## **Eigenset Generalizations of the Eigenvalue Concept**

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For an *n-by-n* complex matrix A some generalizations of the eigenvalue-eigenvector equation

 $Ax = \lambda x, 0 \neq x \in C^n$ 

are investigated. These take the form

 $AS = \lambda S \text{ or } AS \subseteq \lambda S$ 

where S is a subset of  $C^n$  about which various assumptions are made. For example, it is shown that there exists a finite set  $S \subset C^n$ , the sum of whose elements is not 0, such that  $AS = \lambda S$ , if and only if  $\lambda$  is an eigenvalue of A in the usual sense. The requirement that the sum of the elements of S is not 0 should be viewed as a natural analog of the requirement  $x \neq 0$  in the classical eigenvalue-eigenvector equation.

Key words: Bounded set; convex hull; eigenvalue-eigenvector equation; root of unity.

Let  $M_n(C)$  denote the set of *n*-by-*n* complex matrices. For  $A \in M_n(C)$ , the complex number  $\lambda$  is said to be an *eigenvalue* of A if there exists an  $x \in C^n$  such that

(1) 
$$Ax = \lambda x$$
 and  $x \neq 0$ .

We denote the set of all eigenvalues of A by  $\sigma(A)$ , the *spectrum* of A. For S an arbitrary nonempty subset of  $C^n$ , we define AS and  $\alpha S$ , for  $A \in M_n(C)$  and  $\alpha \in C$ , in the natural ways; that is,  $AS = \{Ax : x \in S\}$  and  $\alpha S = \{\alpha x : x \in S\}$ . We may then consider two generalizations of the classical eigenvalue-eigenvector eq (1):

and

 $(3) AS \subseteq \lambda S,$ 

and ask (analogously to the classical eigenvalue question) "for which complex numbers  $\lambda$  do there exist sets S satisfying (2) or (3)." Of course, if we allow  $S = \{0\}$ , then for any value of  $\lambda$  an S would exist satisfying (2) or (3), and, if we allow  $S = C^n$ , then, for non-singular A, any  $\lambda \neq 0$  satisfies (2) and, for any  $A \in M_n(C)$ , any  $\lambda \neq 0$  satisfies (3). Generally speaking, allowing S to be unbounded results in difficulty putting any restrictions on  $\lambda$ .

EXAMPLE 1: Let S be the eigenspace corresponding to any nonzero eigenvalue (if there is one) of  $A \in M_{\pi}(C)$ . Then, since any nonzero scalar multiple of S is identical to S, it follows that (2) and (3) hold for any  $\lambda \neq 0$ .

**REMARK:** There is a  $\{0\} \neq S \subset C^n$  such that (2) or (3) holds for  $\lambda = 0$ , if and only if A is singular. This means that  $\lambda = 0$  can satisfy (2) or (3) if and only if  $0 \in \sigma(A)$ , i.e. 0 is an eigenvalue in the usual sense.

EXAMPLE 2: Let 
$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$
,  $\lambda = 1$  and  $S = \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$ .

Then (2) is satisfied despite the fact that neither of the two elements of S is an eigenvector.

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In this note we investigate some generalizations of (1) of the type (2) or (3). In each case some restriction regarding 0 is necessary, and these should be viewed as analogs of the second part of (1). (Of course, if  $0 \in S$ , then  $0 \in AS$  and  $0 \in \lambda S$ . Thus, neither (2) nor (3) is disturbed by addition of 0, or deletion of 0 if S does not otherwise intersect the null space of A.) The classical case (1) may be viewed as a special case of (2) or (3) in which S has just one element. The first natural generalization of the one element case is the case in which S is finite; the next, the case in which S is bounded.

**REMARK:** The case of S bounded in (3) might be viewed as a generalization of the instance in which A is a column stochastic matrix,  $\lambda = 1$ , and S is the unit simplex (the convex hull of the *n* coordinate vectors). A matrix is column stochastic if and only if it maps the unit simplex into itself, and, of course, such a matrix has an eigenvalue equal to 1.

We first consider the case in which S is finite. THEOREM 1: Let A  $\epsilon M_n(C)$ . There exists a finite set  $S \subset C^n$  satisfying

$$AS = \lambda S$$

and  $\sum_{v \in \mathcal{S}} v \neq 0$ , if and only if  $\lambda \in \sigma(A)$ .

