Propagation of Electromagnetic Waves Through a Continuously Varying Stratified Anisotropic Medium

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Expressions are developed for the transmission and reflection coefficients for propagation of a plane wave through a layered medium, taking account of the effects of the static magnetic field. A matrix formulation is used which allows proceeding to the limit of a continuously varying medium, and series expansions of the fields for this case are developed. The results are expected to have application to interpretation of VLF data obtained within and above the lower ionosphere.

1. Introduction

Theoretical investigations of VLF propagation have primarily been concerned with the region below the ionosphere, as evidenced by the use of semi-infinite model ionospheres not only in earlier semiquantitative studies [Budden, 1951] but also as a reasonable simplifying assumption in current studies [Wait and Walters, 1963a, 1963b]. Even in studies in which a semi-infinite ionosphere is not assumed, the transmission coefficients are often not developed [Wait, 1962a, 1963] or are developed as an incidental part of the analysis [Johler and Harper, 1962]. This emphasis has been consistent with the nature of the available experimental data. However, as data from the ionosphere become available [Rorden et al., 1962], their interpretation requires consideration of propagation into and through the ionosphere. It is the purpose of this paper to provide a framework for this type of calculation.

As is generally the case if tractability is to be maintained, some simplification of the physical situation is desirable. A suitable model for our purposes is a stratified plane ionosphere with plane waves obliquely incident. The earth’s magnetic field is included since it is expected to allow propagation through the ionosphere (whistler modes) at some frequencies and angles of incidence. It is assumed to have constant strength but to be at an arbitrary angle to the plane of stratification.

The equations are first developed for an arbitrary number of homogeneous layers, a problem considered by Johler and Harper [1962]. A different system of representation is used in this study, allowing the number of layers to be increased by multiplying together more and more matrices of constant (4×4) size rather than by increasing the size of a single matrix. This form has the advantage of allowing use of available computer subroutines to handle the matrices and the use of slow access storage for matrices not currently being operated upon. The values of the matrix elements are determined by the solution of the Booker quartic for each layer. The terminology used is that employed by Yabroff [1957] in treating a single planar boundary.

In the next step, it is assumed that the layers become infinitely thin while becoming infinite in number, to represent a continuously varying medium. A series expansion for the transmission and reflection coefficients is then obtained. The reflection coefficients series have the form found by Wait [1962a] and by Heading [1963] by an iterative procedure. A physical interpretation of the series terms as representing multiple reflections within the varying medium is obtained by examining the development of the equations for the limiting conditions.
2. Layered Medium

2.1. Equations Holding in Each Homogeneous Slab

Waves propagating in a homogeneous plasma medium are governed by Maxwell's equations and (neglecting the ions) by the equations of motion for the electrons:

\[ \nabla \times \mathbf{E} = -\mu_0 \frac{\partial \mathbf{H}}{\partial t} \]  
(1)

\[ \nabla \times \mathbf{H} = -N e \mathbf{V} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \]  
(2)

\[ m \frac{\partial \mathbf{v}}{\partial t} = -e \mathbf{E} - m v \mathbf{V} - \mu_0 \epsilon_0 (\mathbf{V} \times \mathbf{H}_0) \]  
(3)

where \( \mathbf{E} \) and \( \mathbf{H} \) are the wave fields, \( \mathbf{V} \) the electron velocity, \( N \) the electron density, \( e \) the electron charge, \( m \) the electron mass, \( v \) the classical electron collision frequency, \( \epsilon_0 \) the dielectric constant of free space, and \( \mu_0 \) the permittivity of free space. If the energy dependence of the collision frequency, \( v \), is considered, \( v \) is replaced by a complex, frequency dependent quantity, as discussed by Wait [1962b] and Johler and Harper [1962]. This substitution does not affect the equations to be derived below.

These equations assume that ion motion can be neglected and that the plasma is “temperate” [Allis et al., 1963], i.e., that the electron motion occurs over only a small fraction of a wavelength and that the electron thermal speed is much larger than the induced speed. These assumptions imply that the wave magnetic field \( \mathbf{H} \) is much less than the earth’s field \( \mathbf{H}_0 \) and hence can be dropped from the last term on the right in (3).

