand (properties frequently true of the prototype instruments developed at the Bureau of Standards), and should be available as a consideration when the circuit is malfunctioning and single fault tests fail to detect the fault.

Each single fault of the simultaneous set is furnished with the appropriate fault cube just as shown in Section 2 and this subsection. The d and $\overline{d}$ signals, moreover, represent this same situation for all of the fault gates, that is, under normal operation the lines assigned d have value 0 and those assigned $\overline{d}$ have value 1 for <u>every</u> fault gate in the simultaneous set, whereas in fault mode operation, the lines asssigned d have value 1 and those assigned $\overline{d}$ have value 0 for <u>every</u> fault gate in the set. With the possibility of faults now occurring in tandem, it is necessary to modify the fault cubes for any fault gate whose input might be affected by another fault in the simultaneous set. This is done by extending the fault cube to allow d and $\overline{d}$ inputs, and is again accomplished by a simple argument of the sort "if the faults occur,..." and "if the faults do not occur,...." We can modify, for example, the cross-wire "or" fault to allow d and $\overline{d}$ inputs as indicated in Table 3.4.

	Inputs		Outputs	
	1	2	3	4
1.	0	0	0	0
2.	0	1	d	1
3.	1	0	1	d
4.	1	1	1	1
5.	0	d	d	d
6.	0	$\overline{d}$	0	$\overline{d}$
7.	1	d	1	d
8.	1	$\overline{d}$	1	1
9.	d	0	d	d
10.	d	1	d	1
11.	d	d	d	d
12.	d	$\overline{d}$	d	1
13.	$\overline{d}$	0	$\overline{d}$	0
14.	$\overline{d}$	1	1	1
15.	$\overline{d}$	d	1	d
16.	$\overline{d}$	$\overline{d}$	$\overline{d}$	$\overline{d}$

Table 3.4: A full d-cube for the cross-wire "or" fault

Consider the element whose inputs are d and $\overline{d}$. Under normal operation the inputs would be (0, 1). These would be passed through normally to the outputs, which would therefore also be (0, 1). In the fault mode, however, the inputs would be (1,0), which would then be altered by the simultaneous

cross-wire fault to the common outputs (1, 1). The output values for this element are therefore (d, 1), obtained by comparing the outputs obtained under each operating mode. Notice now that a partial cancellation has occurred, the cross-wire fault countermanding the previous fault. This effect is even more apparent in the cube element whose inputs are (1, $\bar{d}$), where a complete cancellation occurs in the outputs (1, 1). It is this kind of cancellation which causes single fault tests to fail in some instances to detect those faults in the presence of other faults, and indicates the need for simultaneous fault capabilities.

To handle simultaneous faults we must also be more careful in specifying gate ordering for the backtrack algorithm in the presence of simultaneous faults. In particular, we must insure that the first fault gates processed are those gates which have no fault gates preceding them in the circuit. Call these minimal fault gates. The ordering restriction (3) of Subsection 2.3 must now be modified to read

3'. In the propagation stage, no gate is processed unless it is a minimal fault pseudogate or until at least one gate (or pseudogate) immediately preceding that gate has been processed.

Now with the modification of the fault-cubes described above, all fault gates encountered later are processed as if they were normal gates. We must also modify the propagation rule of Subsection 2.3 to allow propagation from any fault gate. The modified rule is:

Propagation Rule': After all fault pseudogates are processed, at least one leading line must have the value d or $\bar{d}$.

With these modifications the d-algorithm can do a complete analysis of a simultaneous fault condition, and will always produce a test vector if one exists.

3.2 Finding Faults Detected by a Given Test

Up to now, we have been dealing primarily with finding a test vector to detect a given fault. The procedure given in the Subsection 3.1 provides an interesting and efficient method for doing the converse, namely, determining which faults are detected by a given test. In testing circuits, one is more often interested in how broad a class of faults can be detected by a set of test vectors rather than what test will detect a single fault. We give now a quick method which determines, given a set of input vector and a fault, whether the vector tests this particular fault. Since the procedure is so efficient, it can be used effectively to test a large set of faults in turn against a given input vector, and consequently to obtain a sense of the "fault coverage" of that input vector.

The procedure works as follows. For a given input vector and fault (single or simultaneous), associate a simultaneous fault which consists of the given fault, along with a set of input-set-to faults. These "faults" occur at the input gates, but their cube is comprised of a single element whose output value is the desired value of the input. Thus they do not contribute a d or $\bar{d}$ to the system, but instead merely set the input line to its appropriate value. Since the input gates are considered to be fault gates, however, the d-algorithm will always process these gates first. From this point on, the elements of the rest of the gates--including the fault pseudo-gates--are determined uniquely. Therefore in one pass through the gates (entirely in the

propagation stage) the algorithm determines whether a d or $\bar{d}$ appears at an output, i.e., whether the given input values detect the given fault.

The fault testing procedure given above is easily implemented within the context of the d-algorithm as presented. It is part of the FORTRAN Code developed, and is illustrated in Section 5.

3.3 Generalized Cubes

There are three special techniques for constructing and modifying cubes which can improve both the applicability and the efficiency of the d-algorithm. The first technique is the use of extra symbols to denote "unassigned" line values. These allow, when possible, the delaying of assignments of values to certain non-critical lines until later in the backtrack, so that greater freedom can be exercised in choosing values when the lines become critical. The use of this technique in the d-algorithm can improve efficiency substantially. The second technique is the use of empirical rather then logical descriptions of gates to construct d-cubes for those gates. This allows not only the capability of describing circuits on a variety of levels, but also permits the limiting of gate operation to reflect the environment in which the gate or circuit is used which again yield an improvement in efficiency of the algorithm. The final technique is a fast cube search and element retrieval, based on a compressed data structure for storing the d-cube. This final improvement we leave until Section 4, since it is essentially an implementational rather then algorithmic feature.

As mentioned in Subsection 2.1, one of the most critical feature of a backtrack algorithm is the number of elements in each of the decision lists, since a complete backtrack sequence considers a number of decision configurations equal to the product of the length of the individual decision lists. One way to decrease the number of elements in a d-cube is to combine several elements into one. This is accomplished by using line values which represent a delayed non-assignment for that line. The simplest

example of this, and one which we have incorporated into the code, is based on the fact that an "or" gate which has one of its inputs assigned the value 1 will always have its output assigned value 1 regardless of the other input. Thus if we assign a 1 to either of the inputs, we can process many of the succeeding gates without knowing immediately the value of the other input. We therefore give the other input an "unassigned" value, say -1, which is changed to a value of 0, 1, d, or $\overline{d}$ only when necessary later in the backtrack. This decreases the size of the d-cube for that "or" gate from sixteen elements to eleven as shown in Table 3.5:

Inputs		Outputs
-1	1	1
1	-1	1
0	0	0
0	d	d
0	$\overline{d}$	$\overline{d}$
d	0	d
d	d	d
d	$\overline{d}$	1
$\overline{d}$	0	$\overline{d}$
$\overline{d}$	d	1
$\overline{d}$	$\overline{d}$	$\overline{d}$

-1 = unassigned

Table 3.5: A reduced d-cube for the "or" gate

The -1 value assigned to the input line is reassigned when the output of the gate preceding that line is finally assigned. A further, and more elaborate, reduction can be made by assigning "partially unassigned" values to gates. These are assignments to a certain subset of inputs and outputs which are left unassigned, but for which an assignment of a value for one line will dictate the values assigned to every other line in that subset. Again, taking the "or" gate as an example, suppose a value of 0 is assigned to one of the inputs to that gate. Now the output will always have a value equal to that of the other input, regardless of what value is given to that input. We can therefore leave the values of these two lines unassigned with the restriction that they must be given equal values when they are finally assigned. The d-cube now needs only seven elements as shown in Table 3.6:

Inputs		Outputs
0	-1	-1
1	-1	1
-1	0	-1
-1	1	1
-1	-1	-1
d	$\bar{d}$	1
$\bar{d}$	d	1

All lines assigned -1 must be given the same value

Table 3.6: A further reduced d-cube for the "or" gate

We can also handle the case where a pair of lines must have opposite values. The "not" gate for example always has as its output the complement of the input, 1 and 0 being complements of each other, and d and $\bar{d}$ being complements of each other. We can therefore leave the input and output of this gate unassigned with the restriction that they must be given complementary values when they are finally assigned. We can use the symbols two symbols -1 and -2 to represent this condition in the d-cube, by requiring that each line with a -1 in the cube must be given the same value when they are assigned, and each line with -2 in the cube must be given the complementary value to those with -1. Using this convention, we reduce the "not" d-cube to exactly one element, as shown in Table 3.7:

Input	Output
-1	-2

Table 3.7: A reduced cube for the "not" gate

By careful manipulation of these complementary unassigned symbols we can make substantial reductions in the size of more complex gates. Table 3.8 gives complete d-cubes for the "or" and "1-bit adder" gates, both of which have only six elements.

Inputs		Outputs
1	2	3
0	-1	-1
1	-1	1
-1	0	-1
-1	1	1
-1	-1	-1
-1	-2	1

"or"

Inputs		Outputs	
1	2	3	4
0	-1	0	-1
1	-1	-1	-2
-1	0	-1	0
-1	1	-1	-2
-1	-1	-1	0
-1	-2	0	1

"1-bit adder"

Table 3.8: Reduced cubes for the "or" and "1-bit adder" gates

The backtrack algorithm needs only to keep track of each set of unassigned lines whose elements must take the same value along with the complementary set whose elements must take the complementary value, merging sets if necessary when a common element occurs in both sets. It assigns all of the lines in a pair of complementary sets simultaneously whenever any one line is given a value, and backtracks when it detects inconsistencies occurring when two lines from the same set are assigned complementary values, or when lines in complementary sets are assigned the same value. Although the necessary structures to maintain this are fairly simple, we dispense with the details in this report, as it is not operational in the current version of the code.

The final part of this subsection will be spent describing the ways in which cubes can be constructed using empirical data on gate operation. Not only can this allow more general gate types to be developed, but it can also provide the user with a method of directing the search for test vectors by restricting gate operation according to his perception of the operation of the circuit.

Suppose, for example, it is desired to test a circuit which contains a 4-bit adder, whose eight inputs comprise two 4-bit numbers, and whose output is their 5-bit sum. A full non-reduced d-cube for this adder would require 4^8 = 65,536 elements. Although it may be feasible to store this many elements, it is unlikely that the d-algorithm would be practical on a circuit containing many 4-bit adder type gates. What a user of the d-algorithm needs to do in this situation is to review the environment in which the adder is used and choose a subset of elements which are most likely to occur in the operation of the circuit. Thus, he might conclude that numbers greater than 4 are unlikely to be processed by certain of these adders, or that the numbers processed by some adders are always in multiples of 4, thereby allowing him in either case to decrease cube size to 4^4 = 256 elements. He may have gates of which he does not have or does not desire to obtain complete information, and therefore may be reduced to describing only a limited operation of the cube. Again, simply by listing those elements for which he has some knowledge, or which are critical to circuit operation, he thereby obtains a limited but accurate operating description for that gate.

Restricted gate descriptions have the further property that they can be used to determine certain faults to be "non-critical" in the operational environment of a circuit. Consider, for example, the 1-bit adder whose gate configuration is shown in Figure 1.1 and for which it is desired to find a test vector to detect a stuck-at-1 fault in the line between the "or" gate and its succeeding "and" gate. If it is known that the first input gate of this circuit is always set to 1 when the circuit is in normal operation, then the

stuck-at-fault given above is undetectable, since it can never be given a 0 input. Such a fault is therefore not necessary to test in order to declare the circuit fault free, since the situation under which the fault is critical never arises.

The use of restricted cubes, it can be seen, allows a potentially rewarding dialogue between the designer of a circuit and the tester of that circuit. With the designer's knowledge of the operating environment and characteristics of the circuit, and the tester's knowledge of the operation of the d-algorithm, a battery of tests can be built for a circuit which efficiently and effectively demonstrates both the design integrity and the operating capabilities of that circuit.

4. Implementation of the d-Algorithm

This section presents the techniques which can be employed in implementing the d-algorithm in order to improve its efficiency. Subsection 4.1 outlines the ordering schemes which were used to process gates in the backtrack algorithm, along with the advantages and disadvantages of each. Subsection 4.2 deals with a method of coalescing gates into components, allowing for efficient use of repeated gate groupings. Subsection 4.3 gives a specific data structure for cubes which improves cube searches and at the same time reduces storage requirements.