**PROOF:** If  $\lambda \in \sigma(A)$ , let  $S = \{x\}$  where  $x \neq 0$  is an eigenvector of A corresponding to  $\lambda$ . Then  $AS = \lambda S$ ,  $\sum_{x \neq 0} v \neq 0$  and  $S \subset C^n$  is finite.

On the other hand, suppose  $S \subset C^n$  is finite and satisfies (2) and that  $x \equiv \sum_{v \in S} v \neq 0$ . Then

$$Ax = \sum_{v \in S} Av = \sum_{v \in S} \lambda v = \lambda x$$

which means that  $\lambda \in \sigma(A)$ .

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EXAMPLE 3. The requirement  $\sum_{v \in S} v \neq 0$ " is necessary in theorem 1. If  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ ,  $\lambda = 1$  and  $S = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\}$ , then  $AS = \lambda S$  without  $\lambda \in \sigma(A) = \{\pm i\}$ . The trouble, of course, is that  $\begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix} + \begin{pmatrix} -1 \\ -1 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ , but it should be noted that  $\lambda \in \sigma(A^4)$ , and that  $\lambda = 1 = (-i)i$  where one factor is a fourth root of one and the other lies in  $\sigma(A)$  (cf. Theorem 2 below).

We next consider what happens if the requirement  $\sum_{v \in S} v \neq 0$  of theorem 1 is deleted. This broadens the class of  $\lambda$ 's which may occur. A complex number z is called a *root of unity* if there exists a positive integer k such that  $z^k = 1$ .

**THEOREM 2:** Let A  $\notin$  M<sub>n</sub> (V). There exists a finite set 0  $\notin$  S  $\subset$  C<sup>n</sup> satisfying

$$AS \subseteq \lambda S$$

if and only if  $\lambda = z \alpha$  where z is a root of unity and  $\alpha \in \sigma(A)$ .

**PROOF:** First suppose  $\lambda = z\alpha$  where  $\alpha \in \sigma$  (A) and  $z^k = 1$ . Then let  $S = \{x, zx, \dots, z^{k-1}x\}$  where  $0 \neq x \in C^n$  satisfies  $Ax = \alpha x$ . It follows that zS = S so that  $AS = \alpha S = \alpha(zS) = \lambda S$ . Thus  $0 \in S \subset C^n$  satisfies (3) as was to be shown.

On the other hand, suppose  $0 \notin S \ C^n$  such that  $AS \ \lambda S$  is given. Since S is finite there must exist a sequence of vectors  $x_{i_1}, \cdots, x_{i_k} \in S$  such that

$$Ax_{i_{j}} = \lambda x_{i_{j+1}}, \ j = 1, \ \cdots, \ k - 1$$

and  $Ax_{i_k} = \lambda x_{i_1}$ . It then follows that

 $A^k x_{i_1} = \lambda^k x_{i_1}$ 

and, therefore, that

$$\lambda^k = \alpha^k$$

for some  $\alpha \in \sigma(A)$ . If  $\lambda = 0$ , the desired consequence follows trivially, and, if not, this means that  $z = \frac{\lambda}{\alpha}$  is

a *k*th root of unity. Since  $\lambda = z \cdot \alpha$ , this completes the proof.

REMARK: If  $0 \in S$  is allowed in the context of theorem 2, then any  $\lambda$  may be achieved by letting  $S = \{0, x\}$  where x (possibly 0) is in the null space of A. However, if " $0 \notin S$ " is replaced by " $\{0\} \neq S$ " and " $AS \subseteq \lambda S$ " is replaced by " $AS = \lambda S$ " a valid alternative to theorem 2 results.

We call a set  $S \subset C^n$  bounded if there is some finite number r (depending on S) such that the Euclidean length of each element of S is less than r. We next consider the case of S bounded in (2) or (3). We denote the *convex hull* of  $T \subset C^n$  by Co(T) and the closure of T by  $\overline{T}$ .

THEOREM 3: Let A  $\epsilon$  M<sub>n</sub> (C). There exists a bounded set S  $\subset$  C<sup>n</sup> satisfying

$$AS \subseteq \lambda S$$

and  $0 \notin \overline{\text{Co}(S)}$ , if and only if  $\lambda \in \sigma(A)$ .

PROOF: If  $\lambda \in \sigma(A)$ , then we may choose  $S = \{x\}$  where  $0 \neq x \in C^n$  is an eigenvector of A corresponding to  $\lambda$ .