The notation used follows Yabroff [1957]; a right-hand cartesian coordinate system is defined with \( x \) normal to the plane of stratification, so that \( N \) and \( v \) are functions of \( x \) only. The direction of a vector in this coordinate system is specified by the angles \( \alpha \) and \( \beta \). Beta is the angle between the vector and a unit vector in the \( x \) direction; \( \alpha \) is the angle between the projection of the vector in the \( y-z \) plane and a unit vector in the \( z \) direction, as shown in figure 1. \( \mathbf{H}_0 \) is taken to lie in the \( x-z \) plane at an angle \( \beta_H \) to the \( x \) axis. The incident wave in free space is taken to be propagating with its wave normal given by angles \( \alpha_I \) and \( \beta_I \).

The incident wave will be of the form

\[ F_I = (F_{I0}) \exp \left[ i \omega \frac{\alpha}{c} (et - x \cos \beta_I - y \sin \beta_I \sin \alpha_I - z \sin \beta_I \cos \alpha_I) \right] \]  
(4)

Figure 1. Coordinate system.
where \((F_{10})\) is the complex magnitude of the field at the origin of the coordinate system (taken to be in free space). The reflected wave will be similar, with \(\alpha_R=\alpha_I; \beta_R=(\pi-\beta_I)\). In each homogeneous layer, for such an incident wave, the waves will have the form

\[
F_i = (F_{10}) \exp \left[ i \frac{\omega}{c} (ct - zD - y \sin \beta_I \sin \alpha_I - z \sin \beta_I \cos \alpha_I) \right] \tag{5}
\]

where the continuity of the fields at the boundaries between homogeneous layers has been employed to specify the \(y\) and \(z\) variation. For such waves in a layer, (1), (2), and (3) can be manipulated to eliminate \(\mathbf{H}\) and \(\mathbf{V}\), giving a set of homogeneous equations in the components of \(\mathbf{E}\):

\[
\begin{bmatrix}
m_{11} - a^2 & m_{12} + a_T D & m_{13} + a_L D \\
-m_{23} + a_T D & m_{22} - D^2 - a_L^2 & m_{25} + a_L a_T \\
m_{33} + a_T D & -m_{23} + a_L a_T & m_{33} - D^2 - a_L^2
\end{bmatrix}
\begin{bmatrix}
E_z \\
E_y \\
E_x
\end{bmatrix} = 0. \tag{6}
\]

The particular form of the matrix multiplying \(\mathbf{E}\) in (6) is obtained by deriving the conductivity tensor relating \(\mathbf{V}\) to \(\mathbf{E}\) from (3), eliminating \(\mathbf{H}\) from (1) and (2), and replacing \(N_0 \mathbf{V}\) in the resulting equation by the conductivity tensor multiplying \(\mathbf{E}\). A detailed derivation of the equivalent (for a different choice of coordinates) of (6) is given by Budden [1961].

The parameters \(m_{ij}\) and \(a\) are

\[
m_{11} = 1 - \frac{s^2 - h_L^2}{s(s^2 - h^2)}, \quad m_{22} = 1 - \frac{s}{s^2 - h^2}, \quad m_{33} = 1 - \frac{s^2 - h_T^2}{s(s^2 - h^2)} \tag{a}
\]

\[
m_{12} = -i \frac{h_T}{s^2 - h^2}, \quad m_{13} = \frac{h_T h_L}{s(s^2 - h^2)}, \quad m_{25} = -i \frac{h_T}{s^2 - h^2}, \quad m_{23} = -i \frac{h_L}{s^2 - h^2} \tag{b}
\]

\[
a = \sin \beta_I, \quad a_L = a \cos \alpha_I, \quad a_T = a \sin \alpha_I \tag{c}
\]

in terms of

\[
s = \frac{1 - i(v/2\pi)}{(f_0^2/f^2)} \tag{8}
\]

and

\[
h = \frac{f_H^2}{f_0^2} \tag{a}
\]

\[
h_L = h \cos \beta_H \tag{b}
\]

\[
h_T = h \sin \beta_H \tag{c}
\]

Finally, the quantities \(f, f_0\), and \(f_H\) are the familiar wave frequency, plasma frequency, and gyrofrequency, respectively:

\[
f_0^2 = \frac{N_0 e^2}{4 \pi^2 \epsilon_0 m} \tag{11}
\]

\[
f_H = \frac{\mu_0 e \Pi_0}{2 \pi m} \tag{12}
\]