A FORTRAN code which incorporates many of the implementation ideas given in this Section, and has, as well, the capabilities of generalization given in the previous section. A listing of the code is available from the authors. The code is capable of handling general fault and gate cubes, as well as simultaneous faults. It can test an input to find detectable faults (Subsection 3.2), form components (Subsection 4.2) and run several orders of gate ordering for the backtrack. One has to note, however, that many of these capabilities involve changes or additions in the code itself, since they are too cumbersome and confusing to be effective as a user option. The specific user capabilities are outlined in the appendix. It is virtually impossible to use many of the features of the generalized d-algorithms, however, without a firm knowledge of the concepts underlying these generalizations, and many of these could not be included as standard

specifications of the code. What was not incorporated in the present form of the code was any sequential capabilities, of the more elaborate reduced cube schemes (Subsection 3.3), and the compressed data structure (Subsection 4.3). These are left for future development.

4.1 Ordering Schemes for Gate Processing

The restrictions given in Section 2 for the order in which the d-algorithm processes gates still allows a great deal of flexibility in gate ordering. We give four schemes for gate processing which have different effects on the flow of the d-algorithm. They are called the depth-first ordering, the breadth-first ordering, the restricted depth-first ordering, and the restricted breadth-first ordering. They all follow the basic ordering rules given in Subsection 2.3, namely, processing first fault gates, then gates forward of fault gates, and finally gates behind fault gates, and never processing a gate until the appropriate adjacent gate is processed. To do this, a general search procedure requires the maintenance of two lists, the propagation elgibility list (PEL) and the justification elegibility list (JEL), which contain gates elegible in the respective phase according to the restrictions given in Subsection 2.3. Both lists are initially empty, and the general search procedure is as follows.

(1) Place the fault gate (or minimal fault gates) on PEL.

Propagation stage--while PEL is nonempty, perform the following:

(2) Choose a gate G from PEL and process that gate.

(3) Place into PEL all unprocessed gates that are on an output line of G and place into JEL all unprocessed gates that are on an input line of G.

(4) Mark G processed, and delete it from PEL.

When PEL is empty, the propagation stage is completed, and the justification stage begins.

Justification stage--while JEL is nonempty, perform (2'), (3'), and (4') on JEL:

2' Choose a gate G from JEL and process that gate.

3' Place into JEL all unprocessed gates that are on an input line of G.

4' Mark G processed and delete it from JEL.

When JEL is empty the justification stage is complete.

Any ordering which follows the above general format satisifies the basic requirements of gate ordering in the d-algorithm. The details of how to place and remove elements from PEL and JEL are what differentiate the four ordering schemes given above. The ordering schemes are:

Depth-first search - gates are inserted and removed from the top of the lists (LIFO list maintenance).

Breadth-first search - gates are inserted at the bottom of the lists and removed from the top of the lists (FIFO list maintenance).

Restricted breadth-first and depth-first search:

Propagation stage - The gate processed is the topmost gate in PEL for which all input lines coming from propagation stage gates have been assigned values.

Justification stage - The gate processed is the topmost gate in JEL for which all output lines going to justification phase gates have been assigned values.

Roughly speaking, depth-first search attempts to assign values to the outputs (or inputs) as fast as possible, whereas breadth first search keeps as broad a base as possible in which to choose new adjacent gates. Restricted search is a modification which holds processing of a gate until all lines on "one side" of the the gate are either assigned values or will never be assigned in that phase. Thus it could be considered a "local breadth-first search" rule.

Restricted searches also allow for a quicker search of the d-cube, since the data can often be keyed to input or to output values (see Subsection 3.3). It is a non-trivial fact that, in any circuit without feedback, there is always a way of ordering the gates so that a restricted search is possible.

The algorithm as coded is capable of using any of these four search procedures given. We have found thus far that the most efficient option is to use nonrestricted depth first search in the propagation stage and restricted breadth first search in the justification stage. The reasoning for this option is that in the propagation stage the most important goal is to drive a d or $\bar{d}$ to the outputs, hence to employ an unrestricted depth-first search, whereas in the justification stage the most important goal is to maintain logical consistency, hence to employ a restricted breadth first search. Some limited testing seems to bear out this option.

4.2 Component Formation

VLSI's today tend to be made up of components, that is, devices which are used as single units but which comprise internally a system of simpler logical gates, that is, "circuits-within-circuits." There may be many identical components in a circuit, and therefore some initial pre-processing of these components can save time when the algorithm must repeatedly process identical components. The preprocessing performed consists of producing a d-cube for the set of gates in the component so as to treat that component as a single gate. The algorithm then removes the gate system and replaces it by the newly created component/gate.

Creating the d-cube associated with a component involves a complete enumeration of all the possible input vectors and determining the output vector of the component for each of these input vectors. The method of determining the output values for a specific input vector is essentially that of applying the d-algorithm to a smaller circuit with input gates set to the appropriate values. Since cube construction requires only the forward propagation drive mechanism, the algorithm for determining logic cube values can be made faster than the general d-algorithm.

Restrictions on the use of components in place of gate systems are the following:

1. All gates in the component must be contiguous, that is must form a connected set of gates within the circuit.

2. The ordering of gates in a component must be consistent with all other components of the same type.

3. Faults may not be contained in any one of the listed components.

Because of restriction 3, separate consideration of a fault within an individual component necessitates removal of that component from the list, and treating it separately. The main advantage of component formation is the reduction in number of backtracks the algorithm must performs before locating a fault finding test vector. Having determined the internal logic of the component once, the algorithm is not required to re-discover the logic upon encountering each component. Component formation also illustrates the important "macro" capabilities available for the d-algorithm as generalized in this paper. Using component formation, together with the restricted cubes outlined in Subsection 3.2, cubes for large components can be constructed which enable the d-algorithm to find test-vectors more efficiently when large components are being used in quantity.

4.3 Data Structures for d-Cubes

The most expensive structure to maintain and process in the d-algorithm is the d-cube itself. For a reasonably complex gate the cube may be enormous, and the cost in both storing and retrieving data for the cube is a big consideration in constructing the code for the d-algorithm. One method which can save both storage and retrieval time is to "pack" the input and output data each into a single integer element. In particular, if we represent 0, 1, d, and $\overline{d}$, respectively, as 00, 01, 10, 11 (in binary), then the input and output values can each be represented by a single integer comprised of the concatenation of the individual values. The d-cube is then stored as a single-valued array, whose index number is the integer corresponding to the input values and whose value is the integer corresponding to the output values. As an example, the full d-cube for the cross-wire "or" fault can be derived directly from Table 3.4 and is shown in Table 4.1.

Input	Output	Input	Output	Input	Output	Input	Output
1. 0	0	3. 4	7	9. 8	10	13. 12	6
2. 1	13	4. 5	5	10. 9	9	14. 13	5
5. 2	10	7. 6	6	11. 10	10	15. 14	6
6. 3	3	8. 7	5	12. 11	9	16. 15	15

Table 4.1: Storing the d-cube for the cross-wire "or" fault

The inputs ($\overline{d}$, 1) for instance, correspond to the integer 1101 = 13, and the corresponding output integer 5 = 0101 corresponds to the outputs (1, 1).

If stored as the four line values indexed by the cube element number, the d-cube for this gate would take 16 x 4 = 64 words of storage. By using the "packed" scheme, we have reduced the storage to an array of only 16 elements. Furthermore, the time taken for a cube search can decrease dramatically when some of the inputs are already known. For example, if the gate given above, when processed had its second input already assigned d = 10, then the search indices reduce to 4i + 2 for i = 1, 2, 3, 4, that is, 2, 6, 10, and 14. Rather than scanning each element of the cube until a match is found, the algorithm can now reference the above four indices directly, thus reducing the number of search calls four-fold.

For retrieval purposes, this packed format works best in the propagation stage, when one or more inputs have been assigned values. It is especially fast when restricted search is employed, since now most of the gates processed have all of their inputs assigned values, and as a result the packed array is only referenced once. One can think of reordering the cube so that cube elements can be retrieved by their output values instead of their input values. This would work particularly well in the justification stage, where one or more output values have been assigned values when the gate is processed. Unfortunately, an output value may correspond to more than one input value.

To employ the search technique described above, it would be necessary to group the inputs which correspond to a given output and have the output integer reference this list. The resulting data structures would be somewhat more cumbersome, but could still save time over a sequential cube search. The compressed data structure was not incorporated into the current code.

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Appendix: Code and Sample Output

The d-algorithm was implemented on the UNIVAC 1108 in ANSI FORTRAN77.* The capabilities of the compiled code are documented in the program text. The code processes nine gate types (AND, OR, NOT, NAND, NOR, exclusive OR as well as input gates, output gates, and dummy gates), four fault types (stuck-at and cross-wire faults) and the input setting feature (Subsection 3.2). It can form components from a given set of gates, creating a new cube and replacing the component gates with the component in the circuit. The user can specify the number of test vectors to be found for a given fault. Also included are two parameters specifying the minimum number of leading lines which are allowed to have the values d or $\bar{d}$ (called sensitized paths in the code). These allow the user to test a circuit just constructed by setting the inputs and observing the resulting outputs for correct logic, or to find which faults are detected by a particular test vector (Subsection 3.2). In any case it may be desired to have only logical circuit values, and so the minimum number of sensitized paths could be zero. Setting an upper limit on the number of sensitized paths permits the algorithm to act as a path sensitization algorithm (Subsection 1.3) or otherwise limits the extent to which faults are propogated through the system.

There are also several parameters in the program which can easily be reset to broaden the capabilities of the algorithm. The algorithm has a DEBUG flag, which when set allows the user to see each step of the backtrack. The number

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* The sole exception was the use of in-line comments in the parameter and declaration statement.

and size of gates can be changed, and new gates can be inserted by developing the cube and putting it into the program in the format specified. The algorithm currently uses restricted depth first gate orderings in the propogation stage and restricted breadth-first ordering in the justification stage, but these can also be changed by reordering the appropriate indices.

The output streams for six test runs appear in this Appendix. These runs illustrate the narrow features of the code. They were all performed on the arithmetic logic unit circuit shown in Figure A.1. It is made up of NOT, AND, NAND, and NOR gates as indicated. The multi-input gates were decomposed into the appropriate 2-input gates. Then faults were treated in the runs, and they are indicated in the figure. Faults #1 and #2 are stuck-at-0 faults, and Fault #3 is a cross-wire AND fault. The first three runs found several tests each for Fault #1, using three levels of component formation: Run #1 had no components formed, Run #2 had the sets of circled gates in the figure coalesced into a component, and Run #3 had the set of circled and squared gates in the figure coalesced into components. The amount of time needed to form components is indicated (in milliseconds) at the top of each run. Component formation was limited primarily by the size of the d-cube which had to be produced, and larger component formation will probably have to be accompanied by a substantial paring of the d-cube by the user (Subsection 3.3). A very surprising phenomena is that the cube formation implementd in this algorithm actually slows down the backtrack, as indicated by the TIME FOR COMPUTATION which accompanies the output (also in milliseconds). This is probably due to the increase in time for searching the very large cubes produced, and also to the loss of control of the internal gates of the cube.

If component formation is to speed up the backtrack, then more sophisticated search mechanisms will have to be employed. Note that after the first test vector was found, finding additional test vectors is very inexpensive. Run #4 tested the input found in Run #1 against Fault #1. This shows the checking capabilities of the code (Subsection 3.2). Notice the time to check a test is in hundredths of a second, as opposed to several seconds to find a test.

Runs #5 and #6 show the simultaneous fault capabilities of the code. A run was first made for Fault #2 alone, and the test vector and resulting line values are shown in Figure A-2. When Fault #3 is also present the input vector shown will detect neither fault, for the cross-wire fault nullifies the stuck-at fault. When the program was run on the two faults simultaneously, however, a new input is produced which does in fact test the fault, and the resulting line values are shown in Figure A-3.

One final note about the testing of the code. The d-algorithm, due to its inherent intractibility, can perform very badly even on a circuit such as the one tested. An example is the seven-fold jump in computation time between the single and simultaneous faults in Runs #5 and #6. There were, moreover, faults tested on this circuit which would not yield test vectors in the CPU time alloted (usually 5 to 10 minutes). Thus it is difficult to make statements of the efficiency of a program such as this, and also indicates that substantial improvements can be made in running times by adding good heuristics to the algorithm.

