

The Condition of Certain Matrices, III¹

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The condition-numbers of certain matrices associated with various discretizations of the two-dimensional Laplacian operator are estimated. The condition-number gives an estimate of the error obtained by solving the corresponding systems of simultaneous linear equations.

1. *Introduction.* In a previous paper [Todd, 8a]³ the condition of a matrix associated with a particular method of solving a simple partial differential equation was discussed. Certain experimental computations of D. M. Young and his collaborators [Young, 13] suggested the discussion of other methods of handling the same equation. The *P*-condition number of a matrix *M* is defined as λ/μ where λ is the maximum and μ is the minimum of the absolute values of the eigenvalues of *M*; it gives a measure of the difficulty in the numerical inversion of *M*, or, more precisely, of an error in the inverse computed by an elimination method [von Neumann and Goldstine, 11; Todd, 8a, 9].

In [8a] we considered the solution of the Laplace equation in a unit square, with given boundary values. We then used the following five-point approximation to the Laplace operator:

$$(1.1) \quad z_{xx} + z_{yy} = h^{-2}[z(r-1, s) + z(r, s-1) - 4z(r, s) + z(r, s+1) + z(r+1, s)],$$

where $z(r, s) = z(rh, sh)$ and $h = 1/(n+1)$, *n* a positive integer. Following Milne [4, p. 131] we indicate this approximation by the "stencil"

$$\left\{ \begin{array}{ccc} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{array} \right\}.$$

(This has been called a "computational molecule" by Bickley [2]). The $n^2 \times n^2$ matrix which corresponds to the equations for the $z(r, s)$ can be indicated as

$$Z_1 = \begin{pmatrix} \dots & & & & \\ \dots & I & X & I & \dots \\ \dots & & & & \dots \end{pmatrix} \quad \text{where} \quad X = \begin{pmatrix} \dots & & & & \\ \dots & 1 & -4 & 1 & \dots \\ \dots & & & & \dots \end{pmatrix}$$

is an $n \times n$ matrix and *I* is the $n \times n$ unit matrix. Here, and elsewhere, for brevity, we have indicated only the general row in the triple diagonal matrices. For clarity we describe Z_1 and *X* in words. The matrix Z_1 is an $n^2 \times n^2$ matrix partitioned into $n \times n$ blocks; of these the diagonal blocks are all *X* and the blocks adjacent to the diagonal are unit matrices. The matrix *X* is an $n \times n$ matrix with diagonal elements all -4 and the elements adjacent to the diagonal all 1: In symbols $X = (x_{ij})$ where $x_{ii} = -4$, $i = 1, 2, \dots, n$, and for $i \neq j$, $x_{ij} = 0$ unless $|i-j|=1$, when $x_{ij} = 1$.

The equations corresponding to the problem

$$z_{xx} + z_{yy} = 0 \text{ in interior,} \quad z = f \text{ on boundary}$$

can be written as

$$Z_1 \mathbf{z} = \mathbf{f}$$

¹ The problems considered here were suggested by lectures of D. M. Young, Jr., in the National Bureau of Standards-National Science Foundation Training Program in Numerical Analysis held in 1957.

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Figures in brackets indicate the literature references at the end of this paper.

This result has been given by Rutherford [6, 7]. It can be verified as follows: If in the matrix C we put $c=b$ and square we obtain essentially the matrix A . In fact if we choose $b=\sqrt{\beta}$, $a=\alpha/\sqrt{\beta}$, then

$$A=C^2+(z-\alpha^2\beta^{-1}-2\beta)I.$$

(2.3) Let F be a matrix of order n^2 , partitioned into an array of n^2 submatrices f_{ij} , each of order n , such that each f_{ij} is a rational function $f_{ij}(\mathbf{a})$ of a fixed matrix \mathbf{a}_2 of order n . If the characteristic values of \mathbf{a} are $\alpha_1, \alpha_2, \dots, \alpha_n$ then those of F are given by the characteristic values of the n matrices

$$(f_{ij}(\alpha_k)), \quad k=1,2,\dots,n,$$

each of order n .

This has been established by Williamson [12]; for extensions see Afriat [1].

3. We begin by discussing another five-point approximation which is represented by the stencil

$$\frac{1}{2} \begin{pmatrix} 1 & 0 & 1 \\ 0 & -4 & 0 \\ 1 & 0 & 1 \end{pmatrix}.$$

Omitting the factor $\frac{1}{2}$, we see that the corresponding $n^2 \times n^2$ matrix is

$$Z_2 = \begin{pmatrix} \dots & & & & \\ \dots & X & -4I & X & \dots \\ \dots & & & & \dots \end{pmatrix},$$

where

$$X = \begin{pmatrix} \dots & & & & \\ \dots & 1 & 0 & 1 & \dots \\ \dots & & & & \dots \end{pmatrix}$$

is an $n \times n$ matrix and I the $n \times n$ unit matrix. The characteristic values of X are, from (2.1),

$$-2 \cos k\theta, \quad k=1,2,\dots,n.$$

It follows that those of Z_2 are those of the n triple diagonal matrices

$$Z_2^{(k)} = \begin{pmatrix} \dots & & & & \\ \dots & -2 \cos k\theta & -4 & -2 \cos k\theta & \dots \\ \dots & & & & \dots \end{pmatrix}, \quad k=1,2,\dots,n,$$

which are, from (2.1),

$$\nu_{k,l} = -4[1 + \cos k\theta \cos l\theta], \quad k=1,2,\dots,n, \quad l=1,2,\dots,n.$$

We have

$$\lambda(Z_2) = 4[1 + \cos^2\theta]$$

$$\mu(Z_2) = 4 \sin^2\theta$$

so that

$$P(Z_2) \doteq 2\pi^{-2}n^2.$$

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