Nontrivial solutions to (6) exist only if the determinant of the matrix multiplying \(\mathbf{E}\)
vanishes. This condition produces a quartic in $D$ to be solved for each layer:

$$a_4D^4 + a_3D^3 + a_2D^2 + a_1D + a_0 = 0$$  \hspace{1cm} (13)

where

$$a_4 = m_{11} \quad (a)$$

$$a_3 = 2a_Dm_{13} \quad (b)$$

$$a_2 = m_{33}a_T^2 + m_{22}a_T^2 + m_{11}(a^2 - m_{33} - m_{22}) + m_{12}^2 + m_{13}^2 \quad (c)$$

$$a_1 = 2m_{13}(a_T^2 + a_Ta_L^2) - 2a_Dm_{22}m_{13} \quad (d)$$

$$a_0 = (m_{33} - a_T^2)(m_{22} - a_L^2)(m_{11} - a^2) + (m_{33} - a_T^2)m_{12}^2 - (m_{22} - a_L^2)m_{13}^2 + 2m_{23}m_{12}m_{13} - (a_T^2a_L^2 - m_{23}^2)(m_{11} - a^2) \quad (e)$$  \hspace{1cm} (14)

Thus there are generally four modes possible in the medium, two upgoing and two downgoing.

Equations (13) and (14) are the Booker quartic [Booker, 1939] in the form used by Yabroff. He needed only two roots for $D$ corresponding to upgoing waves since only a single boundary with a semi-infinite medium on either side was treated. For a number of boundaries, all four modes have to be included except in the final semi-infinite medium.

The properties of the wave in the medium are contained in $D$. The wave has its phase normal in the direction

$$\alpha_M = \alpha_l \quad (a)$$

$$\beta_M = \tan^{-1}\left(\frac{\sin \beta_l}{\Re(D)}\right) \quad (b)$$  \hspace{1cm} (15)

which is Snell’s law. The phase velocity is

$$V_p = \frac{c}{(\Re(D))^2 + \sin^2 \beta_l} \quad (16)$$

The wave is seen to be an inhomogeneous plane wave since it is attenuated exponentially in the $x$ direction at a rate of

$$\frac{\omega}{c} \Im(D) \quad (17)$$

nepers per unit distance.

2.2. At the Boundaries

At each boundary the tangential components of $\mathbf{E}$ and curl $\mathbf{E}$ have to be continuous. Thus the equations can be written

$$E_{y-} = E_{y+} \quad (a)$$

$$(\nabla \times \mathbf{E})_{y-} = (\nabla \times \mathbf{E})_{y+} \quad (b)$$

$$E_{z-} = E_{z+} \quad (c)$$

$$(\nabla \times \mathbf{E})_{z-} = (\nabla \times \mathbf{E})_{z+} \quad (d)$$  \hspace{1cm} (18)

where $(-)$ and $(+)$ refer to the field just below and just above the boundary, respectively.

The equations may conveniently be written in terms of matrices

$$A_{i-}E_{i-} = A_{i+1}E_{i+1+} \quad (19)$$

where $E_{i-}$ and $E_{i+}$ are column vectors of independent (one for each mode) components of $\mathbf{E}$ in the two mediums $i$ and $i+1$ forming the boundary, and $A_i$ and $A_{i+1}$ are matrices, characteristic of each medium, relating the elements of $E_{i-}$ and $E_{i+}$, respectively, to $E_{i}$, $(\nabla \times \mathbf{E})_{y}$, $E_{z}$, and
Thus \((a_{i+1}E_i)_y\) is the \(y\) component of \(E_{i+1}\), \((a_{i+2}E_{i+2})_y\) is the \(y\) component of \((\nabla \times E)_{i+2}\), \((a_{i+3}E_{i+3})_y\) is the \(y\) component of \((\nabla \times E)_{i+3}\), and so on.