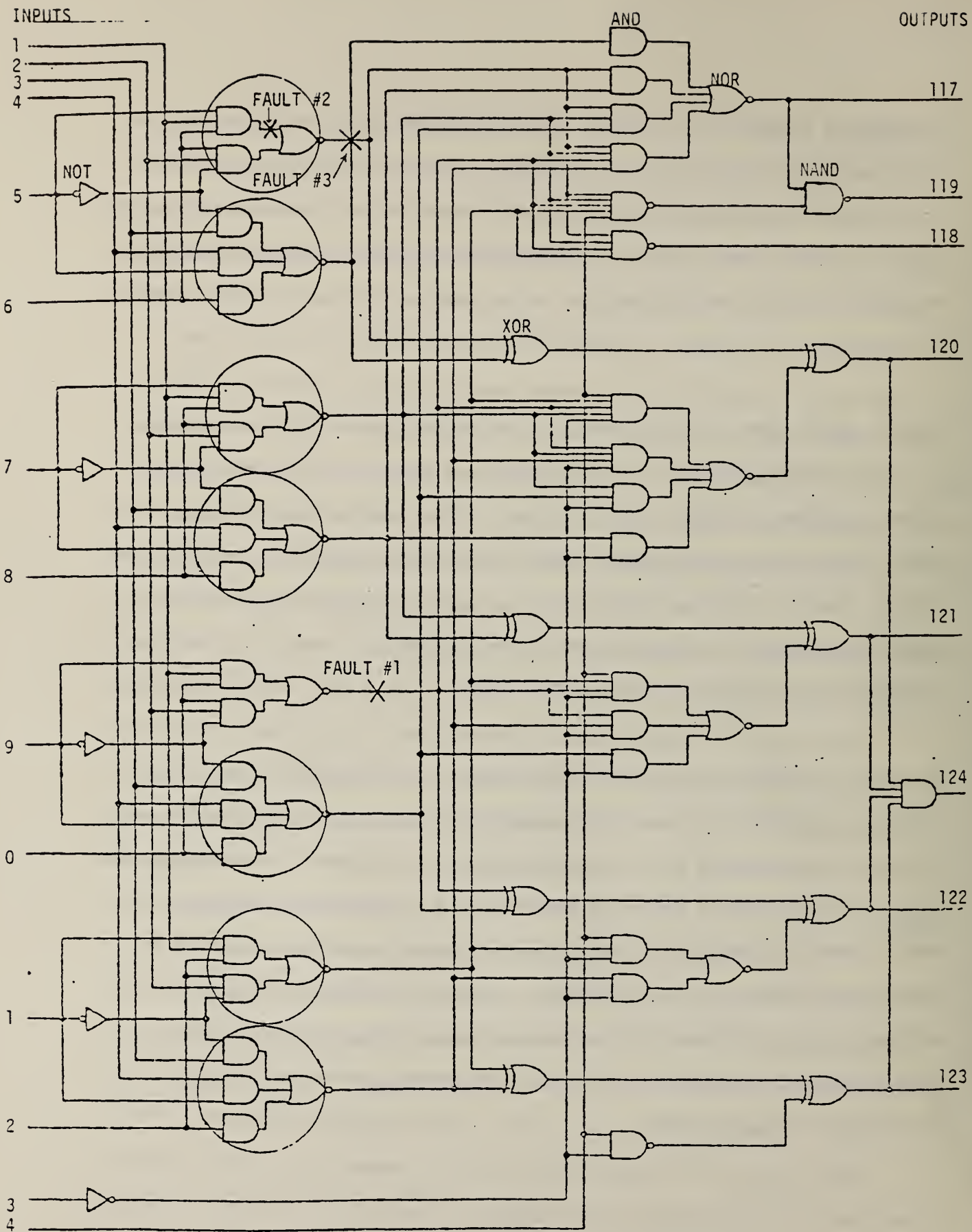

Figure A.1: Test circuit (from The TTL Data Book, Texas Instruments, 1973, p. 390)

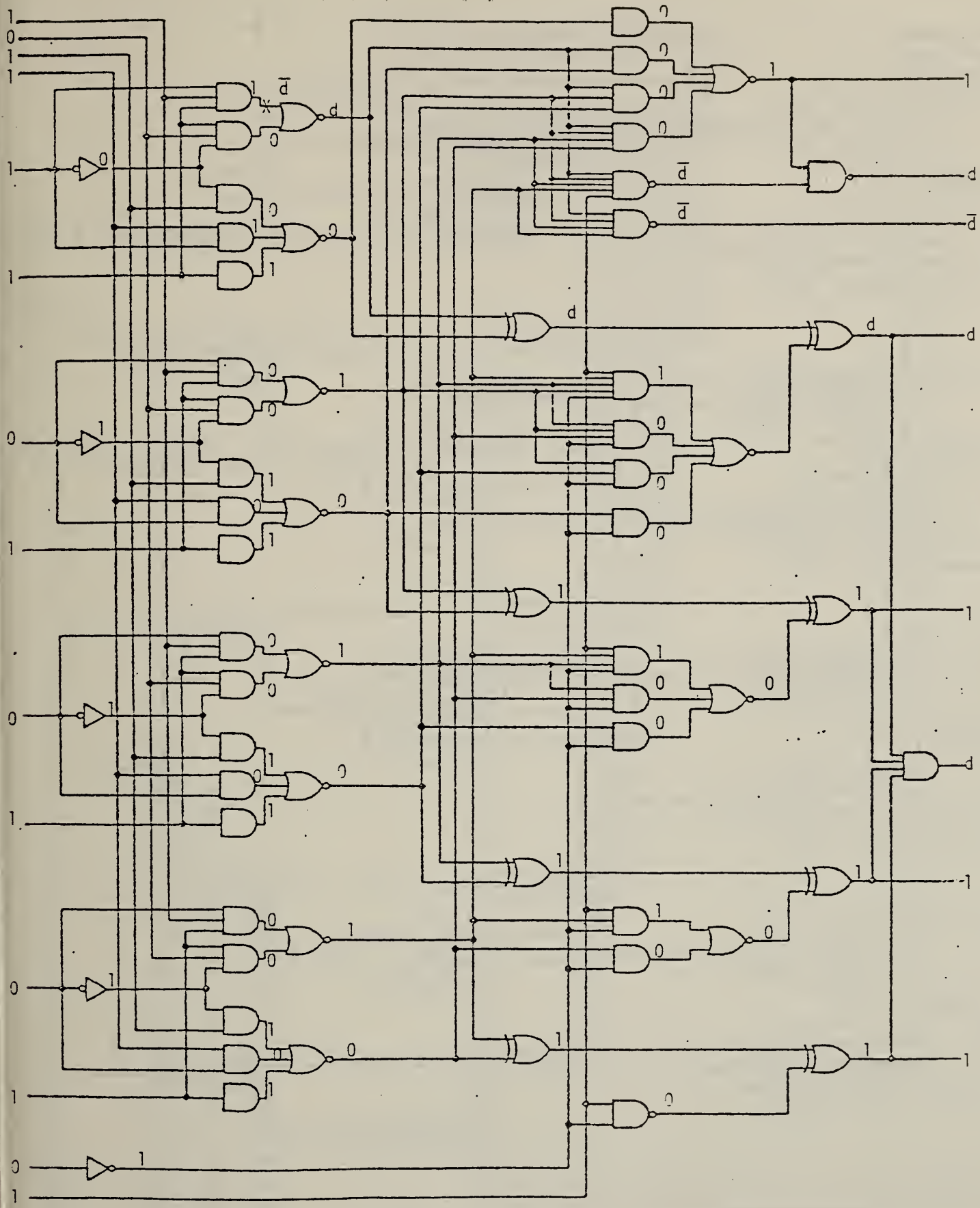

Figure A.2: Single fault test vector

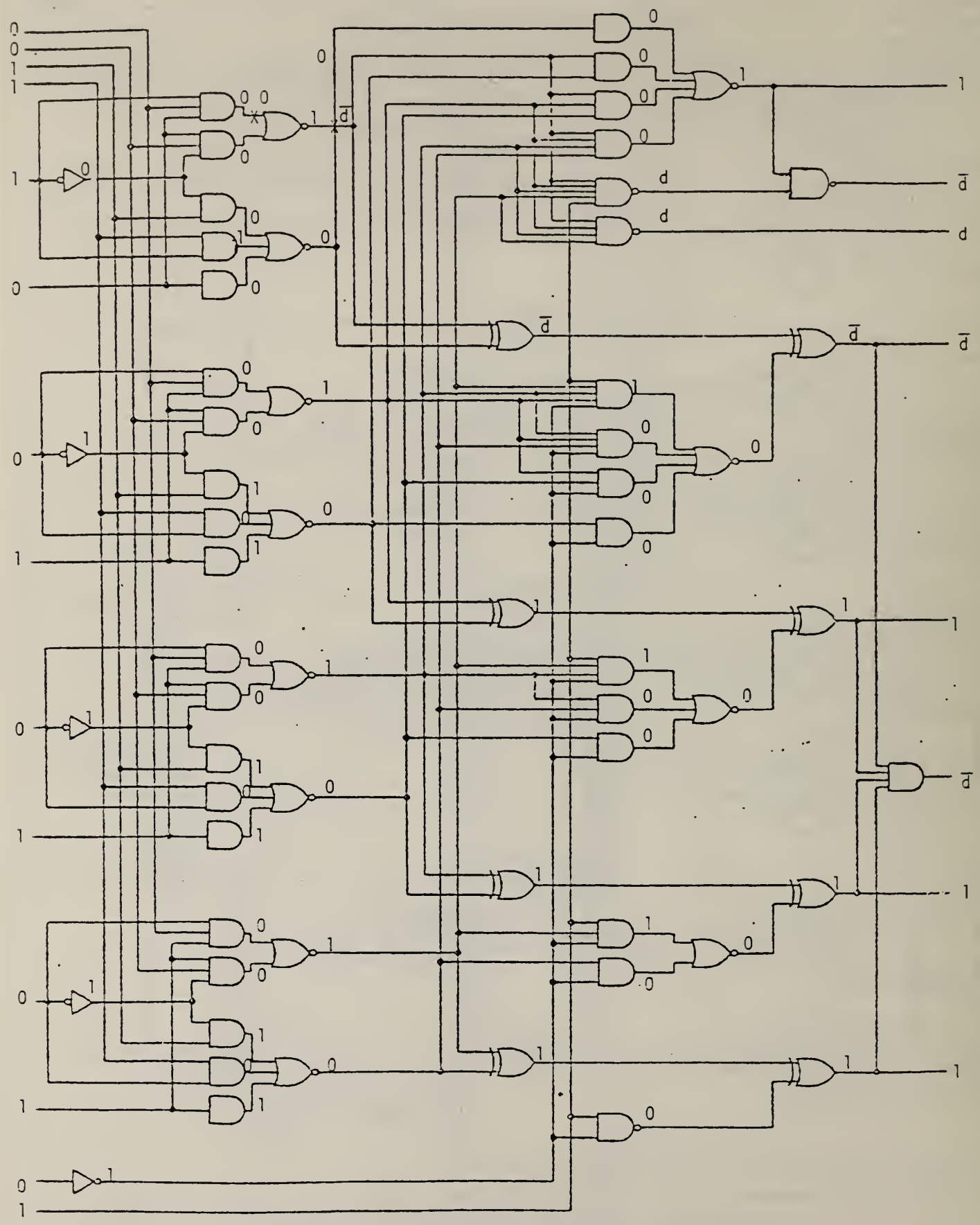

Figure A.3: Multiple fault test vector

JOUT

TIME USED TO FORM COMPONENTS IS 0

FAULT RUN NUMBER 1

FAULTS

GATE	TYPE OF FAULT
125	LINE 3 OF GATE 44 STUCK-AT-0

GATE ASSIGNMENTS

GT	TP	ADJACENT PINS		
1	1	1		
2	1	2		
3	1	3		
4	1	4		
5	1	5		
6	1	6		
7	1	7		
8	1	8		
9	1	9		
10	1	10		
11	1	11		
12	1	12		
13	1	13		
14	1	14		
15	4	5	15	
16	4	7	16	
17	4	9	17	
18	4	11	18	
19	4	13	19	
20	5	1	5	20
21	5	6	20	21
22	5	6	2	22
23	5	15	22	23
24	8	21	23	24
25	5	3	15	25
26	5	4	5	26
27	3	6	27	
28	6	25	26	28
29	8	27	28	29
30	5	7	1	30
31	5	8	30	31
32	5	8	2	32
33	5	16	32	33
34	8	31	33	34
35	5	16	3	35
36	5	4	7	36
37	3	8	37	
38	6	35	36	38
39	8	37	38	39
40	5	9	1	40