On the other hand, suppose a bounded subset S of  $C^n$  such that  $AS \subseteq \lambda S$  and  $0 \notin \overline{Co(S)}$  is given. Then it is straighforward to check that  $\hat{S} = \overline{Co(S)}$  satisfies  $A\hat{S} \subseteq \lambda \hat{S}$ . Now, if  $\lambda = 0$ , the desired result is immediate, and if not,  $1/\lambda A$  is a continuous mapping which maps the compact, convex set  $\hat{S}$  into itself. Therefore, by the Brouwer fixed point theorem  $1/\lambda A$  has a fixed point  $x \in \hat{S}$ . Since  $0 \notin \hat{S}$ , this means that x is an eigenvector of A corresponding to  $\lambda$  and completes the proof.

**REMARK:** The assumption  $0 \notin \overline{Co(S)}$  is, of course, crucial in the above argument. If  $0 \in \overline{Co(S)}$ , then 0 might well be the only fixed point of  $1/\lambda A$ .

If we relax the requirement  $0 \notin Co(S)$  the class of allowable  $\lambda$ 's is again broadened. REMARK: If (2) holds it follows in a straightforward way that for any positive integer t,

(4) 
$$A^t S = \lambda^t S.$$

Similarly, if (3) holds it follows that

**THEOREM 4:** Let A  $\epsilon$  M<sub>n</sub>(C). There exists a bounded set  $\{0\} \neq S \subset C^n$  satisfying

$$AS \subseteq \lambda S$$

if and only if  $|\lambda| \ge m = \min_{\alpha \in \sigma(\Lambda)} |\alpha|$ .

**PROOF:** If  $|\lambda| \ge m$ , let  $x \ne 0$  be an eigenvector corresponding to an eigenvalue  $\alpha$  of A for which  $|\alpha| = m$  and let  $S = \{ax:a \in C, |\alpha| \le 1\}$ . Then  $S \ne \{0\}$  and AS = mS while  $\lambda S = |\lambda|S$  so that (3) holds.

On the other hand, suppose that  $\{0\} \neq S \subset C^n$  such that  $AS \subseteq \lambda S$  is given, and select an element  $0 \neq x \in S$ . If  $\lambda$  were 0, then it would follow that Ax = 0 and that  $0 \in \sigma(A)$  so that m would be 0. Thus  $|\lambda| \geq m$  would be satisfied; and therefore we assume from here on that  $\lambda \neq 0$ . By continuity we may assume without loss of generality that A has a complete set of linearly independent eigenvectors  $x_1, \dots, x_n$  corresponding

respectively to the eigenvalues  $\alpha_1, \dots, \alpha_n$ . Then  $x = \sum_{i=1}^n a_i x_i$  for some complex numbers  $a_1, \dots, a_n$  and  $A^t x = \sum_{i=1}^n a_i \alpha_i^t x_i$ . Since (3) implies (5), we obtain that  $\sum_{i=1}^n a_i \left(\frac{\alpha_i}{\lambda}\right)^t x_i \in S$  for all positive integers t. If  $|\lambda|$  were less than m, then the boundedness of S would be contradicted so that we conclude that  $|\lambda| \ge m$ , as was to be shown.

Only slight modifications of the preceding argument yield the following. THEOREM 5: Let A  $\epsilon$  M<sub>n</sub> (C). There exists a bounded set S  $\subset$  C<sup>n</sup> satisfying 0  $\epsilon$  S and

 $AS \subseteq \lambda S$ 

if and only if  $|\lambda| = |\alpha|$  for some  $\alpha \in \sigma(A)$ . THEOREM 6: Let  $A \in M_n(C)$ . There exists a bounded set  $\{0\} \neq S \subset C^n$  satisfying

 $AS = \lambda S$ 

if and only if  $|\lambda| = |\alpha|$  for some  $\alpha \in \sigma$  (A). REMARK: Analogous to (3) we may also consider

(6)  $AS \supseteq \lambda S.$ 

Analysis of (6), however, is similar to that of (3) along the lines of this note. In fact for  $\lambda \neq 0$  and A nonsingular, (6) holds if and only if (3) holds with A replaced by  $A^{-1}$  and  $\lambda$  by  $\lambda^{-1}$ . It is clear that  $\lambda = 0$  satisfies (6) if and only if the intersection of S and the null space of A is nonempty. Also, in case S is finite and  $\lambda \neq 0$ , (6) implies (2).

We close by noting that many questions are suggested by the above observations. For example, what may be said about the geometric and algebraic properties of eigensets S in the senses of (2) and (3)?

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