For the incident and reflected waves below the first boundary, the independent components of \(E_i\) are conveniently chosen to be the components of \(E\) in \((E_i)_y\) and perpendicular to \((E_i)_x\) the plane of propagation. Thus

\[
E_i = \begin{pmatrix} (E_x)_i \\ (E_y)_i \\ (E_z)_i \\ (E_\theta)_i \end{pmatrix}
\]

(20)

where the subscripts 1 and 2 refer to the incident and reflected waves, respectively. The matrix \(A_i\) is, then,

\[
A_i = \begin{pmatrix} \cos \alpha_i & \sin \alpha_i \cos \beta_i & \cos \alpha_i & \sin \alpha_i \cos \beta_i \\ -\sin \alpha_i \cos \beta_i & \cos \alpha_i (\cos^2 \beta_i - \sin^2 \beta_i) & \sin \alpha_i \cos \beta_i & -\cos \alpha_i \\ -\sin \alpha_i & \cos \alpha_i \cos \beta_i & -\sin \alpha_i & \cos \alpha_i \cos \beta_i \\ -\cos \alpha_i \cos \beta_i & \sin \alpha_i (\sin^2 \beta_i - \cos^2 \beta_i) & \cos \alpha_i \cos \beta_i & \sin \alpha_i \end{pmatrix}
\]

(21)

In the plasma mediums a more convenient choice of independent variables is \(E_y\) for each mode:

\[
E_i = \begin{pmatrix} (E_y)_i \\ (E_x)_i \\ (E_z)_i \\ (E_\theta)_i \end{pmatrix}
\]

(22)

The matrices \(A_i\) are then

\[
A_i = \begin{pmatrix} 1 & 1 & 1 & 1 \\ a_{i21} & a_{i22} & a_{i23} & a_{i24} \\ a_{i31} & a_{i32} & a_{i33} & a_{i34} \\ a_{i41} & a_{i42} & a_{i43} & a_{i44} \end{pmatrix}
\]

(23)

where

\[
(a_{i})_{2j} = - \cos \alpha_i \sin \beta_i S_j^i + D_j R_j^i
\]

(a)

\[
(a_{i})_{3j} = R_j^i
\]

(b)

\[
(a_{i})_{4j} = -D_j + \sin \alpha_i \sin \beta_i S_j^i
\]

(c)

(24)

The quantities \(R_j^i\) and \(S_j^i\) are the cofactor ratios of the matrix in (6), which relate \(E_x\) and \(E_z\), respectively, to \(E_y\) for the \(j\)th mode in the \(i\)th layer:

\[
R_j^i = \frac{(-m_{22} + a_T D_j)(-m_{23} + a_T a_T) - [m_{22} - (D_j)^2 - a_T^2](m_{13} + a_T D_j)}{(m_{23} + a_T a_T)(m_{13} + a_T D_j) - (-m_{12} + a_T D_j)[m_{33} - (D_j)^2 - a_T^2]}
\]

(25)

\[
S_j^i = \frac{[m_{22} - (D_j)^2 - a_T^2][m_{33} - (D_j)^2 - a_T^2] - (m_{23} + a_T a_T)(-m_{23} + a_T a_T)}{(m_{23} + a_T a_T)(m_{13} + a_T D_j) - (-m_{12} + a_T D_j)[m_{33} - (D_j)^2 - a_T^2]}
\]

(26)

It must be remembered that the \(m\) is also characteristic of the \(i\)th medium.
Finally, at the last boundary, the reflected modes are not present in the upper medium, so that

\[ E_{N+} = \begin{pmatrix} (E_\perp)_1 \\ (E_\parallel)_2 \\ 0 \\ 0 \end{pmatrix} \]

(27a)

where the subscript \( N \) is the number of boundaries. The form of \( A_N \) need not be changed, however.

If the final semi-infinite medium is free space, a better choice for the transmitted modes would be

\[ E_{N+} = \begin{pmatrix} (E_\perp)_1 \\ (E_\parallel)_1 \\ 0 \\ 0 \end{pmatrix} \]

(27b)

with \( A_N \) given by (21).

To relate the incident and reflected waves at each boundary of a layer, another matrix, \( \Delta_i \), is defined:

\[ E_{t-} = \Delta_i E_{t+} \]

(28)

where \( \Delta_i \) is diagonal

\[ \Delta_i = \begin{pmatrix} e^{-i\omega d_i/d_1} & 0 & 0 & 0 \\ 0 & e^{-i\omega d_i/d_2} & 0 & 0 \\ 0 & 0 & e^{-i\omega d_i/d_3} & 0 \\ 0 & 0 & 0 & e^{-i\omega d_i/d_4} \end{pmatrix} \]

(29)

and where \( d_i \) is the thickness of the \( i \)th layer.