JOUT

41	5	10	40	41
42	5	10	2	42
43	5	17	42	43
44	8	41	43	117
45	5	17	3	45
46	5	4	9	46
47	3	10	47	
48	6	45	46	48
49	8	47	48	49
50	5	11	1	50
51	5	12	50	51
52	5	12	2	52
53	5	18	52	53
54	8	51	53	54
55	5	18	3	55
56	5	4	11	56
57	3	12	57	
58	6	55	56	58
59	8	57	58	59
60	3	29	60	
61	5	24	39	61
62	5	24	34	62
63	5	49	62	63
64	5	24	34	64
65	5	44	64	65
66	5	59	65	66
67	6	60	61	67
68	6	63	67	68
69	8	66	68	69
70	5	24	34	70
71	5	44	70	71
72	5	54	71	72
73	7	14	72	73
74	5	24	34	74
75	5	44	74	75
76	7	54	75	76
77	11	24	29	77
78	5	8	54	78
79	5	44	78	79
80	5	34	79	80
81	5	19	80	81
82	5	44	34	82
83	5	59	82	83
84	5	19	83	84
85	5	34	49	85
86	5	19	85	86
87	5	19	39	87
88	6	81	84	88
89	6	86	88	89
90	8	87	89	90
91	11	34	39	91
92	5	14	54	92
93	5	44	92	93
94	5	19	93	94
95	5	44	59	95
96	5	19	95	96
97	5	49	19	97
98	6	94	96	98

JOUT

99	8	97	98	99
100	11	44	49	100
101	5	14	54	101
102	5	19	101	102
103	5	59	19	103
104	8	102	103	104
105	11	54	59	105
106	7	14	19	106
107	4	69	107	
108	4	73	108	
109	6	107	108	109
110	11	77	90	110
111	11	91	99	111
112	11	100	104	112
113	11	105	106	113
114	5	110	111	114
115	5	112	114	115
116	5	113	115	116
117	2	69		
118	2	76		
119	2	109		
120	2	110		
121	2	111		
122	2	112		
123	2	113		
124	2	116		
125	22	117	44	

PIN ASSIGNMENTS

PIN	ADJACENT	GATES									
1	1	20	30	40	50						
2	2	22	32	42	52						
3	3	25	35	45	55						
4	4	26	36	46	56						
5	5	15	20	26							
6	6	21	22	27							
7	7	16	30	36							
8	8	31	32	37	78						
9	9	17	40	46							
10	10	41	42	47							
11	11	18	50	56							
12	12	51	52	57							
13	13	19									
14	14	73	92	101	106						
15	15	23	25								
16	16	33	35								
17	17	43	45								
18	18	53	55								
19	19	81	84	86	87	94	96	97	102	103	106
20	20	21									
21	21	24									
22	22	23									
23	23	24									
24	24	61	62	64	70	74	77				
25	25	28									
26	26	28									
27	27	29									

JOUT

28	28	29							
29	29	60	77						
30	30	31							
31	31	34							
32	32	33							
33	33	34							
34	34	62	64	70	74	80	82	85	91
35	35	38							
36	36	38							
37	37	39							
38	38	39							
39	39	61	87	91					
40	40	41							
41	41	44							
42	42	43							
43	43	44							
44	125	65	71	75	79	82	93	95	100
45	45	48							
46	46	48							
47	47	49							
48	48	49							
49	49	63	85	97	100				
50	50	51							
51	51	54							
52	52	53							
53	53	54							
54	54	72	76	78	92	101	105		
55	55	58							
56	56	58							
57	57	59							
58	58	59							
59	59	66	83	95	103	105			
60	60	67							
61	61	67							
62	62	63							
63	63	68							
64	64	65							
65	65	66							
66	66	69							
67	67	68							
68	68	69							
69	69	107	117						
70	70	71							
71	71	72							
72	72	73							
73	73	108							
74	74	75							
75	75	76							
76	76	118							
77	77	110							
78	78	79							
79	79	80							
80	80	81							
81	81	88							
82	82	83							
83	83	84							
84	84	88							
85	85	86							

JOUT

86	86	89	
87	87	90	
88	88	89	
89	89	90	
90	90	110	
91	91	111	
92	92	93	
93	93	94	
94	94	98	
95	95	96	
96	96	98	
97	97	99	
98	98	99	
99	99	111	
100	100	112	
101	101	102	
102	102	104	
103	103	104	
104	104	112	
105	105	113	
106	106	113	
107	107	109	
108	108	109	
109	109	119	
110	110	114	120
111	111	114	121
112	112	115	122
113	113	116	123
114	114	115	
115	115	116	
116	116	124	
117	44	125	

LEVELLING

ELEVEL = 1 PLEVEL = 41 IOPLEV = 124

SCANNING SEQUENCE

125	100	112	122	95	96	93	94	98	99	111	121	82	83	84	79	80	81	88	89
90	110	120	114	115	116	124	75	76	118	71	72	73	108	65	66	69	117	107	109
119	44	104	92	97	91	78	86	87	77	113	74	70	64	68	41	43	102	103	85
105	59	57	58	106	19	13	63	49	47	48	67	40	42	10	45	17	46	101	54
14	51	53	55	56	50	18	52	12	62	34	31	33	30	32	60	29	27	28	61
39	24	37	8	38	21	23	9	11	35	16	36	7	20	1	22	2	6	25	3
15	26	4	5																

LEADFL

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60
61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
101	102	103	104	105	106	107	108	109	110	111	112	113	114	115	116	117			
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	35	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	36	37	0	0	39	0	32	33	34	0	29	0	0	0	17	18
19	14	15	19	0	0	0	20	21	22	0	0	8	9	6	9	0	10	11	3

JOUT

0 0 0 0 0 0 40 40 0 24 24 25 0 25 26 0 0

NUMBER OF TESTS = 2

TIME FOR VECTOR COMPUTATION IS 13285

NL = 21571

TEST NUMBER 1

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
@	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
?	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
i	106	107	108	109	110	111	112	113	114	115	116	117								
VALUE	0	0	0	1	1	1	0	0	1	0	0	0	0	1	0	1	0	1	1	0
	0	0	1	0	1	1	1	0	0	0	0	0	1	0	0	0	0	1	0	0
	0	3	0	1	0	1	0	0	0	0	0	1	0	0	0	0	1	0	1	1
	1	3	3	1	1	0	1	3	3	2	1	3	2	1	0	0	0	0	3	3
	0	0	1	3	3	0	0	1	3	3	3	3	0	3	2	3	1	1	1	0
	0	1	3	1	1	2	3	0	2	0	0	1								

PRINCIPAL INPUTS

GATE	VALUE
1	0
2	0
3	0
4	1
5	1
6	1
7	0
8	0
9	1
10	0
11	0
12	0
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	0
118	2
119	1
120	1
121	2
122	3
123	0
124	0

TIME FOR VECTOR COMPUTATION IS 3

NL = 21579

Problem #2

JOUT

TEST NUMBER 2

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
?	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
↑	106	107	108	109	110	111	112	113	114	115	116	117								
VALUE	0	1	0	1	1	1	0	0	1	0	0	0	0	1	0	1	0	1	1	0
	1	0	1	0	1	1	1	0	0	0	0	0	1	0	0	0	0	1	0	0
	0	3	0	1	0	1	0	0	0	0	0	1	0	0	0	0	1	0	1	1
	1	3	3	1	1	0	1	3	3	2	1	3	2	1	0	0	0	0	3	3
	0	0	1	3	3	0	0	1	3	3	3	3	0	3	2	3	1	1	1	0
	0	1	3	1	1	2	3	0	2	0	0	1								

PRINCIPAL INPUTS

GATE	VALUE
1	0
2	1
3	0
4	1
5	1
6	1
7	0
8	0
9	1
10	0
11	0
12	0
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	0
118	2
119	1
120	1
121	2
122	3
123	0
124	0

END OF RUN

END ONSITE PRINTOUT ON JULY 21, 1982 AT 08:47:22
VLSI*JOUT(1).

```
   ACCOUNT: 33232-PRZYBO    TRAIN: A    REEL: 37      TRACK: 7    PUNCH: N    LINES/INCH:
SOF  CONTROL WORD, OCTAL - SC0130000C00, I =  1, FT = S, P =  0, CT = FIELDATA
ABOVE CONTROL WORD IN BLOCK       1 LOOKS WRONG    ????????????????????????????????????
*SOFF*                                             ------------------------------------


                    TIME USED TO FORM COMPONENTS IS      7533


FAULT RUN NUMBER              2


FAULTS

         GATE   TYPE OF FAULT
          132   LINE              3 OF GATE           44  STUCK-AT-0


GATE ASSIGNMENTS
 GT TP ADJACENT PINS
  1   1   1
  2   1   2
  3   1   3
  4   1   4
  5   1   5
  6   1   6
  7   1   7
  8   1   8
  9   1   9
 10   1  10
 11   1  11
 12   1  12
 13   1  13
 14   1  14
 15   4   9  15
 16   4   7  16
 17   4   9  17
 18   4  11  18
 19   4  13  19
 20   5   1   5  20
 21   5   6  20  21
 22   5   6   2  22
 23   5  15  22  23
 24   6  21  23  24
 25   6   3  15  25
 26   5   4   5  26
 27   3   6  27
 28   6  25  26  29
 29   8  27  28  29
 30   5   7   1  30
 31   5   8  30  31
 32   5   9   2  32
 33   5  16  32  33
 34   8  31  33  34
 35   5  16   3  35
```

36	5	4	7	36
37	3	6	37	
38	6	35	36	38
39	8	37	38	39
40	5	9	1	40
41	5	10	40	41
42	5	10	2	42
43	5	17	42	43
44	8	41	43	117
45	5	17	3	45
46	5	4	9	46
47	3	10	47	
48	6	45	46	48
49	8	47	48	49
50	5	11	1	50
51	5	12	50	51
52	5	12	2	52
53	5	18	52	53
54	8	51	53	54
55	5	18	3	55
56	5	4	11	56
57	3	12	57	
58	6	55	56	58
59	8	57	58	59
60	3	29	60	
61	5	24	39	61
62	5	24	34	62
63	5	49	62	63
64	5	24	34	64
65	5	44	64	65
66	5	59	65	66
67	6	60	61	67
68	6	63	67	68
69	8	66	68	69
70	5	24	34	70
71	5	44	70	71
72	5	54	71	72
73	7	14	72	73
74	5	24	34	74
75	5	44	74	75
76	7	54	75	76
77	11	24	29	77
78	5	8	54	78
79	5	44	78	79
80	5	34	79	80
81	5	19	80	81
82	5	44	34	82
83	5	59	82	83
84	6	19	83	84
85	5	34	49	85
86	5	19	85	86
87	5	19	39	87
88	6	81	84	88
89	5	86	88	89
90	8	87	89	90
91	11	34	39	91
92	5	14	54	92
93	5	44	92	93

94	5	19	93	94				
95	5	44	59	95				
96	5	19	95	96				
97	5	49	19	97				
98	6	94	96	98				
99	6	97	98	99				
100	11	44	49	100				
101	5	14	54	101				
102	5	19	101	102				
103	5	59	19	103				
104	8	102	103	104				
105	11	54	59	105				
106	7	14	19	106				
107	4	69	107					
108	4	73	108					
109	6	107	108	109				
110	11	77	90	110				
111	11	91	99	111				
112	11	100	104	112				
113	11	105	106	113				
114	5	110	111	114				
115	5	112	114	115				
116	5	113	115	116				
117	2	69						
118	2	76						
119	2	109						
120	2	110						
121	2	111						
122	2	112						
123	2	113						
124	2	116						
125	12	1	2	5	6	15	24	
126	12	1	2	7	8	16	34	
127	12	1	2	11	12	18	54	
128	13	3	4	5	6	15	29	
129	13	3	4	7	8	16	39	
130	13	3	4	9	10	17	49	
131	13	3	4	11	12	18	59	
132	22	117	44					