With the above notation, the incident and reflected waves at the first boundary can be related to the transmitted wave at the last boundary by a series of matrix multiplications.

\[ E_{N+} = (A_N^{-1}A_{N-1}\Delta_{N-1}A_{N-1}^{-1}A_{N-2}\Delta_{N-2}A_{N-2}^{-1}\ldots A_1\Delta_1A_1^{-1}A_0)E_{0-} \]

(30)

We define the product matrix, \( M \), so that (30) is more concisely written:

\[ E_{N+} = ME_{0-} \]

(31)

where

\[ M = (A_N^{-1}A_{N-1}\Delta_{N-1}A_{N-1}^{-1}\ldots A_1\Delta_1A_1^{-1}A_0). \]

(32)

Note that if a layer, \( i=a \), is allowed to vanish by letting \( d_a \) become zero, \( \Delta_a \) becomes the identity matrix and the product \( A_a\Delta_aA_a^{-1} \) is also the identity matrix.

By splitting \( E_{0-} \) into the incident and reflected modes

\[ E_{0-} = E_I + E_R \]

(33)
where \( E_i \) and \( E_R \) have the form

\[
E_i = \begin{pmatrix}
(E_{\perp})_1 \\
(E_{\parallel})_1 \\
0 \\
0
\end{pmatrix}
\]

(a)

\[
E_R = \begin{pmatrix}
0 \\
0 \\
(E_{\perp})_2 \\
(E_{\parallel})_2
\end{pmatrix}
\]

(b)

(34)

(31) can be rewritten to give solutions \( E_{N+} = -E_T \) and \( E_R \) in terms of the source \( E_i \):

\[
M^{-1}E_T - E_R = E_i.
\]

(35)

By defining a matrix, \( E_s \), that combines \( E_T \) and \( E_R \), (35) can be written

\[
NE_s = E_i
\]

(36)

where \( N \) is seen to be of the form

\[
N = \begin{pmatrix}
0 & 0 \\
0 & 0 \\
-1 & -1 \\
-1 & -1
\end{pmatrix}
\]

(37)

where the notation means that the left-hand half is identical with the left-hand of \( M^{-1} \) and the right-hand half is as shown; while \( E_s \) is the column vector

\[
E_s = E_T + E_R
\]

(a)

\[
\begin{pmatrix}
(E_{\parallel})_1 \\
(E_{\perp})_1 \\
(E_{\parallel})_2 \\
(E_{\perp})_2
\end{pmatrix}
\]

(b)

(38)

Having solved the quartic, (13) for the roots, \( D \), in each medium, the elements of the matrices forming \( M \), and hence \( N \), can be evaluated. The transmitted and reflected waves then are given as solutions of the four linear equations (36). The ratios of \( (E_{\perp})_1 \) to \( (E_{\perp})_2 \) and \( (E_{\parallel})_2 \), and of \( (E_{\parallel})_1 \) to \( (E_{\parallel})_2 \) and \( (E_{\perp})_2 \) give the reflection coefficients \( R_{\perp}, R_{\parallel}, R_{|\perp,|} \) and \( R_{\perp} \). When the second semi-infinite medium is free space the transmission coefficients can be similarly defined.
Once the transmitted and reflected waves have been determined the fields within the medium can be found. At some boundary within the medium, we have, in the \( i \)th layer just above the boundary,
\[
E_{0i} = A_i^{-1}(A_{i-1}\Delta_i^{-1}A_{i-1}^{-1} \ldots A_i\Delta_i A_i^{-1})A_0 E_0
\]
where the reflected wave components of \( E_0 \) are now known, so that they need only be inserted.