PIN ASSIGNMENTS

PIN	ADJACENT GATES				
1	1	125	126	40	127
2	2	125	126	42	127
3	3	128	129	130	131
4	4	128	129	130	131
5	5	15	125	128	
6	6	125	128		
7	7	16	126	129	
8	8	126	129	78	
9	9	17	40	130	
10	10	41	42	130	
11	11	18	127	131	
12	12	127	131		
13	13	19			
14	14	73	92	101	106
15	15	125	128		

```
16  16 126 129
17  17  43 130
18  18 127 131
19  19  81  84  86  87  94  96  97 102 103 106
20  20  21
21  21  24
22  22  23
23  23  24
24 125  61  62  64  70  74  77
25  25  26
26  26  28
27  27  29
28  28  29
29 128  60  77
30  30  31
31  31  34
32  32  33
33  33  34
34 126  62  64  70  74  80  82  85  91
35  35  38
36  36  38
37  37  39
38  38  39
39 129  61  87  91
40  40  41
41  41  44
42  42  43
43  43  44
44 132  65  71  75  79  82  93  95 100
45  45  48
46  46  49
47  47  49
48  48  49
49 130  63  85  97 100
50  50  51
51  51  54
52  52  53
53  53  54
54 127  72  76  78  92 101 105
55  55  58
56  56  58
57  57  59
58  58  59
59 131  66  83  95 103 105
60  60  67
61  61  67
62  62  63
63  63  68
64  64  65
65  65  66
66  66  69
67  67  68
68  68  69
69  69 107 117
70  70  71
71  71  72
72  72  73
73  73 106
```

```
 74  74  75
 75  75  76
 76  76 118
 77  77 110
 78  78  79
 79  79  80
 80  80  81
 81  81  88
 82  82  83
 83  83  84
 84  84  88
 85  85  86
 86  86  89
 87  87  90
 88  98  89
 89  89  90
 90  90 110
 91  91 111
 92  92  93
 93  93  94
 94  94  98
 95  95  96
 96  96  99
 97  97  95
 98  98  99
 99  99 111
100 100 112
101 101 102
102 102 104
103 103 104
104 104 112
105 105 113
106 106 113
107 107 109
108 108 109
109 109 119
110 110 114 120
111 111 114 121
112 112 115 122
113 113 116 123
114 114 115
115 115 116
116 116 124
117  44 132


LEVELLING
FLEVEL =              1 PLEVEL =             41 TOPLEV =             96
SCANNING SEQUENCE
 132 100 112 122  95  96  93  94  98  99 111 121  82  83  84  79  80  81  88  89
  90 110 120 114 115 116 124  75  76 118  71  72  73 108  65  66  69 117 107 109
 119  44 104  92  97  91  78  86  87  77 113  74  70  64  68  41  43 102 103  85
 105 131 106  19  13  63 130  17  67  40   9  42  10 101 127  14  12  18  11  62
 126  60 128  81 129   3   4   8  16   7 125   1   2   6  15   5


LEADPL
   1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
```

21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60
61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
101	102	103	104	105	106	107	108	109	110	111	112	113	114	115	116	117			
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	35	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	36	37	0	0	39	0	32	33	34	0	29	0	0	0	17	18
19	14	15	19	0	0	0	20	21	22	0	0	8	9	6	9	0	10	11	3
0	0	0	0	0	0	40	40	0	24	24	25	0	25	26	0	0			

NUMBER OF TESTS = 3

TIME FOR VECTOR COMPUTATION IS 20899

NL = 23410

TEST NUMBER 1

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
????	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
???*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
????	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
???T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
???I	105	107	108	109	110	111	112	113	114	115	116	117								
VALUE	0	1	0	1	1	1	0	0	1	0	0	0	0	1	0	1	0	1	1	-1
---^	-1	-1	1	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	0
????	0	3	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	1	1
????	1	3	3	1	1	0	1	3	3	2	1	3	2	1	0	0	0	0	3	3
????	0	0	1	3	3	0	0	1	3	3	3	3	0	3	2	3	1	1	1	0
????	0	1	3	1	1	2	3	0	2	0	0	1								

PRINCIPAL INPUTS

GATE	VALUE
1	0
2	1
3	0
4	1
5	1
6	1
7	0
8	0
9	1
10	0
11	0
12	0
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	0
118	2
119	1

```
  21  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40
  41  42  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60
  61  62  63  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80
  81  82  83  84  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100
 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117
   C   C   C   0   0   0   0   C   0   0   0   0   0   0   0   0   0   0   0   0
   0   0   C   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
   0   0   0  35   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
   0   0   C   0  36  37   0   0  39   0  32  33  34   0  29   0   0   0  17  18
  19  14  15  19   0   0   0  20  21  22   0   0   8   9   6   9   0  10  11   3
   0   0   C   0   0   0  40  40   0  24  24  25   0  25  26   0   0

NUMBER OF TESTS =              3

                    TIME FOR VECTOR COMPUTATION IS      20899
 NL =   23410

TEST NUMBER              1

PIN VALUES
 PIN       1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
   ????  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40  41
   ???*  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60  61  62
   ????  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80  81  82  83
   ???T  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100 101 102 103 104
   ???I 106 107 108 109 110 111 112 113 114 115 116 117
 VALUE   0   1   0   1   1   1   0   0   1   0   0   0   0   1   0   1   0   1   1  -1
   ___^ -1  -1   1  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   C   0
   ????  0   3  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   1   1
   ????  1   3   3   1   1   0   1   3   3   2   1   3   2   1   0   0   0   C   3   3
   ????  0   0   1   3   3   0   C   1   3   3   3   3   0   3   2   3   1   1   1   0
   ????  0   1   3   1   1   2   3   0   2   0   0   1

PRINCIPAL INPUTS
GATE VALUE
   1   0
   2   1
   3   0
   4   1
   5   1
   6   1
   7   0
   8   0
   9   1
  10   0
  11   0
  12   0
  13   0
  14   1

PRINCIPAL OUTPUTS
GATE VALUE
 117   0
 118   2
 119   1
```

120	1
121	2
122	3
123	0
124	0

TIME FOR VECTOR COMPUTATION IS 22

NL = 23435

TEST NUMBER 2

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
????	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
???*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
????	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
???T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
???I	106	107	108	109	110	111	112	113	114	115	116	117								
VALUE	0	1	0	1	1	0	0	0	1	0	0	0	0	1	0	1	0	1	1	-1
___^	-1	-1	1	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	0
????	0	3	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	1	1
????	1	3	3	1	1	0	1	3	3	2	1	3	2	1	0	0	0	0	3	3
????	0	0	1	3	3	0	0	1	3	3	3	3	0	3	2	3	1	1	1	0
????	0	1	3	1	1	2	3	0	2	0	0	1								

PRINCIPAL INPUTS

GATE	VALUE
1	0
2	1
3	0
4	1
5	1
6	0
7	0
8	0
9	1
10	0
11	0
12	0
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	0
118	2
119	1
120	1
121	2
122	3
123	0
124	0

TIME FOR VECTOR COMPUTATION IS 155

NL = 23554

```
TEST NUMBER            3

PIN VALUES
 PIN       1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
   ????   22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40  41
   ???*   43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60  61  62
   ????   64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80  81  82  83
   ???T   85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100 101 102 103 104
   ???I  106 107 108 109 110 111 112 113 114 115 116 117
 VALUE     0   0   0   1   1   1   0   0   1   0   0   0   0   1   0   1   0   1   1  -1
   ___^   -1  -1   1  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   0
   ????    0   3  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   1   1
   ????    1   3   3   1   1   0   1   3   3   2   1   3   2   1   0   0   0   0   3   3
   ????    0   0   1   3   3   0   0   1   3   3   3   3   0   3   2   3   1   1   1   0
   ????    0   1   3   1   1   2   3   0   2   0   0   1

PRINCIPAL INPUTS
GATE VALUE
   1    0
   2    0
   3    0
   4    1
   5    1
   6    1
   7    0
   8    0
   9    1
  10    0
  11    0
  12    0
  13    0
  14    1

PRINCIPAL OUTPUTS
GATE VALUE
 117    0
 118    2
 119    1
 120    1
 121    2
 122    3
 123    0
 124    0



END OF RUN

END OF SDF FILE,   ACCOUNT: 33232-PRZY80     PCY=     411, SPC=     475, PGS=       7, CRD=
```

```
  ACCOUNT: 33232-PRZYBO    TRAIN: A    REEL: 37      TRACK: 7    PUNCH: N    LINES/INCH:
SDF  CONTROL WORD, OCTAL - 50C130000000, I =  1, FT = S, P =  0, CT = FIELDATA
ABOVE CONTROL WORD IN BLOCK      1 LOOKS WRONG    ??????????????????????????????????????
*SOFF*                                            ----------------------------------

                    TIME USED TO FORM COMPONENTS IS      15975


FAULT RUN NUMBER              3

FAULTS

         GATE   TYPE OF FAULT
          146   LINE              3 OF GATE           44  STUCK-AT-0


GATE ASSIGNMENTS
 GT IP ADJACENT PINS
   1   1   1
   2   1   2
   3   1   3
   4   1   4
   5   1   5
   6   1   6
   7   1   7
   8   1   8
   9   1   9
  10   1  10
  11   1  11
  12   1  12
  13   1  13
  14   1  14
  15   4   5  15
  16   4   7  16
  17   4   9  17
  18   4  11  18
  19   4  13  19
  20   5   1   5  20
  21   5   6  20  21
  22   5   6   2  22
  23   5  15  22  23
  24   8  21  23  24
  25   5   3  15  25
  26   5   4   5  26
  27   3   6  27
  28   6  25  26  28
  29   8  27  28  29
  30   5   7   1  30
  31   5   5  30  31
  32   5   8   2  32
  33   5  16  32  33
  34   8  31  33  34
  35   5  16   3  35
```