There is an interesting relationship between (36) and the expressions developed by Johler and Harper [1962] and Wait [1963]. Equation (36) is equivalent to the matrix equation (33) of Johler and Harper, but it represents the effect of many slabs by a product 4 x 4 matrices rather than by a single matrix which grows in rank. Wait uses a method of development for a stratified ionosphere similar to that of Johler and Harper in treating the wave propagation problem in spherical coordinates where the earth and ionosphere are considered the boundaries of a waveguide. In this case, the resulting equation does not involve an arbitrary incident plane wave. \( E_r \) and \( E_t \) are solved for simultaneously (the earth provides another boundary, which would give two more equations and hence 6 x 6 matrices in the formulation employed here), so that the determinant of the equivalent of the matrix \((N-I)\) for the spherical coordinates would yield the waveguide model equation.

2.3. Limit of a Continuously Varying Medium

The development in section 2 is particularly suited to proceeding to the limit of a continuously varying medium. Swift [1962] employed it to investigate the characteristics of the coupling coefficients appearing in the differential equations. In this study we are more interested in developing forms for the reflection and transmission coefficient. Consider the form of the matrix \( M \) (32). It is seen to be a product of elements
\[
\Gamma_i = A_i\Delta_i A_i^{-1}
\]
for each layer, except the semi-infinite layers on each end. The terms of \( \Gamma_i \) have the form
\[
(\Gamma_i)_{jk} = (A_i)_{jk} (\Delta_i)_{jm} (A_i^{-1})_{mk}.
\]
By noting that \( \Delta_i \) is diagonal,
\[
(\Delta_i)_{jk} = \delta_{jk} e^{-\frac{i\omega}{c}D_i^j}
\]
on one summation of (41) can be eliminated, leaving
\[
(\Gamma_i)_{jk} = (A_i)_{jk} (\Delta_i^{-1})_{1k} e^{-\frac{i\omega}{c}D_i^j}
\]
where the \( d_i \) are all taken the same.

As the thickness of each layer is decreased, \( \Gamma_i \) approaches the identity matrix. By expanding \( \Delta_i \) in a power series for each term, we get
\[
\Delta_i = \begin{pmatrix}
1 - i\frac{\omega}{c}D_i^1 + \frac{(i\frac{\omega}{c}D_i^1)^2}{2!} + \ldots & 0 & 0 & 0 \\
0 & 1 - i\frac{\omega}{c}D_i^2 + \ldots & 0 & 0 \\
0 & 0 & 1 - i\frac{\omega}{c}D_i^3 + \ldots & 0 \\
0 & 0 & 0 & 1 - i\frac{\omega}{c}D_i^4 + \ldots
\end{pmatrix}
\]
(44)

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\[ \Gamma_i = I - i \frac{\omega}{c} d \gamma'_i + \left( i \frac{\omega}{c} d \right)^2 \gamma''_i + \ldots \]  
\[ (45) \]

Note that the \( i \frac{\omega}{c} d \) factors are taken to multiply each term of the \( \gamma_i \). The \( \gamma_i \) have the form

\[ (\gamma_i)_r = (A_i)_r (A_i^{-1})_{1k} D_k^1 \]  
\[ (\gamma'_i)_r = (A_i)_r (A_i^{-1})_{1k} (D_k^1)^2 \]
\[ (46) \]

and so on.

The product of the matrices \( \Gamma_i \) can then be written

\[ \prod_{i=1}^{N} \Gamma_i = \left[ I - i \frac{\omega}{c} d \gamma'_1 + \left( i \frac{\omega}{c} d \right)^2 \gamma''_1 + \ldots \right] \left[ I - i \frac{\omega}{c} d \gamma'_2 + \ldots \right] \ldots \left[ 1 - i \frac{\omega}{c} d \gamma'_N + \ldots \right] \]  
\[ (47) \]

This can now be expanded:

\[ \prod_{i=1}^{N} \Gamma_i = I - i \frac{\omega}{c} d \sum_{i=1}^{N} \gamma'_i + \left( i \frac{\omega}{c} d \right)^2 \sum_{i=1}^{N} \sum_{j=1}^{N} \gamma \gamma'_j + \ldots \left( \frac{\omega}{c} d \right)^3 \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{k=1}^{N} \gamma \gamma'_j \gamma''_k + \ldots \]  
\[ + \left( i \frac{\omega}{c} d \right)^3 \sum_{i=1}^{N} \sum_{j=1}^{N} \gamma \gamma'_j + \ldots + \ldots \]  
\[ (48) \]