36	5	4	7	36
37	3	8	37	
38	6	35	36	38
39	8	37	38	39
40	5	9	1	40
41	5	10	40	41
42	5	10	2	42
43	5	17	42	43
44	8	41	43	117
45	5	17	3	45
46	5	4	9	46
47	3	10	47	
48	6	45	46	48
49	8	47	48	49
50	5	11	1	50
51	5	12	50	51
52	5	12	2	52
53	5	18	52	53
54	8	51	53	54
55	5	18	3	55
56	5	4	11	56
57	3	12	57	
58	6	55	56	58
59	8	57	58	59
60	3	29	60	
61	5	24	39	61
62	5	24	34	62
63	5	49	62	63
64	5	24	34	64
65	5	44	64	65
66	5	59	65	66
67	6	60	61	67
68	6	63	67	68
69	8	66	68	69
70	5	24	34	70
71	5	44	70	71
72	5	54	71	72
73	7	14	72	73
74	5	24	34	74
75	5	44	74	75
76	7	54	75	76
77	11	24	29	77
78	5	8	54	78
79	5	44	78	79
80	5	34	79	80
81	5	19	80	81
82	5	44	34	82
83	5	59	82	83
84	5	19	83	84
85	5	34	49	85
86	5	19	85	86
87	5	19	39	87
88	6	81	84	88
89	6	86	88	89
90	8	87	89	90
91	11	34	39	91
92	5	14	54	92
93	5	44	92	93

```
 94    5   19   93   94
 95    5   44   59   95
 96    5   19   95   96
 97    5   45   19   97
 98    6   94   96   98
 99    8   97   98   99
100   11   44   49  100
101    5   14   54  101
102    5   19  101  102
103    5   59   19  103
104    8  102  103  104
105   11   54   59  105
106    7   14   19  106
107    4   65  107
108    4   73  108
109    6  107  108  109
110   11   77   90  110
111   11   91   95  111
112   11  100  104  112
113   11  105  106  113
114    5  110  111  114
115    5  112  114  115
116    5  113  115  116
117    2   65
118    2   76
119    2  109
120    2  110
121    2  111
122    2  112
123    2  113
124    2  116
125   12    1    2    5    6   15   24
126   12    1    2    7    8   16   34
127   12    1    2   11   12   18   54
128   13    3    4    5    6   15   29
129   13    3    4    7    8   16   39
130   13    3    4    9   10   17   49
131   13    3    4   11   12   13   59
132   14   24   34   44   59   66
133   14   19   34   44   59   84
134   14   14   19   44   54   94
135   14  110  111  112  113  116
136   15   14   24   34   44   54   73
137   16   60   61   63   66   69
138   16   81   84   86   87   90
139   17   24   34   49   63
140   17   19   34   49   86
141   17   19   44   59   96
142   17   14   19   54  102
143   18   24   34   44   54   76
144   19   94   96   97   99
145   26    8   19   34   44   54   81
146   22  117   44


PIN ASSIGNMENTS
 PIN ADJACENT GATES
   1    1  125  125   40  127
```

```
 2    2 125 126  42 127
 3    3 128 129 130 131
 4    4 128 129 130 131
 5    5  15 125 128
 6    6 125 128
 7    7  16 126 129
 8    8 126 129 145
 9    9  17  40 130
10   10  41  42 130
11   11  18 127 131
12   12 127 131
13   13  19
14   14 136 134 142 106
15   15 125 128
16   16 126 129
17   17  43 130
18   18 127 131
19   19 145 133 140  87 134 141  97 142 103  74
20   20  21
21   21  24
22   22  23
23   23  24
24  125  61 139 132 136 143  77
25   25  28
26   26  28
27   27  29
28   28  29
29  128  60  77
30   30  31
31   31  34
32   32  33
33   33  34
34  126 139 132 136 143 145 133 140  91
35   35  38
36   36  38
37   37  39
38   38  39
39  129  61  87  91
40   40  41
41   41  44
42   42  43
43   43  44
44  146 132 136 143 145 133 134 141 100
45   45  48
46   46  48
47   47  49
48   48  49
49  130 139 140  97 100
50   50  51
51   51  54
52   52  53
53   53  54
54  127 136 143 145 134 142 105
55   55  58
56   56  58
57   57  59
58   58  59
59  131 132 133 141 103 105
```

```
 60  60 137
 61  61 137
 62  62  63
 63 139 137
 64  64  65
 65  65  66
 66 132 137
 67  67  68
 68  68  69
 69 137 107 117
 70  70  71
 71  71  72
 72  72  73
 73 136 108
 74  74  75
 75  75  76
 76 143 118
 77  77 110
 78  78  79
 79  79  80
 80  80  81
 81 145 138
 82  82  83
 83  83  84
 84 133 138
 85  85  86
 86 140 138
 87  87 138
 88  88  89
 89  89  90
 90 138 110
 91  91 111
 92  92  93
 93  93  94
 94 134 144
 95  95  96
 96 141 144
 97  97 144
 98  98  99
 99 144 111
100 100 112
101 101 102
102 142 104
103 103 104
104 104 112
105 105 113
106 106 113
107 107 109
108 108 109
109 109 119
110 110 135 120
111 111 135 121
112 112 135 122
113 113 135 123
114 114 115
115 115 116
116 135 124
117  44 146
```

```
 LEVELLING
 FLEVEL =              1 PLEVEL =             26 TOPLEV =             71
 SCANNING SEQUENCE
  146 100 112 122 141 134 144 111 121 133 145 138 110 120 135 124 143 118 134 108
  132 137 117 107 109 119  44 104  97  91 140  87  77 113  60  61 139 130 126 125
   41  43  17 142 103  19  13 129   8  16   7 128 105 131 127   3   4  12  18  11
  106  14   6  15   5  40   9   1  42  10   2


LEADFL
    1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
   21  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40
   41  42  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60
   61  62  63  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80
   81  82  83  84  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100
  101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117
    0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
    0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
    0   0   0  21   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
    0   0   0   0   0  22   0   0  24   0   0   0  20   0   0   0   0   0   0   0
   12   0   0  12   0   0   0   0   0  13   0   0   0   7   0   7   0   0   8   3
    0   0   0   0   0   0  25  25   0  15  15  15   0   0   0   0   0


NUMBER OF TESTS =              5


                    TIME FOR VECTOR COMPUTATION IS     205657
 NL =  186700


TEST NUMEER              1

PIN VALUES
 PIN       1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
    ????  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40  41
    ???*  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60  61  62
    ????  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80  81  82  83
    ???T  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100 101 102 103 104
    ???I 106 107 108 109 110 111 112 113 114 115 116 117
 VALUE    0   1   1   0   1   1   1   0   1   1   1   0   0   1   0   0   0   0   1  -1
    ___^ -1  -1   1  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   0
    ????  0   3  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   1  -1
    ????  -1  -1   3  -1  -1   0  -1  -1  -1   2  -1  -1   2   1  -1  -1  -1   0  -1  -1
    ????  -1   0   1  -1  -1   0   0  -1  -1   3  -1   3   0  -1   2   3  -1   1   1   0
    ????   0   1   3   1   1   2   3   0  -1  -1   0   1

PRINCIPAL INPUTS
GATE VALUE
   1   0
   2   1
   3   1
   4   0
   5   1
   6   1
   7   1
   8   0
   9   1
  10   1
  11   1
  12   0
```

```
  13    0
  14    1

PRINCIPAL OUTPUTS
GATE VALUE
 117    0
 118    2
 119    1
 120    1
 121    2
 122    3
 123    0
 124    0


                    TIME FOR VECTOR COMPUTATION IS         103
 NL =  186806


TEST NUMBER              2

PIN VALUES
 PIN       1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
   ????   22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40  41
   ???*   43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60  61  62
   ????   64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80  81  82  83
   ???T   85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100 101 102 103 104
   ???I 106 107 108 109 110 111 112 113 114 115 116 117
 VALUE     0   1   1   0   0   0   1   0   1   1   1   0   0   1   1   0   0   0   1  -1
   ___^   -1  -1   1  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   0
   ????    0   3  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   1  -1
   ????   -1  -1   3  -1  -1   0  -1  -1  -1   2  -1  -1   2   1  -1  -1  -1   0  -1  -1
   ????   -1   0   1  -1  -1   0   0  -1  -1   3  -1   3   0  -1   2   3  -1   1   1   0
   ????    0   1   3   1   1   2   3   0  -1  -1   0   1

PRINCIPAL INPUTS
GATE VALUE
   1    0
   2    1
   3    1
   4    0
   5    0
   6    0
   7    1
   8    0
   9    1
  10    1
  11    1
  12    0
  13    0
  14    1

PRINCIPAL OUTPUTS
GATE VALUE
 117    0
 118    2
 119    1
 120    1
```

```
 121    2
 122    3
 123    0
 124    0

                    TIME FOR VECTOR COMPUTATION IS        246
 NL =  187055

TEST NUMBER             3

PIN VALUES
 PIN       1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
   ????   22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40  41
   ???*   42  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60  61  62
   ????   64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80  81  82  83
   ???T   85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100 101 102 103 104
   ???I 106 107 108 109 110 111 112 113 114 115 116 117
 VALUE     0   0   1   0   1   1   1   0   1   1   1   0   0   1   0   0   0   0   1  -1
   ___^   -1  -1   1  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   0
   ????    0   3  -1  -1  -1  -1   0  -1  -1  -1  -1   1  -1  -1  -1  -1   1   0   1  -1
   ????   -1  -1   3  -1  -1   0  -1  -1  -1   2  -1  -1   2   1  -1  -1  -1   0  -1  -1
   ????   -1   0   1  -1  -1   0   0  -1  -1   3  -1   3   0  -1   2   3  -1   1   1   0
   ????    0   1   3   1   1   2   3   0  -1  -1   0   1

PRINCIPAL INPUTS
GATE VALUE
   1    0
   2    0
   3    1
   4    0
   5    1
   6    1
   7    1
   8    0
   9    1
  10    1
  11    1
  12    0
  13    0
  14    1

PRINCIPAL OUTPUTS
GATE VALUE
 117    0
 118    2
 119    1
 120    1
 121    2
 122    3
 123    0
 124    0

                    TIME FOR VECTOR COMPUTATION IS         74
 NL =  187136
```

TEST NUMBER 4

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
????	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
???*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
????	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
???T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
???I	106	107	108	109	110	111	112	113	114	115	116	117								
VALUE	0	0	1	0	0	1	1	0	1	1	1	0	0	1	1	0	0	0	1	-1
___^	-1	-1	1	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	0
????	0	3	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	1	-1
????	-1	-1	3	-1	-1	0	-1	-1	-1	2	-1	-1	2	1	-1	-1	-1	0	-1	-1
????	-1	0	1	-1	-1	0	0	-1	-1	3	-1	3	0	-1	2	3	-1	1	1	0
????	0	1	3	1	1	2	3	0	-1	-1	0	1								

PRINCIPAL INPUTS

GATE	VALUE
1	0
2	0
3	1
4	0
5	0
6	1
7	1
8	0
9	1
10	1
11	1
12	0
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	0
118	2
119	1
120	1
121	2
122	3
123	0
124	0

TIME FOR VECTOR COMPUTATION IS 61

NL = 187201

TEST NUMBER 5

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
????	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
???*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
????	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
???T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
???I	106	107	108	109	110	111	112	113	114	115	116	117								
VALUE	0	0	1	0	0	0	1	0	1	1	1	0	0	1	1	0	0	0	1	-1
___^	-1	-1	1	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	0
????	0	3	-1	-1	-1	-1	0	-1	-1	-1	-1	1	-1	-1	-1	-1	1	0	1	-1
????	-1	-1	3	-1	-1	0	-1	-1	-1	2	-1	-1	2	1	-1	-1	-1	0	-1	-1

```
   ????  -1   0   1  -1  -1   0   0  -1  -1   3  -1   3   0  -1   2   3  -1   1   1   0
   ????   0   1   3   1   1   2   3   0  -1  -1   0   1

PRINCIPAL INPUTS
GATE VALUE
   1   0
   2   0
   3   1
   4   0
   5   0
   6   0
   7   1
   8   0
   9   1
  10   1
  11   1
  12   0
  13   0
  14   1

PRINCIPAL OUTPUTS
GATE VALUE
 117   0
 118   2
 119   1
 120   1
 121   2
 122   3
 123   0
 124   0



END OF RUN

END OF SDF FILE,   ACCOUNT: 33232-PRZYEO     PCY=     508, SPC=     587, PGS=       9, CPD=
```

Problem #4

```
   ACCOUNT: 33232-PRZYBO     TRAIN: A     REEL: 00       TRACK: 7     PUNCH: N     LINES/INCH:
SDF  CONTROL WORD, OCTAL - 500130000000, I =  1, FF = S, P =  0, CT = FIELDATA
ABOVE CONTROL WORD IN BLOCK       1 LOOKS WRONG     ??????????????????????????????????????
*SDFF*                                              ----------------------------------

                    TIME USED TO FORM COMPONENTS IS          0



FAULT RUN NUMBER              4


FAULTS

          GATE    TYPE OF FAULT
             1    INPUT SET TO 0
             2    INPUT SET TO 0
             3    INPUT SET TO 0
             4    INPUT SET TO 1
             5    INPUT SET TO 1
             6    INPUT SET TO 1
             7    INPUT SET TO 0
             8    INPUT SET TO 0
             9    INPUT SET TO 1
            10    INPUT SET TO 0
            11    INPUT SET TO 0
            12    INPUT SET TO 0
            13    INPUT SET TO 0
            14    INPUT SET TO 1
           125    LINE              3 OF GATE            44   STUCK-AT-0


GATE ASSIGNMENTS
 GT IP ADJACENT PINS
   1  20    1
   2  20    2
   3  20    3
   4  21    4
   5  21    5
   6  21    6
   7  20    7
   8  20    8
   9  21    9
  10  20   10
  11  20   11
  12  20   12
  13  20   13
  14  21   14
  15   4    5   15
  16   4    7   16
  17   4    9   17
  18   4   11   18
  19   4   13   19
  20   5    1    5   20
  21   5    6   20   21
```

22	5	6	2	22
23	5	15	22	23
24	8	21	23	24
25	5	3	15	25
26	5	4	6	26
27	3	6	27	
28	6	25	26	28
29	8	27	28	29
30	5	7	1	30
31	5	8	30	31
32	5	8	2	32
33	5	16	32	33
34	8	31	33	34
35	5	16	3	35
36	5	4	7	36
37	3	9	37	
38	6	35	36	38
39	8	37	39	39
40	5	9	1	40
41	5	10	40	41
42	5	10	2	42
43	5	17	42	43
44	8	41	43	117
45	5	17	3	45
46	5	4	9	46
47	3	10	47	
48	6	45	46	48
49	8	47	48	49
50	5	11	1	50
51	5	12	50	51
52	5	12	2	52
53	5	18	52	53
54	8	51	53	54
55	5	18	3	55
56	5	4	11	56
57	3	12	57	
58	6	55	56	58
59	8	57	58	59
60	3	29	60	
61	5	24	39	61
62	5	24	34	62
63	5	49	62	63
64	5	24	34	54
65	5	44	64	65
66	5	59	65	66
67	6	60	61	67
68	6	63	67	68
69	8	66	68	69
70	5	24	34	70
71	5	44	70	71
72	5	54	71	72
73	7	14	72	73
74	5	24	34	74
75	5	44	74	75
76	7	54	75	75
77	11	24	29	77
78	5	8	54	78
79	5	44	78	79

80	5	34	79	80
81	5	19	80	81
82	5	44	34	82
83	5	59	82	83
84	5	19	83	84
85	5	34	49	85
86	5	19	85	86
87	5	19	39	87
88	6	81	84	88
89	6	86	88	89
90	8	87	89	90
91	11	34	39	91
92	5	14	54	92
93	5	44	92	93
94	5	19	93	94
95	5	44	59	95
96	5	19	95	96
97	5	49	19	97
98	6	94	96	98
99	8	97	98	99
100	11	44	49	100
101	5	14	54	101
102	5	19	101	102
103	5	59	19	103
104	8	102	103	104
105	11	54	59	105
106	7	14	19	106
107	4	69	107	
108	4	73	108	
109	6	107	108	109
110	11	77	90	110
111	11	91	99	111
112	11	100	104	112
113	11	105	106	113
114	5	110	111	114
115	5	112	114	115
116	5	113	115	116
117	2	69		
118	2	76		
119	2	109		
120	2	110		
121	2	111		
122	2	112		
123	2	113		
124	2	116		
125	22	117	44	

PIN ASSIGNMENTS

PIN	ADJACENT GATES			
1	1	20	30	40	50
2	2	22	32	42	52
3	3	25	35	45	55
4	4	26	36	46	56
5	5	15	20	26	
6	6	21	22	27	
7	7	16	30	36	
8	8	31	32	37	78

9	9	17	40	46							
10	10	41	42	47							
11	11	18	50	56							
12	12	51	52	57							
13	13	19									
14	14	73	92	101	106						
15	15	23	25								
16	16	33	35								
17	17	43	45								
18	18	53	55								
19	19	81	84	86	87	94	96	97	102	103	106
20	20	21									
21	21	24									
22	22	23									
23	23	24									
24	24	61	62	64	70	74	77				
25	25	26									
26	26	28									
27	27	29									
28	28	29									
29	29	60	77								
30	30	31									
31	31	34									
32	32	33									
33	33	34									
34	34	62	64	70	74	80	82	85	91		
35	35	36									
36	36	38									
37	37	39									
38	38	39									
39	39	61	87	91							
40	40	41									
41	41	44									
42	42	43									
43	43	44									
44	125	65	71	75	79	82	93	95	100		
45	45	48									
46	46	48									
47	47	49									
48	48	49									
49	49	63	85	97	100						
50	50	51									
51	51	54									
52	52	53									
53	53	54									
54	54	72	76	78	92	101	105				
55	55	56									
56	56	58									
57	57	59									
58	58	59									
59	59	66	83	95	103	105					
60	60	67									
61	61	67									
62	62	63									
63	63	68									
64	64	65									
65	65	66									
66	66	69									

```
 67  67  68
 68  68  69
 69  69 107 117
 70  70  71
 71  71  72
 72  72  73
 73  73 108
 74  74  75
 75  75  76
 76  76 118
 77  77 110
 78  78  79
 79  79  80
 80  80  81
 81  81  88
 82  82  83
 83  83  84
 84  84  88
 85  85  86
 86  86  89
 87  87  90
 88  88  89
 89  89  90
 90  90 110
 91  91 111
 92  92  93
 93  93  94
 94  94  95
 95  95  96
 96  96  98
 97  97  99
 98  98  99
 99  99 111
100 100 112
101 101 102
102 102 104
103 103 104
104 104 112
105 105 113
106 106 113
107 107 109
108 108 109
109 109 115
110 110 114 120
111 111 114 121
112 112 115 122
113 113 116 123
114 114 115
115 115 116
116 116 124
117  44 125


LEVELLING
FLEVEL =              85 FLEVEL =             125 TOPLEV =             125
SCANNING SEQUENCE
  1  14  13  19 106  12  57  11  18  50  51  10  47   9  17  40  41   8  37   7
 16  30  31   6  27   5  15  20  21   4  26  36  46  56   3  25  28  29  60  35
```

```
  38  39  45  48  49  55  58  59 103  97  87   2  22  23  24  61  67  77  32  33
  34  74  70  64  62  65  63  68  91  42  43  44  52  53  54 105  78 113 123  86
 101 102 104  92 125  93  79  65  71  72  75  76 118  62  80  95  83  56  69 117
 107 100 112 122  96  94  98  99 111 121  84  81  88  89  90 110 120 114 115 116
 124  73 108 109 119

LEADFL
   1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
  21  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40
  41  42  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60
  61  62  63  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80
  81  82  83  84  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100
 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117
  28  73  46  34  31  53  32  77  33  70  34  73   4 122  54  60  71  74 112  29
  55  54  65  65  37  37  38  38  58  23  61  60  61  95  41  41  42  42  69  17
  72  71  72 102  44  44  45  45 102  11  75  74  75  92  47  47  48  48  98  57
  57  67  69  83  58  99  68  99 101  89  90 122 123  91  92   0 116  87  95 112
 113  97 111 113  80 114 115 114 115 116 109  86 106 107 105 107 108 108 109 103
  82  83  83 103  78  78 124 124   0 118 118 119 120 119 120   0  85

NUMBER OF TESTS =              1

                    TIME FOR VECTOR COMPUTATION IS          90
 NL =        0

TEST NUMBER              1

PIN VALUES
 PIN        1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
   ????  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40  41
   ???*  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60  61  62
   ????  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80  81  82  83
   ???1  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100 101 102 103 104
   ???I 106 107 108 109 110 111 112 113 114 115 116 117
 VALUE    0   0   0   1   1   1   0   0   1   0   0   0   0   1   0   1   0   1   1   0
   ????   0   0   1   0   1   1   1   0   0   0   0   0   1   0   0   0   0   1   0   0
   ????   0   3   0   1   0   1   0   0   0   0   0   1   0   0   0   0   1   0   1   1
   ????   1   3   3   1   1   0   1   3   3   2   1   3   2   1   0   0   0   0   3   3
   ????   0   0   1   3   3   0   0   1   3   3   3   3   0   3   2   3   1   1   1   0
   ????   0   1   3   1   1   2   3   0   2   0   0   1

PRINCIPAL INPUTS
GATE VALUE
   1   0
   2   0
   3   0
   4   1
   5   1
   6   1
   7   0
   8   0
   9   1
  10   0
  11   0
```

```
  12    0
  13    0
  14    1

PRINCIPAL OUTPUTS
GATE VALUE
 117    0
 118    2
 119    1
 120    1
 121    2
 122    3
 123    0
 124    0



END OF RUN

END OF SCF FILE,   ACCOUNT: 33232-PR2Y80     PCY=     336, SPC=     383, PGS=       6, CRD=
```

```
   ACCOUNT: 33232-PRZYBO     TRAIN: A     REEL: 24       TRACK: 7     PUNCH: N     LINES/INCH
SDF  CONTROL WORD, OCTAL - 500130000000, I =  1, FT = S, P =  0, CT = FIELDATA
ABOVE CONTROL WORD IN BLOCK       1 LOOKS WRONG     ??????????????????????????????????????????
*SDFF*                                              ----------------------------------------

                    TIME USED TO FORM COMPONENTS IS          0


FAULT RUN NUMBER                5

FAULTS

          GATE    TYPE OF FAULT
           125    LINE              1 OF GATE            24  STUCK-AT-0


GATE ASSIGNMENTS
 GT TP ADJACENT PINS
   1    1    1
   2    1    2
   3    1    3
   4    1    4
   5    1    5
   6    1    6
   7    1    7
   8    1    8
   9    1    9
  10    1   10
  11    1   11
  12    1   12
  13    1   13
  14    1   14
  15    4    5   15
  16    4    7   16
  17    4    9   17
  18    4   11   18
  19    4   13   19
  20    5    1    5   20
  21    5    6   20   21
  22    5    6    2   22
  23    5   15   22   23
  24    8  117   23   24
  25    5    3   15   25
  26    5    4    5   26
  27    3    6   27
  28    6   25   26   28
  29    8   27   28   29
  30    5    7    1   30
  31    5    8   30   31
  32    5    8    2   32
  33    5   16   32   33
  34    8   31   33   34
  35    5   16    3   35
```

36	5	4	7	36
37	3	8	37	
38	6	35	36	38
39	8	37	38	39
40	5	9	1	40
41	5	10	40	41
42	5	10	2	42
43	5	17	42	43
44	8	41	43	44
45	5	17	3	45
46	5	4	9	46
47	3	10	47	
48	6	45	46	48
49	8	47	48	49
50	5	11	1	50
51	5	12	50	51
52	5	12	2	52
53	5	18	52	53
54	8	51	53	54
55	5	18	3	55
56	5	4	11	56
57	3	12	57	
58	6	55	56	58
59	8	57	58	59
60	3	29	60	
61	5	24	39	61
62	5	24	34	62
63	5	49	62	63
64	5	24	34	64
65	5	44	64	65
66	5	59	65	66
67	6	60	61	67
68	6	63	67	68
69	8	66	68	69
70	5	24	34	70
71	5	44	70	71
72	5	54	71	72
73	7	14	72	73
74	5	24	34	74
75	5	44	74	75
76	7	54	75	76
77	11	24	29	77
78	5	8	54	78
79	5	44	78	79
80	5	34	79	80
81	5	19	80	81
82	5	44	34	82
83	5	59	82	83
84	5	19	83	84
85	5	34	49	85
86	5	19	85	86
87	5	19	39	87
88	6	81	84	88
89	6	86	88	89
90	8	87	89	90
91	11	34	39	91
92	5	14	54	92
93	5	44	92	93

94	5	19	93	94
95	5	44	59	95
96	5	19	95	96
97	5	49	19	97
98	6	94	96	98
99	8	97	98	99
100	11	44	49	100
101	5	14	54	101
102	5	19	101	102
103	5	59	19	103
104	9	102	103	104
105	11	54	59	105
106	7	14	19	106
107	4	69	107	
108	4	73	108	
109	6	107	108	109
110	11	77	90	110
111	11	91	99	111
112	11	100	104	112
113	11	105	106	113
114	5	110	111	114
115	5	112	114	115
116	5	113	115	116
117	2	69		
118	2	76		
119	2	109		
120	2	110		
121	2	111		
122	2	112		
123	2	113		
124	2	116		
125	22	21	117	

PIN ASSIGNMENTS

PIN	ADJACENT GATES									
1	1	20	30	40	50					
2	2	22	32	42	52					
3	3	25	35	45	55					
4	4	26	36	46	56					
5	5	15	20	26						
6	6	21	22	27						
7	7	16	30	36						
8	8	31	32	37	78					
9	9	17	40	46						
10	10	41	42	47						
11	11	18	50	56						
12	12	51	52	57						
13	13	19								
14	14	73	92	101	106					
15	15	23	25							
16	16	33	35							
17	17	43	45							
18	18	53	55							
19	19	81	84	86	87	94	96	97	102	103	106
20	20	21									
21	21	125									
22	22	23									

23	23	24							
24	24	61	62	64	70	74	77		
25	25	28							
26	26	28							
27	27	29							
28	28	29							
29	29	60	77						
30	30	31							
31	31	34							
32	32	33							
33	33	34							
34	34	62	64	70	74	80	82	85	91
35	35	38							
36	36	38							
37	37	39							
38	38	39							
39	39	61	87	91					
40	40	41							
41	41	44							
42	42	43							
43	43	44							
44	44	65	71	75	79	82	93	95	100
45	45	48							
46	46	48							
47	47	49							
48	48	49							
49	49	63	85	97	100				
50	50	51							
51	51	54							
52	52	53							
53	53	54							
54	54	72	76	78	92	101	105		
55	55	58							
56	56	58							
57	57	59							
58	58	59							
59	59	66	83	95	103	105			
60	60	67							
61	61	67							
62	62	63							
63	63	68							
64	64	65							
65	65	66							
66	66	69							
67	67	68							
68	68	69							
69	69	107	117						
70	70	71							
71	71	72							
72	72	73							
73	73	108							
74	74	75							
75	75	76							
76	76	118							
77	77	110							
78	78	79							
79	79	80							
80	80	81							

```
 81  81  88
 82  82  83
 83  83  84
 84  84  88
 85  85  86
 86  86  89
 87  87  90
 88  88  89
 89  89  90
 90  90 110
 91  91 111
 92  92  93
 93  93  94
 94  94  98
 95  95  96
 96  96  98
 97  97  99
 98  98  99
 99  99 111
100 100 112
101 101 102
102 102 104
103 103 104
104 104 112
105 105 113
106 106 113
107 107 109
108 108 109
109 109 119
110 110 114 120
111 111 114 121
112 112 115 122
113 113 116 123
114 114 115
115 115 116
116 116 124
117 125  24


LEVELLING
FLEVEL =                1 PLEVEL =               31 TOPLEV =              122
SCANNING SEQUENCE
 125  24  77 110 120 114 115 116 124  74  75  76 118  70  71  72  73 108  64  65
  66  62  63  61  67  68  69 117 107 109 119  21  23  90 111 112 113  60  29  20
  22  27   6  28  87  89  91  39  99 100 104 105 106  37  38  25  15  26   5  86
  88  97  98 102 103  35  36  85  49  47  48  45  46  81  84  94  96  19  13 101
  80  83  93  95  59  57  58  55  56   3   4  79  82  34  44  31  33  41  43  30
  16  32  40  17  42  10   7   9  92  14  78  54  51  53   8  50   1  18  52   2
  12  11


LEADFL
   1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
  21  22  23  24  25  26  27  28  29  30  31  32  33  34  35  36  37  38  39  40
  41  42  43  44  45  46  47  48  49  50  51  52  53  54  55  56  57  58  59  60
  61  62  63  64  65  66  67  68  69  70  71  72  73  74  75  76  77  78  79  80
  81  82  83  84  85  86  87  88  89  90  91  92  93  94  95  96  97  98  99 100
 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117
```

```
  0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
  0   0   0  24   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
  0   0   C   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
 25  23  2E  20  21  27  2E  27  29  15  16  17  18  11  12   0   4   0   0   0
  0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0   0
  0   0   0   0   0   0  30  30   0   6   0   0   0   7   8   0   2
```