In the limit as \( d \) approaches zero, only the terms in \( \gamma' \) of (48) remain finite, there being on the order of \((1/d)^n\) terms in the summations for the \( n \)th term. For the terms containing \( \gamma'' \) or a higher order, the number of terms in the summations increases as a lower power of \((1/d)\) than the power of \( d \) appearing as a multiplier. Thus we are left with the series

\[ \prod_{i=1}^{N} \Gamma_i \approx I - i \frac{\omega}{c} d \sum_{i=1}^{N} \gamma'_i + \left( i \frac{\omega}{c} d \right)^2 \sum_{i=1}^{N} \sum_{j=1}^{N} \gamma \gamma'_j + \ldots \]  
\[ (49) \]

as \( d \) becomes small. In the limit the sums become integrals, and we have

\[ M = A_u^{-1} \left\{ I - i \frac{\omega}{c} \int_{x_L}^{x_u} \gamma'(x) dx + \left( i \frac{\omega}{c} \right)^2 \int_{x_L}^{x_u} d x \gamma'(x) \int_{x_L}^{x_u} d y \gamma'(y) + \ldots \right\} A_L \]  
\[ (50) \]

where \( A_u \) and \( A_L \) are the matrices for the upper and lower semi-infinite media, respectively. This form of \( M \) can be evaluated if the quartic for \( D \) is solved with \( x \) a parameter to give a \( D(x) \) for each mode.

The fields within the varying medium are now given by the limit of (39), which is

\[ E(x) = A^{-1} \left[ I - \left( i \frac{\omega}{c} \right) \int_{x_L}^{x_U} \gamma'(y) dy + \left( i \frac{\omega}{c} \right)^2 \int_{x_L}^{x_U} d y \gamma'(y) \int_{x_L}^{x_U} d z \gamma'(z) + \ldots \right] A_E E_0 \]  
\[ (51) \]

where the reflected wave elements of \( E_0 \) are now known.

The form for \( M \) given in (50) should be compared with the solution for the reflection coefficients given by Wait [1962a] and by Heading [1963] for a continuously varying medium. It is seen that the terms for the reflection and transmission coefficients in the present series have the same form as those produced by the iterative procedure used by Wait to solve a differential equation for the reflection coefficient and by Heading to solve an integral equation for the fields for an isotropic ionosphere. The present derivation is thought to give additional insight into the nature of the expansion, as well as to provide expressions for the transmission coefficients for an anisotropic ionosphere. Heading also derives an integral equation for the fields in an anisotropic ionosphere but does not develop the series solution.

From the series in (48) it is seen that the higher terms express multiple reflections within the varying medium. This interpretation can be made clearer by considering a single boundary,
for which the equation for finite slab thicknesses was written

$$ A_t E_{t-} = A_{t+1} E_{t++}. $$

(19)

$E_{t+1-}$, the transmitted incident wave at the next boundary, is given by inserting (28) into (19) and rearranging:

$$ E_{t+1-} = (\Delta_{t+1} A_{t+1}^{-1} A_t) E_{t-}. $$

(52)

It is seen that $E_{t+1-}$ is given by the product of a matrix of the form of $\Gamma_t$ with $E_{t-}$.

Consider now the relationship between the incident, reflected, and transmitted waves for an inhomogeneous region:

$$ E_{N+} = ME_{0-} $$

(32)

where $E_{N+}$ is the transmitted wave, and $E_{0-}$ is the incident and reflected waves. Keeping (52) in mind, we can interpret the form of $M$ given by (50) as follows. Using only the first term of the series in (50), we get the same relation as for a sharp boundary between the upper and lower semi-infinite mediums:

$$ E_{N+}^0 = A_{u}^{-1} A_L E_{0-}. $$

(53)

The second term alters this result by the reflection of the undiminished incident wave throughout the medium:

$$ E_{N+}^1 = \left[ A_{u}^{-1} \left( -i \frac{\omega}{c} \int_{x_L}^{x_u} \gamma'(x) dx \right) A_L \right] E_{0-}. $$

(54)

The $A_L^{-1}$ and $A_L$, of course, couple this reflected wave to the semi-infinite mediums on either side of the inhomogeneous region.