NUMBER OF TESTS = 1

TIME FOR VECTOR COMPUTATION IS 27666

NL = 4C72E

TEST NUMBER 1

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
????	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
???*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
????	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
???T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
???I	106	107	108	109	110	111	112	113	114	115	116	117								
VALUE	1	0	1	1	1	1	0	1	0	1	0	1	0	1	0	1	1	1	1	1
????	0	0	2	0	1	1	1	0	0	0	0	0	1	1	0	1	1	0	0	0
????	0	1	1	0	1	1	0	0	0	0	0	1	1	0	1	1	0	0	0	2
????	2	2	0	0	0	1	2	2	2	3	2	2	3	2	1	1	1	1	1	0
????	0	0	0	1	1	0	1	1	1	1	0	0	0	1	0	1	1	1	0	0
????	0	0	2	2	2	1	1	1	2	2	2	3								

PRINCIPAL INPUTS

GATE	VALUE
1	1
2	0
3	1
4	1
5	1
6	1
7	0
8	1
9	0
10	1
11	0
12	1
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	1
118	3
119	2
120	2
121	1
122	1
123	1
124	2

```
END OF RUN

END OF SDF FILE,   ACCOUNT: 33232-PRZY80     PCY=     322, SPC=     369, PGS=       6, CRD=
```

Problem #6

```
   ACCOUNT: 33232-PRZYBO    TRAIN: A    REEL: 24      TRACK: 7    PUNCH: N    LINES/INCH
SOF  CONTROL WORD, OCTAL - 500130000000, I =  1, FT = S, P =  0, CT = FIELDATA
ABOVE CONTROL WORD IN BLOCK      1 LOOKS WRONG    ??????????????????????????????????????
*SOFF*                                            ----------------------------------
```

TIME USED TO FORM COMPONENTS IS 0

FAULT RUN NUMBER 6

FAULTS

GATE	TYPE OF FAULT				
125	LINE	1 OF GATE	24	STUCK-AT-0	
126	CROSS WIRE AND	BETWEEN LINE	3 OF GATE		24
		AND LINE	3 OF GATE		29

GATE ASSIGNMENTS

GT	TP	ADJACENT PINS			
1	1	1			
2	1	2			
3	1	3			
4	1	4			
5	1	5			
6	1	6			
7	1	7			
8	1	8			
9	1	9			
10	1	10			
11	1	11			
12	1	12			
13	1	13			
14	1	14			
15	4	5	15		
16	4	7	16		
17	4	9	17		
18	4	11	18		
19	4	13	19		
20	5	1	5	20	
21	5	6	20	21	
22	5	6	2	22	
23	5	15	22	23	
24	8	117	23	118	
25	5	3	15	25	
26	5	4	5	26	
27	3	6	27		
28	6	25	26	28	
29	8	27	28	119	
30	5	7	1	30	
31	5	6	30	31	
32	5	8	2	32	
33	5	16	32	33	

34	8	31	33	34
35	5	16	3	35
36	5	4	7	36
37	3	8	37	
38	6	35	36	38
39	8	37	38	39
40	5	9	1	40
41	5	10	40	41
42	5	10	2	42
43	5	17	42	43
44	8	41	43	44
45	5	17	3	45
46	5	4	9	46
47	3	10	47	
48	6	45	46	48
49	8	47	48	49
50	5	11	1	50
51	5	12	50	51
52	5	12	2	52
53	5	18	52	53
54	8	51	53	54
55	5	18	3	55
56	5	4	11	56
57	3	12	57	
58	6	55	56	58
59	8	57	58	59
60	3	29	60	
61	5	24	39	61
62	5	24	34	62
63	5	49	62	63
64	5	24	34	64
65	5	44	64	65
66	5	59	65	66
67	6	60	61	67
68	6	63	67	68
69	8	66	68	69
70	5	24	34	70
71	5	44	70	71
72	5	54	71	72
73	7	14	72	73
74	5	24	34	74
75	5	44	74	75
76	7	54	75	76
77	11	24	29	77
78	5	8	54	78
79	5	44	78	79
80	5	34	79	80
81	5	19	80	81
82	5	44	34	82
83	5	59	82	83
84	5	19	83	84
85	5	34	49	85
86	5	19	85	86
87	5	19	39	87
88	6	81	84	88
89	6	86	88	89
90	8	87	89	90
91	11	34	39	91

```
 92    5  14  54  92
 93    5  44  92  93
 94    5  19  93  94
 95    5  44  59  95
 96    5  19  95  96
 97    5  49  19  97
 98    6  94  96  98
 99    8  97  98  99
100   11  44  49 100
101    5  14  54 101
102    5  19 101 102
103    5  59  19 103
104    8 102 103 104
105   11  54  59 105
106    7  14  19 106
107    4  69 107
108    4  73 108
109    6 107 108 109
110   11  77  90 110
111   11  91  99 111
112   11 100 104 112
113   11 105 106 113
114    5 110 111 114
115    5 112 114 115
116    5 113 115 116
117    2  69
118    2  76
119    2 109
120    2 110
121    2 111
122    2 112
123    2 113
124    2 116
125   22  21 117
126   24 118 119  24  29


PIN ASSIGNMENTS
 PIN ADJACENT GATES
   1    1  20  30  40  50
   2    2  22  32  42  52
   3    3  25  35  45  55
   4    4  26  36  46  56
   5    5  15  20  26
   6    6  21  22  27
   7    7  16  30  36
   8    8  31  32  37  78
   9    9  17  40  46
  10   10  41  42  47
  11   11  18  50  56
  12   12  51  52  57
  13   13  19
  14   14  73  92 101 106
  15   15  23  25
  16   16  33  35
  17   17  43  45
  18   18  53  55
  19   19  81  84  86  87  94  96  97 102 103 106
```

```
20   20   21
21   21  125
22   22   23
23   23   24
24  126   61   62   64   70   74   77
25   25   28
26   26   28
27   27   29
28   28   29
29  126   60   77
30   30   31
31   31   34
32   32   33
33   33   34
34   34   62   64   70   74   80   82   85   91
35   35   38
36   36   38
37   37   39
38   38   39
39   39   61   87   91
40   40   41
41   41   44
42   42   43
43   43   44
44   44   65   71   75   79   82   93   95  100
45   45   48
46   46   48
47   47   49
48   48   49
49   49   63   85   97  100
50   50   51
51   51   54
52   52   53
53   53   54
54   54   72   76   78   92  101  105
55   55   58
56   56   58
57   57   59
58   58   59
59   59   66   83   95  103  105
60   60   67
61   61   67
62   62   63
63   63   68
64   64   65
65   65   66
66   66   69
67   67   68
68   68   69
69   69  107  117
70   70   71
71   71   72
72   72   73
73   73  108
74   74   75
75   75   76
76   76  118
77   77  110
```

```
 78  78  79
 79  79  80
 80  80  81
 81  81  88
 82  82  83
 83  83  84
 84  84  88
 85  85  86
 86  86  89
 87  87  90
 88  88  89
 89  89  90
 90  90 110
 91  91 111
 92  92  93
 93  93  94
 94  94  98
 95  95  96
 96  96  98
 97  97  99
 98  98  99
 99  99 111
100 100 112
101 101 102
102 102 104
103 103 104
104 104 112
105 105 113
106 106 113
107 107 109
108 108 109
109 109 119
110 110 114 120
111 111 114 121
112 112 115 122
113 113 116 123
114 114 115
115 115 116
116 116 124
117 125  24
118  24 126
119  29 126


LEVELLING
FLEVEL =              3 PLEVEL =             33 TOPLEV =            123
SCANNING SEQUENCE
 125  24 126  60  77 110 120 114 115 116 124  74  75  76 118  70  71  72  73 108
  64  65  66  62  63  61  67  68  69 117 107 109 119  21  23  29  90 111 112 113
  20  22  27   6  28  87  89  91  39  99 100 104 105 106  37  38  25  15  26   5
  86  88  97  98 102 103  35  36  85  49  47  48  45  46  81  84  94  96  19  13
 101  80  83  93  95  59  57  58  55  56   3   4  79  82  34  44  31  33  41  43
  30  16  32  40  17  42  10   7   9  92  14  78  54  51  53   8  50   1  18  52
   2  12  11


LEADFL
   1   2   3   4   5   6   7   8   9  10  11  12  13  14  15  16  17  18  19  20
```

21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60
61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
101	102	103	104	105	106	107	108	109	110	111	112	113	114	115	116	117	118	119	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	26	0	0	0	0	5	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	27
27	25	28	22	23	29	28	29	31	17	19	19	20	13	14	0	6	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	32	32	0	8	0	0	0	9	10	0	2	3	0	

NUMBER OF TESTS = 1

TIME FOR VECTOR COMPUTATION IS 196438

NL = 323031

TEST NUMBER 1

PIN VALUES

PIN	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
????	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
???*	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62
????	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83
???T	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100	101	102	103	104
???I	106	107	108	109	110	111	112	113	114	115	116	117	118	119						
VALUE	0	0	1	1	1	0	0	1	0	1	0	1	0	1	0	1	1	1	1	0
????	0	0	3	0	1	0	1	0	0	0	0	0	1	1	0	1	1	0	0	0
????	0	1	1	0	1	1	0	0	0	0	0	1	1	0	1	1	0	0	0	3
????	3	3	0	0	0	1	3	3	3	2	3	3	2	3	1	1	1	1	1	0
????	0	0	0	1	1	0	1	1	1	1	0	0	0	1	0	1	1	1	0	0
????	0	0	3	3	3	1	1	1	3	3	3	0	1	0						

PRINCIPAL INPUTS

GATE	VALUE
1	0
2	0
3	1
4	1
5	1
6	0
7	0
8	1
9	0
10	1
11	0
12	1
13	0
14	1

PRINCIPAL OUTPUTS

GATE	VALUE
117	1
118	2
119	3

```
 120    3
 121    1
 122    1
 123    1
 124    3


END OF RUN

END OF SDF FILE,   ACCOUNT: 33232-PRZY80     PCY=     327, SPC=     379, PGS=       6, CRD=
```

NBS-114A (REV. 2-8C)

U.S. DEPT. OF COMM. BIBLIOGRAPHIC DATA SHEET (See instructions)	1. PUBLICATION OR REPORT NO. NBSIR 83-2794	2. Performing Organ. Report No.	3. Publication Date September 1983

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ON GENERALIZING THE D-ALGORITHM

5. AUTHOR(S)

J. Scott Provan and Paul Domich

6. PERFORMING ORGANIZATION (If joint or other than NBS, see instructions)

NATIONAL BUREAU OF STANDARDS
DEPARTMENT OF COMMERCE
WASHINGTON, D.C. 20234

7. Contract/Grant No.

8. Type of Report & Period Covered

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10. SUPPLEMENTARY NOTES

☐ Document describes a computer program; SF-185, FIPS Software Summary, is attached.

11. ABSTRACT (A 200-word or less factual summary of most significant information. If document includes a significant bibliography or literature survey, mention it here)

We consider in this paper the d-algorithm of J. P. Roth, which tests for specific faulty behavior in the integrated circuit. We develop a formal and general mathematical description of the algorithm, which allows a large degree of flexibility and extension in its implementation. We include a subsequent FORTRAN coding of such an extended d-algorithm, along with some sample testing.

12. KEY WORDS (Six to twelve entries; alphabetical order; capitalize only proper names; and separate key words by semicolons)

backtrack; d-algorithm; fault-specific testing; VLSI

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