The third term then reflects the wave given by (54) throughout the medium

$$ E_{N+}^2 = A_{u}^{-1} \left\{ -i \frac{\omega}{c} \int_{x_L}^{x_u} dx \gamma'(x) \left[ \int_{x}^{x_u} dy \gamma'(y) \right] \right\} A_L E_{0-} $$

(55)

where now the inner integral from $x$ to $x_u$ gives the wave at $x$ that is due to the incident wave, $E_{0-}$, being reflected from the region beyond $x$; the outer integral then gives the result of reflection of this wave throughout the medium. Higher terms in the series are similarly interpreted. This interpretation of the series terms agrees with that given by Westcott [1962], who considered the scattering process from infinitesimal slabs of the medium.

We can check this for a single homogeneous slab, in which $D(x)$ and, hence, $\gamma'$ are constant. Doing the indicated integrals in (48) produces the series

$$ M = A_{u}^{-1} \left\{ I - i \frac{\omega}{c} \gamma'(x_u-x_L) - \left( \frac{\omega}{c} \right)^2 \gamma'^2 \left( \frac{x_u-x_L}{2} \right)^2 + \ldots \right\} A_L $$

(56)

which is recognized as the series for $\Gamma$ for a single slab where the exp $\left[ -i \frac{\omega}{c} D_t(x_u-x_L) \right]$ terms in $\Delta$ (41) have been expanded in a power series.

3. List of Symbols

- $E$: electric wave vector
- $H$: magnetic wave vector
- $H_0$: static (earth’s) magnetic field vector
- $V$: electron velocity vector
- $N$: electron density, number of mediums, subscript for final medium
- $m$: electron mass
- $\nu$: electron collision frequency

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1 When the limit of $d \to 0$ is taken $A_{t+1} \to A$ and $\Delta_{t+1} \to \Delta$. Also, as the matrices become diagonal the order of multiplication becomes immaterial.
\[ \varepsilon_0 = \text{dielectric constant for free space} \]
\[ \mu_0 = \text{permittivity for free space} \]
\[ x, y, z = \text{coordinate axes or variables of integration} \]
\[ \alpha, \beta = \text{angles specifying direction of a vector in coordinate system} \]
\[ \beta_H = \text{direction of static field} \]
\[ F = \text{any wave field component} \]
\[ I, T, R = \text{subscripts for incident, transmitted, reflected quantities} \]
\[ c = \text{speed of light} \]
\[ i = \text{super- or subscript for ith layer, or for matrix quantities, or the imaginary unit} \]
\[ m_{ij} = \text{parameters appearing in quartic determinant—see (7)} \]
\[ a, a_L, a_T = \text{angular parameters for wave normal—see (8)} \]
\[ s, h, h_L, h_T = \text{parameters characterizing plasma—see (9) and (10)} \]
\[ D_j = \text{variable in Booker quartic, root for jth mode in ith layer} \]
\[ f = \text{wave frequency} \]
\[ f_0 = \text{plasma frequency} \]
\[ f_H = \text{gyrofrequency} \]
\[ V_p = \text{phase velocity} \]
\[ \omega = \text{wave angular frequency} \]
\[ A = \text{matrix relating field component of each mode to field components tangential to boundaries} \]
\[ a_{ij} = \text{components of } A \]
\[ E_j = \text{component of } E_i \text{ lying in the plane containing the wave normal} \]
\[ E_i = \text{component of } E_i \text{ lying perpendicular to plane containing the wave normal} \]
\[ R_j = \text{ratios of electric field components for jth mode in ith layer—see (25) and (26)} \]
\[ S_j = \text{matrix relating fields across ith layer—see (29)} \]
\[ d_i = \text{thickness of ith layer} \]
\[ M = \text{matrix relating incident, transmitted, and reflected waves—see (32)} \]
\[ E_{S, T, R, N, L} = \text{column matrices containing a component of } E \text{ for each mode, see (20), (22), (27), and (34)} \]
\[ N = \text{matrix relating } E_S \text{ to } E_T \text{—see (37)} \]
\[ \Gamma_i = \text{matrix product for ith layer—see (40)} \]
\[ \gamma_{ij} = \text{matrix terms of series expansion of } \Gamma_i \text{—see (44)} \]
\[ I = \text{identity matrix} \]
\[ u, L = \text{subscripts for upper and lower semi-infinite mediums respectively.} \]

4. References


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